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bq25703A SLUSCU1 - MAY 2017

# bg25703A I2C Multi-Chemistry Battery Buck-Boost Charge Controller With System Power Monitor and Processor Hot Monitor

#### Features 1

- Charge 1- to 4-Cell Battery From Wide Range of Input Sources
  - 3.5-V to 24-V Input Operating Voltage
  - Supports USB2.0, USB 3.0, USB 3.1 (Type C), and USB\_PD Input Current Settings
  - Seamless Transition Between Buck and Boost Operation
  - Input Current and Voltage Regulation (IDPM) and VDPM) Against Source Overload
- Power/Current Monitor for CPU Throttling
  - Comprehensive PROCHOT Profile, IMVP8 Compliant
  - Input and Battery Current Monitor
  - System Power Monitor, IMVP8 Compliant
- Narrow-VDC (NVDC) Power Path Management
  - Instant-On With No Battery or Deeply **Discharged Battery**
  - Battery Supplements System When Adapter is Fully-Loaded
  - Ideal Diode Operation in Supplement Mode
- Power Up USB Port From Battery (USB OTG)
  - Output 4.48-V to 20.8-V Compatible With USB PD
  - Output Current Limit up to 6.35 A
- 800-kHz or 1.2-MHz Programmable Switching Frequency for 1-µH to 2.2-µH Low Profile Inductor
- Host Control Interface for Flexible System Configuration
  - I2C (bq25703A) Port for Optimal System Performance and Status Reporting
  - Hardware Pin to Set Input Current Limit \_ Without EC Control
- High Accuracy Regulation and Monitor
  - ±0.5% Charge Voltage Regulation
  - ±2% Input/Charge Current Regulation
  - ±2% Input/Charge Current Monitor
  - ±5% Power Monitor
- Safety
  - Thermal Shutdown
  - Input, System, Battery Overvoltage Protection
  - MOSFET Inductor Overcurrent Protection
- Low Battery Quiescent Current

- Input Current Optimizer (ICO) to Extract Max Input • Power
- Charge Any Battery Chemistry: Li+, LiFePO4, NiCd, NiMH, Lead Acid
- Package: 32-Pin 4 × 4 WQFN

#### 2 Applications

- Drones, Bluetooth Speakers, IP Cameras, • Detachable, and Tablet PCs and Power Bank
- Industrial and Medical Equipment
- Portable Equipment With Rechargeable Batteries

## 3 Description

The bg25703A is a synchronous NVDC battery buckboost charge controller, offering low component count, high efficiency solution for space-constraint, multi-chemistry battery charging applications.

The NVDC-1 configuration allows the system to be regulated at battery voltage, but not drop below system minimum voltage. The system keeps operating even when the battery is completely discharged or removed. When load power exceeds input source rating, the battery goes into supplement mode and prevents the input source from being overloaded.

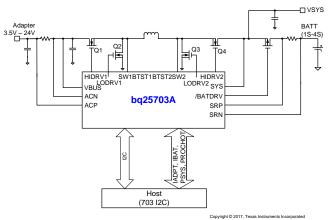
The bg25703A charges battery from a wide range of input sources including USB adapter, high voltage USB PD sources and traditional adapters.

Device	Information	(1)
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PART NUMBER	PACKAGE	BODY SIZE (NOM)
bq25703A	WQFN (32)	4.00 mm × 4.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

## **Application Diagram**





An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.

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## 4 Revision History

DATE	REVISION	NOTES
May 2017	*	Initial release.



## **5** Description (Continued)

During power up, the charger sets converter to buck, boost or buck-boost configuration based on input source and battery conditions. The charger automatically transits among buck, boost and buck-boost configuration without host control.

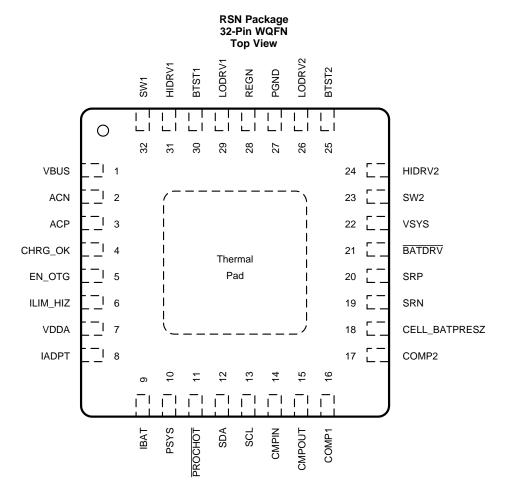
In the absence of an input source, the bq25703A supports On-the-Go (OTG) function from 1- to 4-cell battery to generate 4.48 V to 20.8 V on VBUS. During OTG mode, the charger regulates output voltage and output current.

The bq25703A monitors adapter current, battery current and system power. The flexibly programmed PROCHOT output goes directly to CPU for throttle back when needed.

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## 6 Pin Configuration and Functions



#### **Pin Functions**

PIN		1/0	DESCRIPTION		
NAME	NUMBER	1/0	DESCRIPTION		
ACN	2	PWR	Input current sense resistor negative input. The leakage on ACP and ACN are matched. The series resistors on the ACP and ACN pins are placed between sense resistor and filter cap. Refer to <i>Application and Implementation</i> for ACP/ACN filter design.		
ACP	3	PWR	Input current sense resistor positive input. The leakage on ACP and ACN are matched. The series resistors on the ACP and ACN pins are placed between sense resistor and filter cap. Refer to <i>Application and Implementation</i> for ACP/ACN filter design.		
BATDRV	21	Ο	P-channel battery FET (BATFET) gate driver output. It is shorted to VSYS to turn off the BATFET. It goes 10 V below VSYS to fully turn on BATFET. BATFET is in linear mode to regulate VSYS at minimum system voltage when battery is depleted. BATFET is fully on during fast charge and supplement mode.		
BTST1	30	PWR	Buck mode high side power MOSFET driver power supply. Connect a 0.047-µF capacitor between SW1 and BTST1. The bootstrap diode between REGN and BTST1 is integrated.		
BTST2	25	PWR	Boost mode high side power MOSFET driver power supply. Connect a $0.047$ - $\mu$ F capacitor between SW2 and BTST2. The bootstrap diode between REGN and BTST2 is integrated.		
CELL_BATPRESZ	18	I	Battery cell selection pin for 1–4 cell battery setting. CELL_BATPRESZ pin is biased fro VDDA. CELL_BATPRESZ pin also sets SYSOVP threshold to 5 V for 1-cell, 12 V for 2- and 18.5 V for 3-cell. CELL_BATPRESZ pin is pulled below V <sub>CELL_BATPRESZ_FALL</sub> to ind battery removal. The device exits LEARN mode, and disables charge. REG0x05/04() gi back to default.		



## Pin Functions (continued)

PIN					
NAME	NUMBER	I/O	DESCRIPTION		
CHRG_OK	4	0	Open drain active high indicator to inform the system good power source is connected to the charger input. Connect to the pullup rail via 10-k $\Omega$ resistor. When VBUS rises above 3.5V or falls below 24.5V, CHRG_OK is HIGH after 50ms deglitch time. When VBUS is falls below 3.2 V or rises above 26 V, CHRG_OK is LOW.		
CMPIN	14	I	Input of independent comparator. The independent comparator compares the voltage sensed on CMPIN pin to internal reference, and its output is on CMPOUT pin. Internal reference, output polarity and deglitch time is selectable by I2C. With polarity HIGH (REG0x30[6] = 1), place a resistor between CMPIN and CMPOUT to program hysteresis. With polarity LOW (REG0x30[6] = 0), the internal hysteresis is 100 mV. If the independent comparator is not in use, tie CMPIN to ground.		
CMPOUT	15	Ι	Open-drain output of independent comparator. Place pullup resistor from CMPOUT to pullup supply rail. Internal reference, output polarity and deglitch time are selectable by I2C.		
COMP2	17	Ι	Buck boost converter compensation pin 2. Refer to bq25700 EVM schematic for COMP2 pin RC network.		
COMP1	16	Ι	Buck boost converter compensation pin 1. Refer to bq25700 EVM schematic for COMP1 pin RC network.		
EN_OTG	5	Ι	Active HIGH to enable OTG mode. When EN_OTG pin is HIGH and REG0x35[4] is HIGH, OTG can be enabled, refer to USB On-The-Go (OTG) for details of how to enable OTG function		
HIDRV1	31	0	Buck mode high side power MOSFET (Q1) driver. Connect to high side n-channel MOSFET gate.		
HIDRV2	24	0	Boost mode high side power MOSFET(Q4) driver. Connect to high side n-channel MOSFET gate.		
IADPT	8	ο	Buffered adapter current output. $V_{(IADP)} = 20 \text{ or } 40 \times (V_{(ACP)} - V_{(ACN)})$ . With ratio selectable in REG0x00[4]. Place a resistor from the IADPT pin to ground corresponding to inductor in use For 2.2 µH, the resistor is 137 k $\Omega$ . Place 100-pF or less ceramic decoupling capacitor from IADPT pin to ground. IADPT output voltage is clamped below 3.3 V.		
IBAT	9	0	Buffered battery current selected by I2C. $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRP)} - V_{(SRN)})$ for charge current, or $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRN)} - V_{(SRP)})$ for discharge current, with ratio selectable in REG0x00[3]. Place 100-pF or less ceramic decoupling capacitor from IBAT pin to ground. This pin can be floating if not in use. Its output voltage is clamped below 3.3 V.		
ILIM_HIZ	6	I	Input current limit input. Program ILIM_HIZ voltage by connecting a resistor divider from supply rail to ILIM_HIZ pin to ground. The pin voltage is calculated as: $V_{(ILIM_HIZ)} = 1 V + 40 \times IDPM \times RAC$ , in which IDPM is the target input current. The input current limit used by the charger is the lower setting of ILIM_HIZ pin and REG0x0F() and REG0x0E(). When the pin voltage is below 0.4 V, the device enters Hi-Z mode with low quiescent current. When the pin voltage is above 0.8 V, the device is out of Hi-Z mode.		
LODRV1	29	0	Buck mode low side power MOSFET (Q2) driver. Connect to low side n-channel MOSFET gate.		
LODRV2	26	0	Boost mode low side power MOSFET (Q3) driver. Connect to low side n-channel MOSFET gate.		
PGND	27	GND	Device power ground.		
PROCHOT	11	0	Active low open drain output of processor hot indicator. It monitors ad <u>apter input</u> current, battery discharge current, and system voltage. After any event in the PROCHOT profile is triggered, a minimum 10-ms pulse is asserted. The pulse width is adjustable in REG0x36[5:2].		
PSYS	10	0	Current mode system power monitor. The output current is proportional to the total power from the adapter and battery. The gain is selectable through I2C. Place resistor from PSYS to ground to generate output voltage. This pin can be floating if not in use. Its output voltage is clamped below 3.3 V. Place a capacitor in parallel with resistor for filtering.		
REGN	28	PWR	6-V linear regulator output supplied from VBUS or VSYS. The LDO is active when VBUS above V <sub>VBUS_CONVEN</sub> . Connect a 2.2- or 3.3-μF ceramic capacitor from REGN to power ground. REGN pin output is for power stage gate drive.		
SCL	13	Ι	I2C clock input. Connect to clock line from the host controller or smart battery. Connect a 10- $k\Omega$ pullup resistor according to I2C specifications.		
SDA	12	I/O	I2C open-drain data I/O. Connect to data line from the host controller or smart battery. Connect a $10$ -k $\Omega$ pullup resistor according to I2C specifications.		

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## Pin Functions (continued)

PIN		I/O	DESCRIPTION		
NAME	NUMBER	1/0			
SRN	19	PWR	Charge current sense resistor negative input. SRN pin is for battery voltage sensing as well. Connect SRN pin with optional $0.1$ - $\mu$ F ceramic capacitor to GND for common-mode filtering. Connect a $0.1$ - $\mu$ F ceramic capacitor from SRP to SRN to provide differential mode filtering. The leakage current on SRP and SRN are matched. For reverse battery plug-in protection, $10$ - $\Omega$ series resistors are placed on SRP and SRN.		
SRP	20	PWR	harge current sense resistor positive input. Connect $0.1$ - $\mu$ F ceramic capacitor from SRP to RN to provide differential mode filtering. The leakage current on SRP and SRN are atched. For reverse battery plug-in protection, $10$ - $\Omega$ series resistors are placed on SRP and RN. Connect SRP pin with optional 0.1- $\mu$ F ceramic capacitor to GND for common-mode tering.		
SW1	32	PWR	Buck mode high side power MOSFET driver source. Connect to the source of the high side n-channel MOSFET.		
SW2	23	PWR	Boost mode high side power MOSFET driver source. Connect to the source of the high side n-channel MOSFET.		
VBUS	1	PWR	Charger input voltage. An input low pass filter of $1\Omega$ and 0.47 $\mu$ F (minimum) is recommended.		
VDDA	7	PWR	nternal reference bias pin. Connect a 10- $\Omega$ resistor from REGN to VDDA and a 1- $\mu$ F eramic capacitor from VDDA to power ground.		
VSYS	22	PWR	Charger system voltage sensing. The system voltage regulation limit is programmed in REG0x05/04() and REG0X0D/0C().		
Thermal pad	_	_	Exposed pad beneath the IC. Analog ground and power ground star-connected near the IC's ground. Always solder thermal pad to the board, and have vias on the thermal pad plane connecting to power ground planes. It also serves as a thermal pad to dissipate the heat.		



## 7 Specifications

## 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)(2)</sup>

		MIN	MAX	UNIT
	SRN, SRP, ACN, ACP, VBUS, VSYS, BATDRV	-0.3	30	
	SW1, SW2	-2.0	30	
	BTST1, BTST2, HIDRV1, HIDRV2	-0.3	36	
	LODRV1, LODRV2 (2% duty cycle)	-4.0	7	
	HIDRV1, HIDRV2 (2% duty cycle)	-4.0	36	
Voltage	SW1, SW2 (2% duty cycle)	-4.0	30	V
	SDA, SCL, REGN, CHRG_OK, CELL_BATPRESZ, ILIM_HIZ, LODRV1, LODRV2, VDDA, COMP1, COMP2, CMPIN, CMPOUT, EN_OTG	-0.3	7	
	PROCHOT	-0.3	5.5	
	IADPT, IBAT, PSYS	-0.3	3.6	
Differential values	BTST1-SW1, BTST2-SW2, HIDRV1-SW1, HIDRV2-SW2	-0.3	7	V
Differential voltage	SRP-SRN, ACP-ACN	-0.5	0.5	V
Junction temperature range, $T_J$	Junction temperature range, T <sub>J</sub>		155	°C
Storage temperature, T <sub>stg</sub>		-40	155	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltages are with respect to GND if not specified. Currents are positive into, negative out of the specified terminal. Consult Packaging Section of the data book for thermal limitations and considerations of packages.

## 7.2 ESD Ratings

				VALUE	UNIT
v	V <sub>(Fob</sub> ) Electrostatic discharde	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V	
V(E		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	v	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

## 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT	
	ACN, ACP, VBUS	0	24		
	SRN, SRP, VSYS, BATDRV	0	19.2		
	SW1, SW2	-2	24		
Voltage	BTST1, BTST2, HIDRV1, HIDRV2	0	30	V	
Vollage	SDA, SCL, REGN, CHRG_OK, CELL_BATPRESZ, ILIM_HIZ, LODRV1, LODRV2, VDDA, COMP1, COMP2, CMPIN, CMPOUT	0	6.5	·	
	PROCHOT	0	5.3		
	IADPT, IBAT, PSYS	0	3.3		
Differential	BTST1-SW1, BTST2-SW2, HIDRV1-SW1, HIDRV2-SW2	0	6.5	N/	
voltage	SRP-SRN, ACP-ACN	-0.35	0.35	v	
Junction temp	Junction temperature, T <sub>J</sub>		125	°C	
Operating free	-air temperature, T <sub>A</sub>	-40	85	°C	

## 7.4 Thermal Information

		bq25703A	
	THERMAL METRIC <sup>(1)</sup>	RSN (WQFN)	UNIT
		32 PINS	
$R_{\thetaJA}$	Junction-to-ambient thermal resistance	37.2	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	26.1	°C/W
$R_{\theta J B}$	Junction-to-board thermal resistance	7.8	°C/W
ΨJT	Junction-to-top characterization parameter	0.3	°C/W
ΨЈВ	Junction-to-board characterization parameter	7.8	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	2.3	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

## 7.5 Electrical Characteristics

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>INPUT_OP</sub>	Input voltage operating range		3.5		26	V
REGULATION ACC	CURACY					
MAX SYSTEM VOI	LTAGE REGULATION					
V <sub>SYSMAX_RNG</sub>	System voltage regulation, measured on V <sub>SYS</sub>		1.024		19.2	V
		REG0x05/04() = 0x41A0H		V <sub>SRN</sub> + 160 mV		V
		(16.800 V)	-2%		2%	
		REG0x05/04() = 0x3130H		V <sub>SRN</sub> + 160 mV		V
	System voltage regulation	(12.592 V)	-2%		2%	
VSYSMAX_ACC	accuracy (charge disable)	REG0x05/04() = 0x20D0H		V <sub>SRN</sub> + 160 mV		V
		(8.400 V)	-3%		3%	
		REG0x05/04() = 0x1060H		V <sub>SRN</sub> + 160 mV	26         19.2         V         2%         V         3%         V         3%         V         3%         19.2         8         2%         4         3%         4         19.2         8         2%         4         3%         4         19.2         8         0.5%         2         0.5%         4         0.6%	V
	UT_OP         Input voltage operating range         3.5           SULATION ACCURACY	3%				
MINIMUM SYSTEM	I VOLTAGE REGULATION				I	
V <sub>SYSMIN_RNG</sub>			1.024		19.2	V
		REG0x0D/0C() = 0x3000H		12.288		V
			-2%		2%	
	•••			9.216	mV 2% mV 2% mV 2% mV 3% mV 3% mV 3% 288 2% 2 288 2% 2 216 2% 1 216 2% 1 384 4% 584 4% 584 4% 584 4% 584 4% 1 584 4% 584 4% 1 584 4% 584 4% 1	V
		REG0x0D/0C() = 0x2400H	-2%		2%	
V <sub>SYSMIN_REG_ACC</sub>	enable, VBAT below			6.144		V
	REG0x0D/0C() setting)	REG0x0D/0C() = 0x1800H	-3%		3%	
				3.584		V
REGULATION ACCU MAX SYSTEM VOLT V <sub>SYSMAX_RNG</sub> V <sub>SYSMAX_ACC</sub> MINIMUM SYSTEM V V <sub>SYSMIN_RNG</sub>		REG0x0D/0C() = 0x0E00H	-3%		4%	
CHARGE VOLTAG	E REGULATION					
V <sub>BAT RNG</sub>	Battery voltage regulation		1.024		19.2	V
2,11,2,11,0				16.8		V
		REG0x05/04() = 0x41A0H	-0.5%		0.5%	
				12.592		V
		REG0x05/04() = 0x3130H	-0.5%		0.5%	
V <sub>BAT_REG_ACC</sub>			/ •	8.4		V
		REG0x05/04() = 0x20D0H	-0.6%		0.6%	
			0.075	4.192	26 19.2 2% 2% 3% 3% 19.2 2% 2% 3% 4% 19.2 0.5% 0.5% 0.5%	V
		REG0x05/04() = 0x1060H	1 10/		4 00/	•



## **Electrical Characteristics (continued)**

P	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
CHARGE CURRENT	REGULATION IN FAST CHARG	<b>BE</b>				
Vireg_chg_rng	Charge current regulation differential voltage range	VIREG_CHG = VSRP – VSRN	0		81.28	mV
		REG0x03/02() = 0x1000H		4096	MAX         81.28         2%         3%         3%         3%         3%         3%         3%         3%         3%         3%         3%         3%         3%         3%         2%         3%         2%         3%         2%         2%         30%         10         25%         30%         10         4000         3000         1500         30%         10         44000         3000         1500         300         10         44200         3200         1700         700         1         19.52	mA
		REG0003/02() = 0.000011	0 $81.28$ $4096$ 2% $-3\%$ 2% $-4\%$ 3% $-4\%$ 3% $-1\%$ 1024 $-5\%$ 6% $-12\%$ 12% $-12\%$ 12% $-12\%$ 384 $2$ $384$ $-15\%$ $15\%$ $-25\%$ $25\%$ $-25\%$ $25\%$ $-20\%$ $20\%$ $-35\%$ $35\%$ $-25\%$ $25\%$ $-20\%$ $20\%$ $-35\%$ $35\%$ $-35\%$ $35\%$ $-30\%$ $30\%$ $-30\%$ $30\%$ $-12$ $10$ $-12$ $10$			
	Charge current regulation	REG0x03/02() = 0x0800H		2048		mA
	accuracy 10-m $\Omega$ current sensing resistor, VBAT above		-4%		3%	
CHRG_REG_ACC	0x0D/0C() setting (0°C to	REG0x03/02() = 0x0400H		1024		mA
	85°C)		-5%		6%	
		REG0x03/02() = 0x0200H		512	81.28         2%         3%         6%         12%         12%         25%         20%         35%         20%         35%         20%         35%         20%         35%         0         15%         20%         35%         0         10         4         4000         300%         10         4         4000         300%         10         700	mA
			-12%		12%	
CHARGE CURRENT	REGULATION IN LDO MODE					
		CELL 2s-4s		384		mA
CLAMP	Pre-charge current clamp	CELL 1 s, V <sub>SRN</sub> < 3 V		81.28         4096         2048         2048         3%         1024         6%         512         12%         384         384         384         2         384         2         384         2         384         2         384         2         384         15%         256         20%         35%         192         25%         30%         192         25%         30%         192         25%         30%         192         25%         30%         10         128         30%         10         10         10         10         10         10         10         10         10         10         10         10         10	mA	
	-	CELL 1 s, 3 V < V <sub>SRN</sub> < VSYSMIN		2		А
		REG0x03/02() = 0x0180H		384		mA
	Pre-charge current regulation accuracy with 10-Ω SRP/SRN series resistor, VBAT below REG0x0D/0C() setting (0°C to 85°C)	2S-4S	-15%		15%	
		1S	-25%		25%	
		REG0x03/02() = 0x0100H		256		mA
PRECHRG_REG_ACC		2S-4S	-20%		20%	
		1S	-35%		35%	
		REG0x03/02() = 0x00C0H		192		mA
		2S-4S	-25%		25%	
		1S	-50%		50%	
		REG0x03/02() = 0x0080H		128	4096       2%         2048       3%         1024       6%         512       12%         384       2         384       2         384       2         384       2         384       2         384       25%         256       20%         192       25%         192       25%         192       30%         192       30%         192       30%         192       50%         192       50%         10       10         150       100         1500       100         128       30%         10       10         10       10         10       10         10       10         10       10         10       10         10       10         10       10         10       10         10       10         10       10         10       10         10       10         100       100	mA
		2S-4S	-30%		30%	
LEAK_SRP_SRN	SRP, SRN leakage current mismatch (0°C to 85°C)		-12		10	μA
NPUT CURRENT R	EGULATION					
VIREG_DPM_RNG	Input current regulation differential voltage range	$V_{IREG_{DPM}} = V_{ACP} - V_{ACN}$	0.5		64	mV
		REG0x0F/0E() = 0x4FFFH	3820		4000	mA
	Input current regulation accuracy (–40°C to 105°C)	REG0x0F/0E() = 0x3BFFH	2830		3000	mA
DPM_REG_ACC	with 10- $\Omega$ ACP/ACN series	REG0x0F/0E() = 0x1DFFH	1350		1500	mA
	resistor	REG0x0F/0E() = 0x09FFH	340		81.28         2%         3%         6%         12%         12%         25%         25%         35%         20%         35%         10         25%         50%         30%         10         44000         3000         1500         10         700         10         10         10         10         10         10         10         10         10         10         11         10         11         11         11         11         11         11         11         11	mA
LEAK_ACP_ACN	ACP, ACN leakage current mismatch		-16		10	μA
VIREG_DPM_RNG_ILIM	Voltage Range for input current regulation		1		4	V
	Input Current Regulation	$V_{ILIM_{HIZ}} = 2.6 V$	3800	4000	4200	mA
	Accuracy on ILIM_HIZ pin	$V_{ILIM HIZ} = 2.2 V$	2800	3000	3200	mA
DPM_REG_ACC_ILIM	$V_{ILIM_HIZ} = 1 V + 40 \times IDPM \times R_{AC}$ , with 10- $\Omega$ ACP/ACN	$V_{ILIM_{HIZ}} = 1.6 V$	1300	1500	1700	mA
	series resistor	$V_{ILIM HIZ} = 1.2 V$	300	500	700	mA
LEAK_ILIM	I <sub>LIM_HIZ</sub> pin leakage	_	-1		1	μA
NPUT VOLTAGE RI		I				

## **Electrical Characteristics (continued)**

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		REG0x07/06()=0x3C80H		18688		mV
			-2%		2%	
	Input voltage regulation	REG0x07/06()=0x1E00H		10880		mV
V <sub>DPM_REG_ACC</sub>	accuracy		-2.5%		2.5%	
		REG0x07/06()=0x0500H		4480		mV
			-3%		5%	
OTG CURRENT RE	GULATION				I	
VIOTG_REG_RNG	Input current regulation differential voltage range	$V_{IREG_{DPM}} = V_{ACP} - V_{ACN}$	0		81.28	mV
	Input current regulation	REG0x09/08() = 0x3C00H	2800	3000	3200	mA
I <sub>OTG_ACC</sub>	accuracy with 50-mA LSB,	REG0x09/08() = 0x1E00H	1300	1500	1700	mA
010_100	CURRENT REGULATION         REG_RNG       Input current regulation differential voltage range         Input current regulation accuracy with 50-mA LSB, with 10-Ω ACP/ACN series resistor         OLTAGE REGULATION         DPM_RNG       Input voltage regulation range         REG_ACC       OTG voltage regulation accuracy         REG_ACC       REGN regulator voltage (0 mA-60 mA)         DUT       REGN voltage in drop out mode         IM_Charging       REGN current limit when converter is enabled         REGN output capacitor required for stability       REGN output capacitor required for stability         REGN output capacitor required for stability       REGN output capacitor required for stability         CENT CURRENT       System powered by battery.         ITFET_ON       System powered by battery.         BATFET on. I <sub>SRN</sub> + I <sub>SRP</sub> + I <sub>SW2</sub> + I <sub>BTST2</sub> + I <sub>SW1</sub> + I <sub>BTST1</sub> + ACP + I <sub>ACN</sub> + I <sub>VBUS</sub> + I <sub>VSYS</sub>	REG0x09/08() = 0x0A00H	300	500	700	mA
OTG VOLTAGE RE	GULATION	, v				
VIREG_DPM_RNG	Input voltage regulation range	Voltage on VBUS	4.48		20.8	V
	1 0 0 0 0 0 00			20.032		V
		REG0x0B/0A()=0x3CC0H	-2%		2%	
	OTG voltage regulation	Accuracy REG0x0B/0A()=0x1D80H -2% 2% REG0x0B/0A()=0x0240H 5.056	_,,,	V		
V <sub>OTG_REG_ACC</sub> accuracy REG0x0B/0A()=0x1D80H -2% REG0x0B/0A()=0x0240H 5.056	2%	-				
	-			5,056		V
		REG0x0B/0A()=0x0240H	-3%	0.000	3%	•
REFERENCE AND	BUFFFR		070		070	
V <sub>REGN_REG</sub>	REGN regulator voltage (0	V <sub>VBUS</sub> = 10 V	5.7	6	6.3	V
V <sub>DROPOUT</sub>		$V_{VBUS} = 5 V, I_{LOAD} = 20 mA$	3.8	4.3	4.6	V
REGN_LIM_Charging		$V_{VBUS}$ = 10 V, force $V_{REGN}$ = 4 V	50	65		mA
C <sub>REGN</sub>		$I_{LOAD} = 100 \ \mu A \text{ to } 50 \ \text{mA}$	2.2			μF
C <sub>VDDA</sub>		$I_{LOAD} = 100 \ \mu A \text{ to } 50 \ \text{mA}$	1			μF
QUIESCENT CURR	ENT					
		VBAT = 18 V, REG0x01[7] = 1, in low power mode		22	45	μA
		VBAT = 18 V, REG0x01[7] = 0, REG0x31[6:5] = 01, REGN off		105	175	μA
I <sub>BAT_BATFET_ON</sub>	BATFET on. I <sub>SRN</sub> + I <sub>SRP</sub> + I <sub>SW2</sub> + I <sub>BTST2</sub> + I <sub>SW1</sub> + I <sub>BTST1</sub> +	VBAT=18 V, REG0x01[7] = 0, REG0x31[6:5] = 10, REGN off		60	90	μA
	ACP + IACN + IVBUS + IVSYS	VBAT = 18 V, REG0x01[7] = 0, REG0x31[4] = 0, REGN on, EN_PSYS		860	1150	μA
		VBAT = 18 V, REG0x01[7] = 0, REG0x = 1, REGN on		960	1250	ľ
AC_SW_LIGHT_buck	Input current during PFM in buck mode, no load, $I_{VBUS}$ + $I_{ACP}$ + $I_{ACN}$ + $I_{VSYS}$ + $I_{SRP}$ + $I_{SRN}$ + $I_{SW1}$ + $I_{BTST}$ + $I_{SW2}$ + $I_{BTST2}$	VIN = 20 V, VBAT = 12.6 V, 3 s, REG0x01[2] = 0; MOSFET Qg = 4 nC		2.2		mA



## **Electrical Characteristics (continued)**

over  $T_J = -40$  to  $125^{\circ}C$  (unless otherwise noted)

PA	RAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
I <sub>AC_SW_LIGHT_boost</sub>	Input current during PFM in boost mode, no load, $I_{VBUS}$ + $I_{ACP}$ + $I_{ACN}$ + $I_{VSYS}$ + $I_{SRP}$ + $I_{SRN}$ + $I_{SW1}$ + $I_{BTST2}$ + $I_{SW2}$ + $I_{BTST2}$	VIN = 5 V, VBAT = 8.4 V, 2 s, REG0x01[2] = 0; MOSFET Qg = 4 nC		2.7		mA
I <sub>AC_SW_LIGHT_buckboost</sub>	Input current during PFM in buck boost mode, no load, I <sub>VBUS</sub> + I <sub>ACP</sub> + I <sub>ACN</sub> + I <sub>VSYS</sub> + I <sub>SRP</sub> + I <sub>SRN</sub> + I <sub>SW1</sub> + I <sub>BTST1</sub> + I <sub>SW2</sub> + I <sub>BTST2</sub>	VIN = 12 V, VBAT = 12 V, REG0x01[2] = 0; MOSFET Qg = 4 nC		2.4		mA
		VBAT = 8.4 V, VBUS = 5 V, 800-kHz switching frequency, MOSFET Qg = 4 nC		3		
I <sub>OTG_STANDBY</sub>	Quiescent current during PFM in OTG mode $I_{VBUS} + I_{ACP} + I_{ACN} + I_{VSYS} + I_{SRP} + I_{SRN} + I_{SW1} + I_{BTST2} + I_{SW2} + I_{BTST2}$	VBAT = 8.4 V, VBUS = 12 V, 800-kHz switching frequency, MOSFET Qg = 4 nC		4.2		mA
		VBAT = 8.4 V, VBUS = 20 V, 800-kHz switching frequency, MOSFET Qg = 4 nC		6.2		
V <sub>ACP/N_OP</sub>	Input common mode range	Voltage on ACP/ACN	3.8		26	V
VIADPT_CLAMP	IADPT output clamp voltage		3.1	3.2	3.3	V
IIADPT	IADPT output current				1	mA
AIADPT	Input current sensing gain	$V_{(IADPT)} / V_{(ACP-ACN)},$ REG0x00[4] = 0		20		V/V
	input outfolk ochoing guin	$V_{(IADPT)} / V_{(ACP-ACN)},$ REG0x00[4] = 1		40		V/V
		$V_{(ACP-ACN)} = 40.96 \text{ mV}$	-2%		2%	
VIADPT_ACC	Input current monitor	$V_{(ACP-ACN)} = 20.48 \text{ mV}$	-3%		3%	
	accuracy	V <sub>(ACP-ACN)</sub> =10.24 mV	-6%		6%	
		$V_{(ACP-ACN)} = 5.12 \text{ mV}$	-10%		10%	
CIADPT_MAX	Maximum output load capacitance				100	pF
V <sub>SRP/N_OP</sub>	Battery common mode range	Voltage on SRP/SRN	2.5		18	V
VIBAT_CLAMP	IBAT output clamp voltage		3.05	3.2	3.3	V
I <sub>IBAT</sub>	IBAT output current				1	mA
A <sub>IBAT</sub>	Charge and discharge current	$V_{(IBAT)} / V_{(SRN-SRP)},$ REG0x00[3] = 0,		8		V/V
	sensing gain on IBAT pin	$V_{(IBAT)} / V_{(SRN-SRP)},$ REG0x00[3] = 1,		16		V/V
		V <sub>(SRN-SRP)</sub> = 40.96 mV	-2%		2%	
IIBAT CHG ACC	Charge and discharge current	V <sub>(SRN-SRP)</sub> = 20.48 mV	-3%		4%	
.21_0110_1000	monitor accuracy on IBAT pin	V <sub>(SRN-SRP)</sub> =10.24 mV	-6%		6%	
		$V_{(SRN-SRP)} = 5.12 \text{ mV}$	-12%		12%	
C <sub>IBAT_MAX</sub>	Maximum output load capacitance				100	pF
SYSTEM POWER SE	NSE AMPLIFIER	· · · · · · · · · · · · · · · · · · ·			I	
V <sub>PSYS</sub>	PSYS output voltage range		0		3.3	V
I <sub>PSYS</sub>	PSYS output current		0		160	μA
A <sub>PSYS</sub>	PSYS system gain	$V_{(PSYS)} / (P_{(IN)} + P_{(BAT)}),$ REG0x31[1] = 1		1		µA/W

# **Electrical Characteristics (continued)**

over $T_1 = -40$ to $125^{\circ}C_1$	(unless otherwise noted)

F	PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
		Adapter only with system power = 19.5 V / 45 W, $T_A = 0$ to 85°C	-5%		5%	
N/	PSYS gain accuracy	Adapter only with system power = 19.5 V / 45 W, $T_A = -40$ to 125°C	-7%		6%	
V <sub>PSYS_ACC</sub>	(REG0x31[1] = 1)	Battery only with system power = 11 V / 44 W, $T_A = 0$ to 85°C	-5%		5%	
		Battery only with system power = 11 V / 44 W, $T_A =$ -40 to 125°C	-6%		6%	
V <sub>PSYS_CLAMP</sub>	PSYS clamp voltage		3		3.3	V
COMPARATOR						
VBUS UNDER VOL	TAGE LOCKOUT COMPARATOR	8				
V <sub>VBUS_UVLOZ</sub>	VBUS undervoltage rising threshold	VBUS rising	2.34	2.55	2.77	V
V <sub>VBUS_UVLO</sub>	VBUS undervoltage falling threshold	VBUS falling	2.2	2.4	2.6	V
V <sub>VBUS_UVLO_HYST</sub>	VBUS undervoltage hysteresis			150		mV
V <sub>VBUS_CONVEN</sub>	VBUS converter enable rising threshold	VBUS rising	3.2	3.5	3.9	V
V <sub>VBUS_CONVENZ</sub>	VBUS converter enable falling threshold	VBUS falling	2.9	3.2	3.5	V
V <sub>VBUS_CONVEN_HYST</sub>	VBUS converter enable hysteresis			400		mV
BATTERY UNDER \	OLTAGE LOCKOUT COMPARA	TOR				
V <sub>VBAT_UVLOZ</sub>	VBAT undervoltage rising threshold	VSRN rising	2.35	2.55	2.75	V
V <sub>VBAT_UVLO</sub>	VBAT undervoltage falling threshold	VSRN falling	2.2	2.4	2.6	V
V <sub>VBAT_UVLO_HYST</sub>	VBAT undervoltage hysteresis			150		mV
V <sub>VBAT_OTGEN</sub>	VBAT OTG enable rising threshold	VSRN rising	3.3	3.55	3.75	V
V <sub>VBAT_OTGENZ</sub>	VBAT OTG enable falling threshold	VSRN falling	3	3.2	3.4	V
V <sub>VBAT_OTGEN_HYST</sub>	VBAT OTG enable hysteresis			350		mV
VBUS UNDER VOL	TAGE COMPARATOR (OTG MOI	,				
V <sub>VBUS_OTG_UV</sub>	VBUS undervoltage falling threshold	As percentage of REG0x07/06()		85.0%		
tvbus_otg_uv	VBUS undervoltage deglitch time			7		ms
VBUS OVER VOLTA	AGE COMPARATOR (OTG MODI	E)				
V <sub>VBUS_OTG_OV</sub>	VBUS overvoltage rising threshold	As percentage of REG0x07/06()		105%		
t <sub>VBUS_OTG_OV</sub>	VBUS Over-Voltage Deglitch Time			10		ms
V <sub>BAT_SYSMIN_RISE</sub>	LDO mode to fast charge mode threshold, VSRN rising	as percentage of 0x0D/0C()	98%	100%	102%	
VBAT_SYSMIN_FALL	LDO mode to fast charge mode threshold, VSRN falling	as percentage of 0x0D/0C()		97.5%		



## **Electrical Characteristics (continued)**

F	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>BAT_SYSMIN_HYST</sub>	Fast charge mode to LDO mode threshold hysteresis	as percentage of 0x0D/0C()		2.5%		
BATTERY LOWV C	OMPARATOR (Pre-charge to Fa	st Charge Thresold for 1S)			1	
V <sub>BATLV_FALL</sub>	BATLOWV falling threshold	1 s		2.80		V
V <sub>BATLV_RISE</sub>	BATLOWV rising threshold			3.00		V
V <sub>BATLV_RHYST</sub>	BATLOWV hysteresis			200		mV
NPUT OVER-VOLT	AGE COMPARATOR (ACOVP)					
V <sub>ACOV_RISE</sub>	VBUS overvoltage rising threshold	VBUS rising	25	26	27	V
V <sub>ACOV_FALL</sub>	VBUS overvoltage falling threshold	VBUS falling	24	24.5	25	V
V <sub>ACOV_HYST</sub>	VBUS overvoltage hysteresis			1.5		V
t <sub>ACOV_RISE_DEG</sub>	VBUS overvoltage rising deglitch	VBUS rising to stop converter		100		μs
t <sub>ACOV_FALL_DEG</sub>	VBUS overvoltage falling deglitch	VBUS falling to start converter		1		ms
INPUT OVER CURR	RENT COMPARATOR (ACOC)					
V <sub>ACOC</sub>	ACP to ACN rising threshold, w.r.t. ILIM2 in REG0x37[7:3]	Voltage across input sense resistor rising, Reg0x32[2] = 1	195%	210%	225%	
V <sub>ACOC_FLOOR</sub>	Measure between ACP and ACN	Set IDPM to minimum	44	50	56	mV
V <sub>ACOC_CEILING</sub>	Measure between ACP and ACN	Set IDPM to maximum	172	180	188	mV
t <sub>ACOC_DEG_RISE</sub>	Rising deglitch time	Deglitch time to trigger ACOC		250		μs
t <sub>ACOC_RELAX</sub>	Relax time	Relax time before converter starts again		250		ms
SYSTEM OVER-VO	LTAGE COMPARATOR (SYSOV	P)				
		1 s	4.85	5	5.1	
.,	System overvoltage rising	2 s	11.7	12	12.2	
V <sub>SYSOVP_RISE</sub>	threshold to turn off converter	3 s	19	19.5	20	V
		4 s	19	19.5	20	
		1 s		4.8		
	System overvoltage falling	2 s		11.5		.,
V <sub>SYSOVP_FALL</sub>	threshold	3 s		19		V
		4 s		19		
ISYSOVP	Discharge current when SYSOVP stop switching was triggered	on SYS		20		mA
BAT OVER-VOLTA	GE COMPARATOR (BATOVP)	• •				
	Overvoltage rising threshold	1 s, 4.2 V	102.5%	104%	106%	
VBATOVP_RISE	as percentage of V <sub>BAT_REG</sub> in REG0x05/04()	2 s - 4 s	102.5%	104%	105%	
	Overvoltage falling threshold	1 s	100%	102%	104%	
VBATOVP_FALL	as percentage of VBAT_REG in REG0x05/04()	2 s - 4 s	100%	102%	103%	
V <sub>BATOVP_HYST</sub>	Overvoltage hysteresis as percentage of V <sub>BAT_REG</sub> in	1 s 2 s - 4 s		2% 2%		
	REG0x05/04() Discharge current during	on SRP and SRN		278		mA



## **Electrical Characteristics (continued)**

P	ARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>BATOVP_RISE</sub>	Overvoltage rising deglitch to turn off BATDRV to disable charge			20		ms
CONVERTER OVER	-CURRENT COMPARATOR (Q2	)				
	Convertor Quer Current Limit	Reg0x32[5]=1		150		mV
VOCP_limit_Q2	Converter Over-Current Limit	Reg0x32[5]=0		210		IIIV
VOCP_limit_SYSSH	System Short or SRN<2.5 V	Reg0x32[5]=1		45		mV
ORT_Q2	System Short of Skin<2.5 V	Reg0x32[5]=0		60		IIIV
CONVERTER OVER	-CURRENT COMPARATOR (AC	X)				
VOCP_limit_Q3	Converter Over-Current Limit	Reg0x32[4]=1		150		mV
		Reg0x32[4]=0		280		IIIV
VOCP_limit_SYSSH	System Short or SRN<2.5 V	Reg0x32[4]=1		90		mV
ORT_Q3		Reg0x32[4]=0		150		IIIV
THERMAL SHUTDO	WN COMPARATOR					
T <sub>SHUT_RISE</sub>	Thermal shutdown rising temperature	Temperature increasing		155		°C
T <sub>SHUTF_FALL</sub>	Thermal shutdown falling temperature	Temperature reducing		135		°C
T <sub>SHUT_HYS</sub>	Thermal shutdown hysteresis			20		°C
t <sub>SHUT_RDEG</sub>	Thermal shutdown rising deglitch			100		μs
t <sub>SHUT_FHYS</sub>	Thermal shutdown falling deglitch			12		ms
VSYS PROCHOT CC	MPARATOR					
		Reg0x36[7:6] = 00, 1 s		2.85		V
		Reg0x36[7:6] = 00, 2–4 s		5.75		V
		Reg0x36[7:6] = 01, 1 s	2.95	3.1	3.25	V
V <sub>SYS_PROCHOT</sub>	V <sub>SYS</sub> threshold falling	Reg0x36[7:6] = 01, 2–4 s	5.8	5.95	6.1	V
SYS_PROCHOT	threshold	Reg0x36[7:6] = 10, 1 s		3.3		V
		Reg0x36[7:6] = 10, 2–4 s		6.25		V
		Reg0x36[7:6] = 11, 1 s		3.5		V
		Reg0x36[7:6] = 11, 2–4 s		6.5		V
t <sub>SYS_PRO_RISE_DEG</sub>	V <sub>SYS</sub> rising deglitch for throttling			8		μs
ICRIT PROCHOT CO	MPARATOR					
.,	Input current rising threshold	Reg0x37[7:3] = 00000	105%	110%	116%	
V <sub>ICRIT_PRO</sub>	for throttling as 10% above ILIM2 (REG0x37[7:3])	Reg0x37[7:3] = 01001	142%	150%	156%	
INOM PROCHOT CO						
V <sub>INOM_PRO</sub>	INOM rising threshold as 10% above IIN (REG0x0F/0E())		105%	110%	116%	
IDCHG PROCHOT C	OMPARATOR	1				
VIDCHG_PRO	IDCHG threshold for throttling for IDSCHG of 6 A	Reg0x39[7:2] =001100	95%	6272	102%	mA
INDEPENDENT COM	IPARATOR					
	Independent comparator	Reg0x30[7] = 1, CMPIN falling	1.17	1.2	1.23	V
VINDEP_CMP	threshold	Reg0x30[7] = 0, CMPIN falling	2.27	2.3	2.33	V



## **Electrical Characteristics (continued)**

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
VINDEP_CMP_HYS	Independent comparator hysteresis	Reg0x06[6] = 0, CMPIN falling		100		mV
POWER MOSFET	DRIVER					
PWM OSCILLATO	R AND RAMP					
F <sub>SW</sub>	PWM switching frequency	Reg0x01[1] = 0 Reg0x01[1] = 1	1020 680	1200 800	1380 920	kHz kHz
BATFET GATE DR	RIVER (BATDRV)		000	000	520	KI IZ
V <sub>BATDRV_ON</sub>	Gate drive voltage on BATFET		8.5	10	11.5	V
V <sub>BATDRV_DIODE</sub>	Drain-source voltage on BATFET during ideal diode operation			30		mV
R <sub>BATDRV_ON</sub>	Measured <u>by sourci</u> ng 10-µA current to BATDRV		3	4	6	kΩ
R <sub>BATDRV_OFF</sub>	Measured by sinking 10-µA current from BATDRV			1.2	2.1	kΩ
PWM HIGH SIDE D	DRIVER (HIDRV Q1)					
R <sub>DS_HI_ON_Q1</sub>	High side driver (HSD) turnon resistance	$V_{BTST1} - V_{SW1} = 5 V$		6		Ω
R <sub>DS_HI_OFF_Q1</sub>	High side driver turnoff resistance	$V_{BTST1} - V_{SW1} = 5 V$		1.3	2.2	Ω
V <sub>BTST1_REFRESH</sub>	Bootstrap refresh comparator falling threshold voltage	V <sub>BTST1</sub> – V <sub>SW1</sub> when low side refresh pulse is requested	3.2	3.7	4.6	V
PWM HIGH SIDE D	DRIVER (HIDRV Q4)					
R <sub>DS_HI_ON_Q4</sub>	High side driver (HSD) turnon resistance	$V_{BTST2} - V_{SW2} = 5 V$		6		Ω
R <sub>DS_HI_OFF_Q4</sub>	High side driver turnoff resistance	$V_{BTST2} - V_{SW2} = 5 V$		1.5	2.4	Ω
V <sub>BTST2_REFRESH</sub>	Bootstrap refresh comparator falling threshold voltage	V <sub>BTST2</sub> – V <sub>SW2</sub> when low side refresh pulse is requested	3.3	3.7	4.6	V
PWM LOW SIDE D	RIVER (LODRV Q2)	· · · · · · · · ·				
R <sub>DS_LO_ON_Q2</sub>	Low side driver (LSD) turnon resistance	$V_{BTST1} - V_{SW1} = 5.5 V$		6		Ω
R <sub>DS_LO_OFF_Q2</sub>	Low side driver turnoff resistance	$V_{BTST1} - V_{SW1} = 5.5 V$		1.7	2.6	Ω
PWM LOW SIDE D	ORIVER (LODRV Q3)					
R <sub>DS_LO_ON_Q3</sub>	Low side driver (LSD) turnon resistance	$V_{BTST2} - V_{SW2} = 5.5 \text{ V}$		7.6		Ω
R <sub>DS_LO_OFF_Q3</sub>	Low side driver turnoff resistance	$V_{BTST2} - V_{SW2} = 5.5 \text{ V}$		2.9	4.6	Ω
INTERNAL SOFT S	START During Charge Enable					
SSSTEP_DAC	Soft Start Step Size			64		mA
SSSTEP_DAC	Soft Start Step Time			8		μs
INTEGRATED BTS	· /					
V <sub>F_D1</sub>	Forward bias voltage	I <sub>F</sub> = 20 mA at 25°C		0.8		V
V <sub>R_D1</sub>	Reverse breakdown voltage	$I_R = 2 \ \mu A \ at \ 25^{\circ}C$			20	V
INTEGRATED BTS	ST DIODE (D2)	1				
V <sub>F_D2</sub>	Forward bias voltage	I <sub>F</sub> = 20 mA at 25°C		0.8		V
V <sub>R_D2</sub>	Reverse breakdown voltage	I <sub>R</sub> = 2 μA at 25°C			20	V
PWM DRIVERS TI	MING					

## **Electrical Characteristics (continued)**

over  $T_J = -40$  to 125°C (unless otherwise noted)

Р	ARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
INTERFACE		·				
LOGIC INPUT (SDA,	SCL, EN_OTG)					
V <sub>IN_LO</sub>	Input low threshold	I2C			0.4	V
V <sub>IN_ HI</sub>	Input high threshold	I2C	1.3			V
	EN DRAIN (SDA, CHRG_OK, C	MPOUT)			1	
V <sub>OUT_LO</sub>	Output saturation voltage	5-mA drain current			0.4	V
V <sub>OUT_ LEAK</sub>	Leakage current	V = 7 V	-1		1	mA
LOGIC OUTPUT OP	EN DRAIN SDA	•				
VOUT LO SDA	Output Saturation Voltage	5 mA drain current			0.4	V
V <sub>OUT_ LEAK_SDA</sub>	Leakage Current	V = 7V	-1		1	mA
	EN DRAIN CHRG_OK	<u> </u>			1	
VOUT LO CHRG OK	Output Saturation Voltage	5 mA drain current			0.4	V
VOUT_ LEAK _CHRG_OK	Leakage Current	V = 7V	-1		1	mA
LOGIC OUTPUT OP	EN DRAIN CMPOUT	•				
VOUT_ LO_CMPOUT	Output Saturation Voltage	5 mA drain current			0.4	V
V <sub>OUT LEAK CMPOUT</sub>	Leakage Current	V = 7V	-1		1	mA
	EN DRAIN (PROCHOT)	<u> </u>			1	
V <sub>OUT_ LO_PROCHOT</sub>	Output saturation voltage	50- $\Omega$ pullup to 1.05 V / 5-mA load			300	mV
VOUT_ LEAK_PROCHOT	Leakage current	V = 5.5 V	-1		1	mA
ANALOG INPUT (ILI	M_HIZ)	<u> </u>			1	
V <sub>HIZ_ LO</sub>	Voltage to get out of HIZ mode	ILIM_HIZ pin rising	0.8			V
V <sub>HIZ_ HIGH</sub>	Voltage to enable HIZ mode	ILIM_HIZ pin falling			0.4	V
ANALOG INPUT (CE	LL_BATPRESZ)				, ,	
V <sub>CELL_4S</sub>	4S	REGN = 6 V, as percentage of REGN	68.4%	75%		
V <sub>CELL_3S</sub>	3S	REGN = 6 V, as percentage of REGN	51.7%	55%	65%	
V <sub>CELL_2S</sub>	2S	REGN = 6 V, as percentage of REGN	35%	40%	49.1%	
V <sub>CELL_1S</sub>	1S	REGN = 6 V, as percentage of REGN	18.4%	25%	31.6%	
V <sub>CELL_BATPRESZ_RISE</sub>	Battery is present		18%			
V <sub>CELL_BATPRESZ_FALL</sub>	Battery is removed	CELL_BATPRESZ falling			15%	
ANALOG INPUT (CC	OMP1, COMP2)	·			L. L	
ILEAK_COMP1	COMP1 Leakage		-120		120	nA
ILEAK COMP2	COMP2 Leakage		-120		120	nA

## 7.6 Timing Requirements

		MIN	TYP MAX	UNIT
I2C TIMINO	G CHARACTERISTICS			
t <sub>r</sub>	SCLK/SDATA rise time		1	μs
t <sub>f</sub>	SCLK/SDATA fall time		300	ns
t <sub>W(H)</sub>	SCLK pulse width high	4	50	μs
t <sub>W(L)</sub>	SCLK Pulse Width Low	4.7		μs
t <sub>SU(STA)</sub>	Setup time for START condition	4.7		μs
t <sub>H(STA)</sub>	START condition hold time after which first clock pulse is generated	4		μs

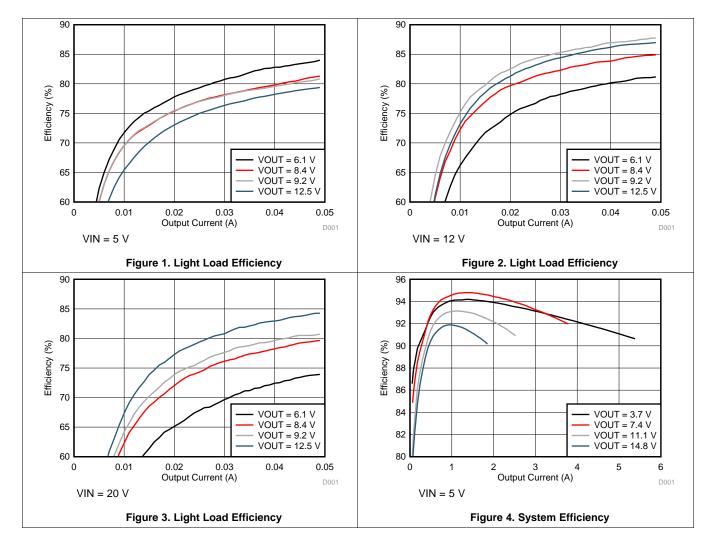


## **Timing Requirements (continued)**

		MIN	TYP	MAX	UNIT
t <sub>SU(DAT)</sub>	Data setup time	250			ns
t <sub>H(DTA)</sub>	Data hold time	300			ns
t <sub>SU(STOP)</sub>	Setup time for STOP condition	4			μs
t <sub>(BUF)</sub>	Bus free time between START and STOP condition	4.7			μs
F <sub>S(CL)</sub>	Clock Frequency	100		400	KHz
HOST COM	IMUNICATION FAILURE				
t <sub>BOOT</sub>	Deglitch for watchdog reset signal	10			ms
	Watchdog timeout period, ChargeOption() bit [6:5] = 01 <sup>(1)</sup>	35	44	53	S
t <sub>WDI</sub>	Watchdog timeout period, ChargeOption() bit bit [6:5] = 10 <sup>(1)</sup>	70	88	105	S
	Watchdog timeout period, ChargeOption() bit bit [6:5] = 11 <sup>(1)</sup> (default)	140	175	210	S

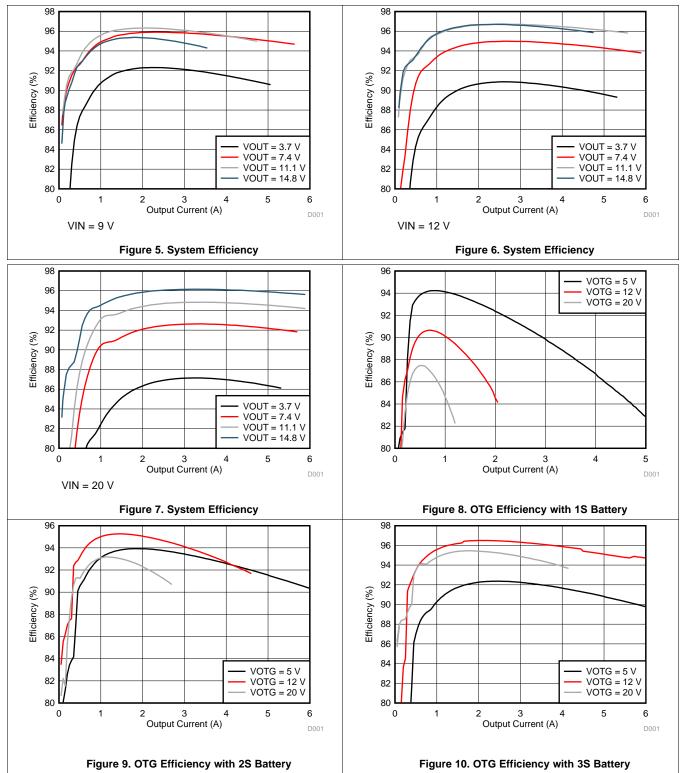
(1) User can adjust threshold via SMBus ChargeOption() REG0x01/00.

## 7.7 Typical Characteristics



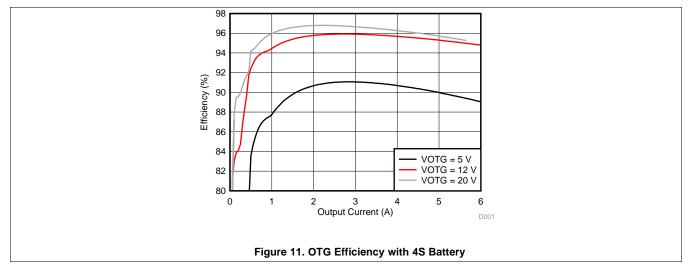


## **Typical Characteristics (continued)**





## **Typical Characteristics (continued)**



## 8 Detailed Description

## 8.1 Overview

The bq25703A is a buck boost NVDC (narrow voltage DC) charge controller for multi-chemistry portable applications such as notebook, detachable, ultrabook, tablet and other mobile devices with rechargeable batteries. It provides seamless transition between converter operation modes (buck, boost, or buck boost), fast transient response, and high light load efficiency.

The bq25703A supports wide range of power sources, including USB PD ports, legacy USB ports, traditional AC-DC adapters, etc. It takes input voltage from 3.5 V to 24 V, and charges battery of 1-4 series. It also supports USB On-The-Go (OTG) to provide 4.48V to 20.8V output at USB port.

The bq25703A features Dynamic Power Management (DPM) to limit the input power and avoid AC adapter overloading. During battery charging, as the system power increases, the charging current will reduce to maintain total input current below adapter rating. If system power demand temporarily exceeds adapter rating, the bq25703A supports NVDC architecture to allow battery discharge energy to supplement system power. For details, refer to *System Voltage Regulation* section.

In order to be compliant with Intel IMVP8 compliant system, the bq25703A includes PSYS function to monitor the total platform power from adapter and battery. Besides PSYS, it provides both an independent input current buffer (IADPT) and a battery current buffer (IBAT) with highly accurate current sense amplifiers. If the platform power exceeds the available power from adapter and battery, a PROCHOT signal is asserted to CPU so that the CPU optimizes its performance to the power available to the system.

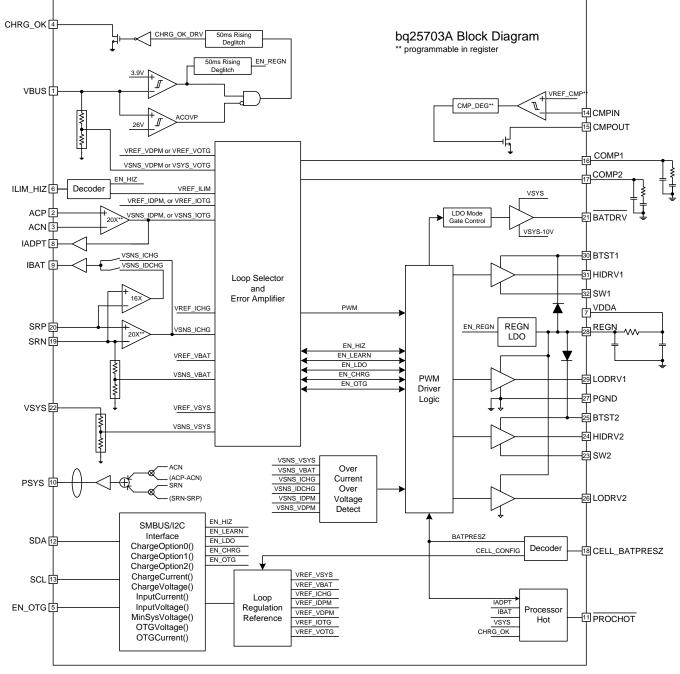
The I2C controls input current, charge current and charge voltage registers with high resolution, high accuracy regulation limits. It also sets the PROCHOT timing and threshold profile to meet system requirements.

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## 8.2 Functional Block Diagram



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## 8.3 Feature Description

### 8.3.1 Power-Up from Battery Without DC Source

If only battery is present and the voltage is above  $V_{VBAT\_UVLOZ}$ , the BATFET turns on and connects battery to system. By default, the charger is in low power mode (REG0x01[7] = 1) with lowest quiescent current. The LDO stays off. When device moves to performance mode (REG0x01[7] = 0), The host enables IBAT buffer through I2C to monitor discharge current. For PSYS, PROCHOT or independent comparator, REGN LDO is enabled for an accurate reference.

## 8.3.2 Power-Up From DC Source

When an input source plugs in, the charger checks the input source voltage to turn on LDO and all the bias circuits. It sets the input current limit before the converter starts.

The power-up sequence from DC source is as follows:

- 1. 50 ms after VBUS above V<sub>VBUS CONVEN</sub>, enable 6 V LDO and CHRG\_OK goes HIGH
- 2. Input voltage and current limit setup
- 3. Battery CELL configuration
- 4. 150 ms after VBUS above  $V_{VBUS CONVEN}$ , converter powers up.

### 8.3.2.1 CHRG\_OK Indicator

CHRG\_OK is an active HIGH open drain indicator. It indicates the charger is in normal operation when the following conditions are valid:

- VBUS is above V<sub>VBUS\_CONVEN</sub>
- VBUS is below V<sub>ACOV</sub>
- No MOSFET/inductor fault

### 8.3.2.2 Input Voltage and Current Limit Setup

After CHRG\_OK goes HIGH, the charger sets default input current limit in REG0x0F/0E() to 3.30 A. The actual input current limit is the lower setting of REG0x0F/0E() and ILIM\_HIZ pin.

Charger initiates a VBUS voltage measurement without load (VBUS at noLoad). The default VINDPM threshold is VBUS at noLoad – 1.28 V.

After input current and voltage limits are set, the charger device is ready to power up. The host can always update input current and voltage limit based on input source type.

#### 8.3.2.3 Battery Cell Configuration

CELL\_BATPRESZ pin is biased with resistors from REGN to CELL\_BATPRESZ to GND. After VDDA LDO is activated, the device detects the battery configuration through CELL\_BATPRESZ pin bias voltage. Refer to *Electrical Characteristics* for CELL setting thresholds.

CELL COUNT	L COUNT PIN VOLTAGE w.r.t. VDDA BATTERY VOLTAGE (REG0x05/04)		SYSOVP
4S	75%	16.800V	No SYSOVP (Refer to System Overvoltage Protection (SYSOVP) section)
3S	55%	12.592V	18.5V
2S	40%	8.400V	12V
1S	25%	4.192V	5V

#### **Table 1. Battery Cell Configuration**

## 8.3.2.4 Device Hi-Z State

The charger enters Hi-Z mode when ILIM\_HIZ pin voltage is below 0.4 V or REG0x35[7] is set to 1. During Hi-Z mode, the input source is present, and the charger is in the low quiescent current mode with REGN LDO enabled.

## 8.3.3 USB On-The-Go (OTG)

The device supports USB OTG operation to deliver power from the battery to other portable devices through USB port. The OTG mode output voltage is set in REG0x07/06(). The OTG mode output current is set in REG0x09/08(). The OTG operation can be enabled if the conditions are valid:

- Valid battery voltage is set REG0x05/04()
- OTG output voltage is set in REG0x07/06() and output current is set in REG0x09/08()
- EN\_OTG pin is HIGH and REG0x35[4] = 1
- VBUS is below V<sub>VBUS UVLO</sub>
- 10 ms after the above conditions are valid, converter starts and VBUS ramps up to target voltage. CHRG\_OK pin goes HIGH if REG0x01[3] = 1.

### 8.3.4 Converter Operation

The charger employs a synchronous buck-boost converter that allows charging from a standard 5-V or a high-voltage power source. The charger operates in buck, buck-boost and boost mode. The buck-boost can operate uninterruptedly and continuously across the three operation modes.

		•	
MODE	BUCK	BUCK-BOOST	BOOST
Q1	Switching	Switching	ON
Q2	Switching	Switching	OFF
Q3	OFF	Switching	Switching
Q4	ON	Switching	Switching

### **Table 2. MOSFET Operation**

## 8.3.4.1 Inductor Setting through IADPT Pin

The charger reads the inductor value through the IADPT pin.

INDUCTOR IN USE	RESISTOR ON IADPT PIN
1 µH	93 kΩ
2.2 μH	137 kΩ
3.3 µH	169 kΩ

#### Table 3. Inductor Setting on IADPT Pin

### 8.3.4.2 Continuous Conduction Mode (CCM)

With sufficient charge current, the inductor current does not cross 0, which is defined as CCM. The controller starts a new cycle with ramp coming up from 200 mV. As long as error amplifier output voltage is above the ramp voltage, the high-side MOSFET (HSFET) stays on. When the ramp voltage exceeds error amplifier output voltage, HSFET turns off and lowside MOSFET (LSFET) turns on. At the end of the cycle, ramp gets reset and LSFET turns off, ready for the next cycle. There is always break-before-make logic during transition to prevent cross-conduction and shoot-through. During the dead time when both MOSFETs are off, the body-diode of the low-side power MOSFET conducts the inductor current.

During CCM, the inductor current always flows and creates a fixed two-pole system. Having the LSFET turn-on keeps the power dissipation low and allows safe charging at high currents.

### 8.3.4.3 Pulse Frequency Modulation (PFM)

In order to improve converter light-load efficiency, the bq25703A switches to PFM control at light load when inductor current is less than 500 mA. The effective switching frequency will decrease accordingly when system load decreases. The minimum frequency can be limit to 25 kHz (ChargeOption0() bit[10]=1). To have higher light load efficiency, set EN\_OOA bit low (Chargeoption0() bit[10] = 0).



#### 8.3.5 Current and Power Monitor

### 8.3.5.1 High-Accuracy Current Sense Amplifier (IADPT and IBAT)

As an industry standard, a high-accuracy current sense amplifier (CSA) is used to monitor the input current during forward charging, or output current during OTG (IADPT) and the charge/discharge current (IBAT). IADPT voltage is 20x or 40x the differential voltage across ACP and ACN. IBAT voltage is 8x/16x (during charging), or 8x/16x (during discharging) of the differential across SRP and SRN. After input voltage or battery voltage is above UVLO, IADPT output becomes valid. To lower the voltage on current monitoring, a resistor divider from CSA output to GND can be used and accuracy over temperature can still be achieved.

- V<sub>(IADPT)</sub> = 20 or 40 × (V<sub>(ACP)</sub> V<sub>(ACN)</sub>) during forward mode, or 20 or 40 × (V<sub>(ACN)</sub> V<sub>(ACP)</sub>) during reverse OTG mode.
- $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRP)} V_{(SRN)}) \text{ during forward mode.}$
- $V_{(IBAT)} = 8 \text{ or } 16 \times (V_{(SRN)} V_{(SRP)})$  during forward mode, or reverse OTG mode.

A maximum 100-pF capacitor is recommended to connect on the output for decoupling high-frequency noise. An additional RC filter is optional, if additional filtering is desired. Note that adding filtering also adds additional response delay. The CSA output voltage is clamped at 3.3 V.

### 8.3.5.2 High-Accuracy Power Sense Amplifier (PSYS)

The charger monitors total system power. During forward mode, the input adapter powers system. During reverse OTG mode, the battery powers the system and VBUS output. The ratio of PSYS current and total power  $K_{PSYS}$  can be programmed in REG0x31[1] with default 1  $\mu$ A/W. The input and charge sense resistors (RAC and RSR) are programmed in REG0x31[3:2]. PSYS voltage can be calculated with Equation 1 where IIN>0 when adapter is in forward charging, and IBAT>0 when the battery is in discharge when the battery is in discharge.

$$V_{PSYS} = R_{PSYS} \times K_{PSYS} (V_{ACP} \times I_{IN} + V_{BAT} \times I_{BAT})$$

(1)

For proper PSYS functionality, RAC and RSR values are limited to 10 m $\Omega$  and 20 m $\Omega$ .

### 8.3.6 Input Source Dynamic Power Manage

Refer to Input Current and Input Voltage Registers for Dynamic Power Management.

### 8.3.7 Two-Level Adapter Current Limit (Peak Power Mode)

Usually adapter can supply current higher than DC rating for a few milliseconds to tens of milliseconds. The charger employs two-level input current limit, or peak power mode, to fully utilize the overloading capability and minimize battery discharge during CPU turbo mode. Peak power mode is enabled in REG0x33[5]. The DC current limit, or  $I_{LIM1}$ , is the same as adapter DC current, set in REG0x0F/0E(). The overloading current, or  $I_{LIM2}$ , is set in REG0x37[7:3], as in percentage of  $I_{LIM1}$ .

When the charger detects input current surge and battery discharge due to load transient, it applies  $I_{LIM2}$  for  $T_{OVLD}$  in REG0x33[7:6], first, and then  $I_{LIM1}$  for up to  $T_{MAX} - T_{OVLD}$  time.  $T_{MAX}$  is programmed in REG0x33[1:0]. After  $T_{MAX}$ , if the load is still high, another peak power cycle starts. Charging is disabled during  $T_{MAX}$ ; once  $T_{MAX}$ , expires, charging continues.



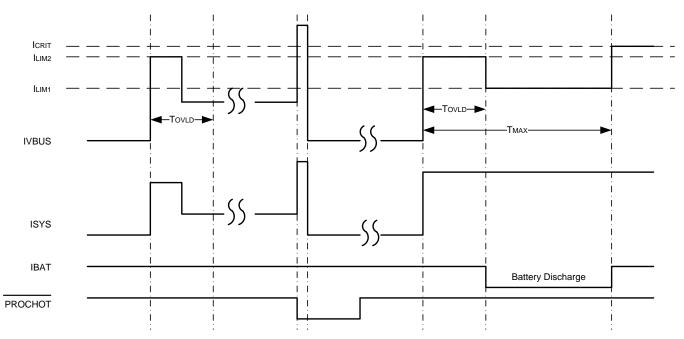


Figure 12. Two-Level Adapter Current Limit Timing Diagram

### 8.3.8 Processor Hot Indication

When CPU is running turbo mode, the system peak power may exceed available power from adapter and battery together. The adapter current and battery discharge peak current, or system voltage drop is indications that system power are too high. The charger processor hot function monitors these events, and PROCHOT pulse is asserted. Once CPU receives PROCHOT pulse from charger, it slows down to reduce system power. The processor hot function monitors these events, and PROCHOT pulse is asserted.

The **PROCHOT** triggering events include:

- ICRIT: adapter peak current, as 110% of ILIM2
- INOM: adapter average current (110% of input current limit)
- IDCHG: battery discharge current
- VSYS: system voltage on VSYS
- Adapter Removal: upon adapter removal (CHRG\_OK pin HIGH to LOW)
- Battery Removal: upon battery removal (CELL\_BATPRESZ pin goes LOW)
- CMPOUT: Independent comparator output (CMPOUT pin HIGH to LOW)

The threshold of ICRIT, IDCHG or VSYS, and the deglitch time of ICRIT, INOM, IDCHG or CMPOUT are programmable through I2C. Each triggering event can be individually enabled in REG0x38[6:0]. When any event in PROCHOT profile is triggered, PROCHOT is asserted low for minimum 10 ms programmable in 0x36[4:3]. At the end of the 10 ms, if the PROCHOT event is still active, the pulse gets extended.



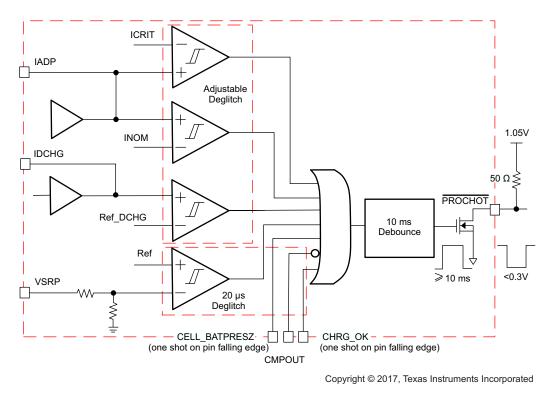


Figure 13. PROCHOT Profile

## 8.3.8.1 **PROCHOT** During Low Power Mode

<u>During low</u> power mode (REG0x01[7] = 1), the charger offers a low quiescent current (~150  $\mu$ A) Low power PROCHOT function uses the independent comparator to monitor battery discharge current and system voltage, and assert PROCHOT to CPU.

Below lists the register setting to enable **PROCHOT** during low power mode.

- REG0x01[7] = 1
- REG0x38[5:0] = 000000
- REG0x30[6:4] = 100
- Independent comparator threshold is always 1.2 V
- When REG0x31[6] = 1, charger monitors discharge current. Connect CMPIN to voltage proportional to IBAT pin. PROCHOT triggers from HIGH to LOW when CMPIN voltage falls below 1.2 V.
- <u>When REG</u>0x31[5] = 1, charger monitors system voltage. Connect CMPIN to voltage proportional to system. PROCHOT triggers from HIGH to LOW when CMPIN voltage rises above 1.2 V.



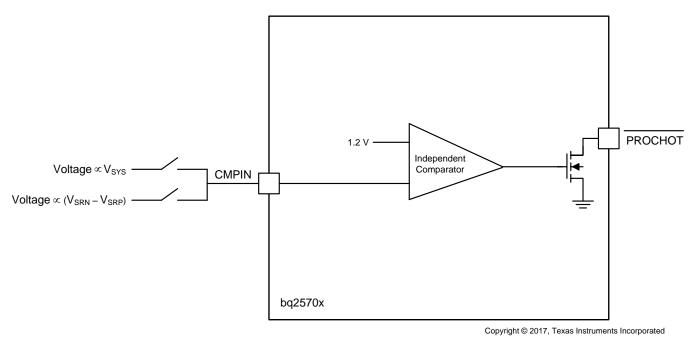


Figure 14. **PROCHOT** Low Power Mode Implementation

## 8.3.8.2 **PROCHOT** Status

REG0x22[6:0] reports which event in the profile triggers PROCHOT by setting the corresponding bit to 1. The status bit can be reset back to 0 after it is read by host, and current PROCHOT event is no longer active.

Assume there are two PROCHOT events, event A and event B. Event A triggers PROCHOT first, but event B is also active. Both status bits will be HIGH. At the end of the 10 ms PROCHOT pulse, if PROCHOT is still active (either by A or B), the PROCHOT pulse is extended.

### 8.3.9 Device Protection

### 8.3.9.1 Watchdog Timer

The charger includes watchdog timer to terminate charging if the charger does not receive a write MaxChargeVoltage() or write ChargeCurrent() command within 175 s (adjustable via REG0x01[6:5]). When watchdog timeout occurs, all register values are kept unchanged except ChargeCurrent() resets to zero. Battery charging is suspended. Write MaxChargeVoltage() or write ChargeCurrent() commands must be re-sent to reset watchdog timer and resume charging. Writing REG0x01[6:5] = 00 to disable watchdog timer also resumes charging.

### 8.3.9.2 Input Overvoltage Protection (ACOV)

The charger has fixed ACOV voltage. When VBUS pin voltage is higher than ACOV, it is considered as adapter over voltage. CHRG\_OK will be pulled low, and converter will be disabled. As system falls below battery voltage, BATFET will be turned on. When VBUS pin voltage falls below ACOV, it is considered as adapter voltage returns back to normal voltage. CHRG\_OK is pulled high by external pull up resistor. The converter resumes if enable conditions are valid.

## 8.3.9.3 Input Overcurrent Protection (ACOC)

If the input current exceeds the 1.25× or 2× (REG0x32[2]) of I<sub>LIM2</sub>\_VTH (REG0x37[7:3]) set point, converter stops switching. After 300 ms, converter starts switching again.



### 8.3.9.4 System Overvoltage Protection (SYSOVP)

When the converter starts up, the bq25700 reads CELL pin configuration and sets MaxChargeVoltage() and SYSOVP threshold (1s - 5 V, 2s - 12 V, 3s - 18.5 V). Before REGx05/04() is written by the host, the battery configuration will change with CELL pin voltage. When SYSOVP happens, the device latches off the converter. REG20[4] is set as 1. The user can clear latch-off by either writing 0 to the SYSOVP bit or removing and plugging in the adapter again. After latch-off is cleared, the converter starts again.

### 8.3.9.5 Battery Overvoltage Protection (BATOVP)

Battery over-voltage may happen when battery is removed during charging or the user plugs in a wrong battery. The BATOVP threshold is 104% (1 s) or 102% (2 s to 4 s) of regulation voltage set in REG0x05/04().

#### 8.3.9.6 Battery Short

If BAT voltage falls below SYSMIN during charging, the maximum current is limited to 384 mA.

### 8.3.9.7 Thermal Shutdown (TSHUT)

The WQFN package has low thermal impedance, which provides good thermal conduction from the silicon to the ambient, to keep junction temperatures low. As added level of protection, the charger converter turns off for self-protection whenever the junction temperature exceeds the 155°C. The charger stays off until the junction temperature falls below 135°C. During thermal shut down, the LDO current limit is reduced to 16 mA and REGN LDO stays off. When the temperature falls below 135°C, charge can be resumed with soft start.

### 8.4 Device Functional Modes

#### 8.4.1 Forward Mode

When input source is connected to VBUS, bq25703A is in forward mode to regulate system and charge battery.

#### 8.4.1.1 System Voltage Regulation with Narrow VDC Architecture

The bq25703A employs Narrow VDC architecture (NVDC) with BATFET separating system from battery. The minimum system voltage is set by MinSystemVoltage(). Even with a deeply depleted battery, the system is regulated above the minimum system voltage.

When the battery is below minimum system voltage setting, the BATFET operates in linear mode (LDO mode).

As the battery voltage rises above the minimum system voltage, BATFET is fully on when charging or in supplement mode and the voltage difference between the system and battery is the VDS of BATFET. System voltage is regulated 160 mV above battery voltage when BATFET is off (no charging or no supplement current).

See System Voltage Regulation for details on system voltage regulation and register programming.

### 8.4.1.2 Battery Charging

The bq25703A charges 1-4 cell battery in constant current (CC), and constant voltage (CV) mode. Based on CELL\_BATPREZ pin setting, the charger sets default battery voltage 4.2V/cell to ChargeVoltage(), or REG0x05/04(). According to battery capacity, the host programs appropriate charge current to ChargeCurrent(), or 0x03/02(). When battery is full or battery is not in good condition to charge, host terminates charge by setting 0x00[0] to 1, or setting ChargeCurrent() to zero.

See *Feature Description* for details on register programming.

#### 8.4.2 USB On-The-Go

The bq25703A supports USB OTG functionality to deliver power from the battery to other portable devices through USB port (reverse mode). The OTG output voltage is compliant with USB PD specification, including 5 V, 9 V, 15 V, and 20 V (REG0x07/06()). The output current regulation is compliant with USB type C specification, including 500 mA, 1.5 A, 3 A and 5 A (REG0x09/08()).

Similar to forward operation, the device switches from PWM operation to PFM operation at light load to improve efficiency.



## 8.5 Programming

The charger supports battery-charger commands that use either Write-Word or Read-Word protocols, as summarized in . The SMBUS address is 12h (0001001\_X), where X is the read/write bit. The ManufacturerID and DeviceID registers are assigned identify the charger device. The ManufacturerID register command always returns 40h.

### 8.5.1 I<sup>2</sup>C Serial Interface

The bq25703A uses I2C compatible interface for flexible charging parameter programming and instantaneous device status reporting. I<sup>2</sup>C is a bi-directional 2-wire serial interface. Only two bus lines are required: a serial data line (SDA) and a serial clock line (SCL). Devices can be considered as masters or slaves when performing data transfers. A master is the device which initiates a data transfer on the bus and generates the clock signals to permit that transfer. At that time, any device addressed is considered a slave.

The device operates as a slave device with address D6h, receiving control inputs from the master device like micro controller or a digital signal processor through REG00-REG0F. The I<sup>2</sup>C interface supports both standard mode (up to 100 kbits), and fast mode (up to 400 kbits). connecting to the positive supply voltage via a current source or pull-up resistor. When the bus is free, both lines are HIGH. The SDA and SCL pins are open drain.

### 8.5.1.1 Data Validity

The data on the SDA line must be stable during the HIGH period of the clock. The HIGH or LOW state of the data line can only change when the clock signal on the SCL line is LOW. One clock pulse is generated for each data bit transferred.

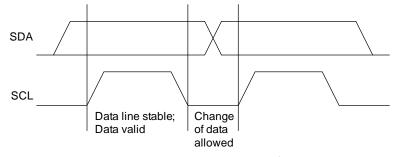


Figure 15. Bit Transfer on the I<sup>2</sup>C Bus

### 8.5.1.2 START and STOP Conditions

All transactions begin with a START (S) and can be terminated by a STOP (P). A HIGH to LOW transition on the SDA line while SCI is HIGH defines a START condition. A LOW to HIGH transition on the SDA line when the SCL is HIGH defines a STOP condition.

START and STOP conditions are always generated by the master. The bus is considered busy after the START condition, and free after the STOP condition.

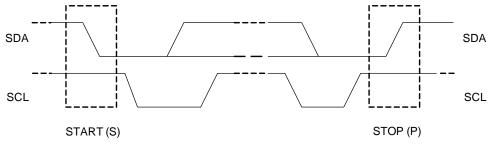


Figure 16. START and STOP Conditions



### Programming (continued)

#### 8.5.1.3 Byte Format

Every byte on the SDA line must be 8 bits long. The number of bytes to be transmitted per transfer is unrestricted. Each byte has to be followed by an Acknowledge bit. Data is transferred with the Most Significant Bit (MSB) first. If a slave cannot receive or transmit another complete byte of data until it has performed some other function, it can hold the clock line SCL low to force the master into a wait state (clock stretching). Data transfer then continues when the slave is ready for another byte of data and release the clock line SCL.

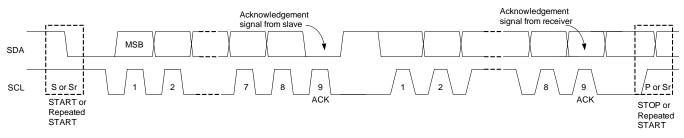


Figure 17. Data Transfer on the I<sup>2</sup>C Bus

### 8.5.1.4 Acknowledge (ACK) and Not Acknowledge (NACK)

The acknowledge takes place after every byte. The acknowledge bit allows the receiver to signal the transmitter that the byte was successfully received and another byte may be sent. All clock pulses, including the acknowledge 9th clock pulse, are generated by the master.

The transmitter releases the SDA line during the acknowledge clock pulse so the receiver can pull the SDA line LOW and it remains stable LOW during the HIGH period of this clock pulse.

When SDA remains HIGH during the 9th clock pulse, this is the Not Acknowledge signal. The master can then generate either a STOP to abort the transfer or a repeated START to start a new transfer.



## **Programming (continued)**

## 8.5.1.5 Slave Address and Data Direction Bit

After the START, a slave address is sent. This address is 7 bits long followed by the eighth bit as a data direction bit (bit R/W). A zero indicates a transmission (WRITE) and a one indicates a request for data (READ).



Figure 18. Complete Data Transfer

### 8.5.1.6 Single Read and Write

:	1	7	1	1	8	1	8	1	1
	S	Slave Address	0	ACK	Reg Addr	ACK	Data to Addr	ACK	P
I —									

Figure 19. Single Write

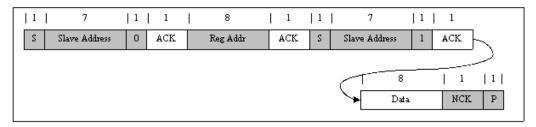


Figure 20. Single Read

If the register address is not defined, the charger IC send back NACK and go back to the idle state.

### 8.5.1.7 Multi-Read and Multi-Write

The charger device supports multi-read and multi-write.

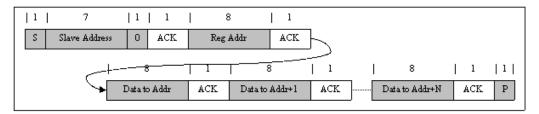


Figure 21. Multi Write

## Programming (continued)

1  7	1   1	8	1   1	7	1   1		
S Slave Add	ress 0 ACK	Reg Addr	ACK S	Slave Address	1 ACK		
	+8	1   8	1	8	1   1		
	Data @ Addr	ACK Data @ Ad	idr+1 ACK	Data @ Add	r+N NCK P		
Data @ Addr ACK Data @ Addr+1 ACK Data @ Addr+N NCK P							

Figure 22. Multi Read

## 8.5.1.8 Write 2-Byte I2C Commands

A few I2C commands combine two 8-bit registers together to form a complete value. These commands include:

- ChargeCurrent()
- MaxChargeVoltage()
- IIN\_DPM()
- OTGVoltage()
- InputVoltage()

Host has to write LSB command followed by MSB command. No other command can be inserted in between these two writes. The charger waits for the complete write to the two registers to decide whether to accept or ignore the new value.

After the completion of LSB and MSB bytes, the two bytes will be updated at the same time. If host writes MSB byte first, the command will be ignored. If the time between write of LSB and MSB bytes exceeds watchdog timer, both the LSB and MSB commands will be ignored.

## 8.6 Register Map

I2C ADDR (MSB/LSB)	REGISTER NAME	TYPE	DESCRIPTION	LINKS
01/00	ChargeOption0()	R/W	Charge Option 0	Go
03/02	ChargeCurrent()	R/W	7-bit charge current setting LSB 64 mA, Range 8128 mA	Go
05/04	MaxChargeVoltage()	R/W	11-bit charge voltage setting LSB 16 mV, Default: 1S-4192mV, 2S-8400mV, 3S-12592mV, 4S-16800mV	Go
31/30	ChargeOption1()	R/W	Charge Option 1	Go
33/32	ChargeOption2()	R/W	Charge Option 2	Go
35/34	ChargeOption3()	R/W	Charge Option 3	Go
37/36	ProchotOption0()	R/W	PROCHOT Option 0	Go
39/38	ProchotOption1()	R/W	PROCHOT Option 1	Go
3B/3A	ADCOption()	R/W	ADC Option	Go
21/20	ChargerStatus()	R	Charger Status	Go
23/22	ProchotStatus()	R	Prochot Status	Go
25/24	IIN_DPM()	R	7-bit input current limit in use LSB: 50 mA, Range: 50 mA - 6400 mA	Go
27/26	ADCVBUS/PSYS()	R	8-bit digital output of input voltage, 8-bit digital output of system power PSYS: Full range: 3.06 V, LSB: 12 mV VBUS: Full range: 3.2 V - 19.52 V, LSB 64 mV	Go

## Table 4. Charger Command Summary



## **Register Map (continued)**

I2C ADDR (MSB/LSB)	REGISTER NAME	TYPE	DESCRIPTION	LINKS
29/28	ADCIBAT()	R	8-bit digital output of battery charge current, 8-bit digital output of battery discharge current ICHG: Full range 8.128 A, LSB 64 mA IDCHG: Full range: 32.512 A, LSB: 256 mA	Go
2B/2A	ADCIINCMPIN()	R	8-bit digital output of input current, 8-bit digital output of CMPIN voltage POR State - IIN: Full range: 12.75 A, LSB 50 mA CMPIN: Full range 3.06 V, LSB: 12 mV	Go
2D/2C	ADCVSYSVBAT()	R	8-bit digital output of system voltage, 8-bit digital output of battery voltage VSYS: Full range: 2.88 V - 19.2 V, LSB: 64 mV VBAT: Full range : 2.88 V - 19.2 V, LSB 64 mV	Go
07/06	OTGVoltage()	R/W	8-bit OTG voltage setting LSB 64 mV, Range: 4480 – 20800 mV	Go
09/08	OTGCurrent()	R/W	7-bit OTG output current setting LSB 50 mA, Range: 0 A – 6350 mA	Go
0B/0A	InputVoltage()	R/W	8-bit input voltage setting LSB 64 mV, Range: 3200 mV – 19520 mV	Go
0D/0C	MinSystemVoltage()	R/W	6-Bit minimum system voltage setting LSB: 256 mV, Range: 1024 mV - 16182 mV Default: 1S-3.584V, 2S-6.144V, 3S-9.216V, 4S- 12.288V	Go
0F/0E	IIN_HOST()	R/W	6-bit Input current limit set by host LSB: 50-mA, Range: 0 mA - 6350 mA	Go
2E	ManufacturerID()	R	Manufacturer ID - 0x0040H	Go
2F	DeviceAddress()	R	Device Address ID	Go

## Table 4. Charger Command Summary (continued)

## 8.6.1 Setting Charge and PROCHOT Options

## 8.6.1.1 ChargeOption0 Register (I2C address = 01/00h) [reset = E20Eh]

## Figure 23. ChargeOption0 Register (I2C address = 01h/00h) [reset = E20Eh]

15	14 13		12	11	10	9	8
EN_LWPWR	VR WDTMR_ADJ		IDPM_AUTO_ DISABLE	OTG_ON_ CHRGOK	EN_OOA	PWM_FREQ	Reserved
R/W	R/W		R/W	R/W	R/W	R/W	R/W
7	7 6 5		4	3	2	1	0
Rese	erved	EN_LEARN	IADPT_GAIN	IBAT_GAIN	EN_LDO	EN_IDPM	CHRG_INHIBIT
R/W R/W		R/W	R/W	R/W	R/W	R/W	

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## Table 5. ChargeOption0 Register (I2C address = 01h) Field Descriptions

l2C 01h	FIELD	TYPE	RESET	DESCRIPTION
7	EN_LWPWR	R/W	1b	Low Power Mode Enable 0b: Disable Low Power Mode. Device in performance mode with battery only. The PROCHOT, current/power monitor buffer and comparator follow register setting. 1b: Enable Low Power Mode. Device in low power mode with battery only for lowest quiescent current. PROCHOT, discharge current monitor buffer, power monitor buffer and independent comparator are disabled. ADC is not available in Low Power Mode.Independent comparator can be enabled by setting either REG0X31()[6] or [5] to 1. <default at="" por=""></default>
6-5	WDTMR_ADJ	R/W	11b	WATCHDOG Timer Adjust Set maximum delay between consecutive I2C write of charge voltage or charge current command. If device does not receive a write on the REG0x05/04() or the REG0x03/02() within the watchdog time period, the charger will be suspended by setting the REG0x03/02() to 0 mA. After expiration, the timer will resume upon the write of REG0x03/02(), REG0x05/04() or REG0x01[6:5]. The charger will resume if the values are valid. 00b: Disable Watchdog Timer 01b: Enabled, 5 sec 10b: Enabled, 88 sec 11b: Enable Watchdog Timer, 175 sec <default at="" por=""></default>
4	IDPM_AUTO_ DISABLE	R/W	Ob	IDPM Auto Disable When CELL_BATPRESZ pin is LOW, the charger automatically disables the IDPM function by setting EN_IDPM (REG0x00[1]) to 0. The host can enable IDPM function later by writing EN_IDPM bit (REG0x00[1]) to 1. 0b: Disable this function. IDPM is not disabled when CELL_BATPRESZ goes LOW. <default at="" por=""> 1b: Enable this function. IDPM is disabled when CELL_BATPRESZ goes LOW.</default>
3	OTG_ON_ CHRGOK	R/W	Ob	Add OTG to CHRG_OK Drive CHRG_OK to HIGH when the device is in OTG mode. 0b: Disable <default at="" por=""> 1b: Enable</default>
2	EN_OOA	R/W	Ob	Out-of-Audio Enable 0b: No limit of PFM burst frequency <default at="" por=""> 1b: Set minimum PFM burst frequency to above 25 kHz to avoid audio noise</default>

## Table 5. ChargeOption0 Register (I2C address = 01h) Field Descriptions (continued)

l2C 01h	FIELD	TYPE	RESET	DESCRIPTION
1	PWM_FREQ	R/W	1b	Switching Frequency
				Two converter switching frequencies. One for small inductor and the other for big inductor.
				Recommend 800 kHz with 2.2 $\mu$ H or 3.3 $\mu$ H, and 1.2 MHz with 1 $\mu$ H or 1.5 $\mu$ H. Host has to set the right PWM frequency after device POR.
				0b: 1200 kHz
				1b: 800 kHz
0	Reserved	R/W	0b	Reserved

## Table 6. ChargeOption0 Register (I2C address = 00h) Field Descriptions

l2C 00h	FIELD	TYPE	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Reserved
5	EN_LEARN	R/W	Ob	LEARN function allows the battery to discharge while the adapter is present. It calibrates the battery gas gauge over a complete discharge/charge cycle. When the battery voltage is below battery depletion threshold, the system switches back to adapter input by the host. When CELL_BATPRESZ pin is LOW, the device exits LEARN mode and this bit is set back to 0. 0b: Disable LEARN Mode <default at="" por=""> 1b: Enable LEARN Mode</default>
4	IADPT_GAIN	R/W	Ob	IADPT Amplifier Ratio The ratio of voltage on IADPT and voltage across ACP and ACN. 0b: 20x <default at="" por=""> 1b: 40x</default>
3	IBAT_GAIN	R/W	1b	IBAT Amplifier Ratio 0b: 8x 1b: 16x <default at="" por=""></default>
2	EN_LDO	R/W	1b	LDO Mode Enable When battery voltage is below minimum system voltage (REG0x0D/0C()), the charger is in pre-charge with LDO mode enabled.
				0b: Disable LDO mode, BATFET fully ON. Precharge current is set by battery pack LDO. The system is regulated by the MaxChargeVoltage register.
				1b: Enable LDO mode, Precharge current is set by the ChargeCurrent register and clamped below 384 mA (2 cell – 4 cell) or 2A (1 cell). The system is regulated by the MinSystemVoltage register. <default at="" por=""></default>
1	EN_IDPM	R/W	1b	IDPM Enable
				Host writes this bit to enable IDPM regulation loop. When the IDPM is disabled by the charger (refer to IDPM_AUTO_DISABLE), this bit goes LOW.
				0b: IDPM disabled
				1b: IDPM enabled <default at="" por=""></default>
0	CHRG_INHIBIT	R/W	0b	Charge Inhibit
				When this bit is 0, battery charging will start with valid values in the MaxChargeVoltage register and the ChargeCurrent register.
				0b: Enable Charge <default at="" por=""></default>
				1b: Inhibit Charge

## 8.6.1.2 ChargeOption1 Register (I2C address = 31h/30h) [reset = 211h]

15	14	13	12	11	10	9	8
EN_IBAT	EN_PROC	HOT_LPWR	EN_PSYS	RSNS_RAC	RSNS_RSR	PSYS_RATIO	Reserved
R/W	R	/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
CMP_REF	CMP_POL	CMP_	DEG	FORCE_ LATCHOFF	Reserved	EN_SHIP_ DCHG	AUTO_ WAKEUP_EN
R/W	R/W	R/	W	R/W	R/W	R/W	R/W

## Figure 24. ChargeOption1 Register (I2C address = 31h/30h) [reset = 211h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## Table 7. ChargeOption1 Register (I2C address = 31h) Field Descriptions

l2C 31h	FIELD	TYPE	RESET	DESCRIPTION	
7	EN_IBAT	R/W	Ob	IBAT Enable Enable the IBAT output buffer. In low power mode (REG0x01[7] = 1), IBAT buffer is always disabled regardless of this bit value. 0b Turn off IBAT buffer to minimize Iq <default at="" por=""> 1b: Turn on IBAT buffer</default>	
6-5	EN_PROCHOT _LPWR	R/W	00b	Enable PROCHOT during battery only low power mode With battery only, enable IDCHG or VSYS in PROCHOT with low power consumption. Do not enable this function with adapter present. Refer to PROCHOT During Low Power Mode for more details. 00b: Disable low power PROCHOT <default at="" por=""> 01b: Enable IDCHG low power PROCHOT 10b: Enable VSYS low power PROCHOT 11b: Reserved</default>	
4	EN_PSYS	R/W	Ob	<ul> <li>PSYS Enable</li> <li>Enable PSYS sensing circuit and output buffer (whole PSYS circuit). In low power mode (REG0x01[7] = 1), PSYS sensing and buffer are always disabled regardless of this bit value.</li> <li>0b: Turn off PSYS buffer to minimize Iq <default at="" por=""></default></li> <li>1b: Turn on PSYS buffer</li> </ul>	
3	RSNS_RAC	R/W	0b	Input sense resistor RAC 0b: 10 m $\Omega$ <default at="" por=""> 1b: 20 m<math>\Omega</math></default>	
2	RSNS_RSR	R/W	Ob	Charge sense resistor RSR 0b: 10 m $\Omega$ <default at="" por=""> 1b: 20 m<math>\Omega</math></default>	
1	PSYS_RATIO	R/W	1b	<ul> <li>PSYS Gain</li> <li>Ratio of PSYS output current vs total input and battery power with 10-mΩ sense resistor.</li> <li>0b: 0.25 µA/W</li> <li>1b: 1 µA/W <default at="" por=""></default></li> </ul>	
0	Reserved	R/W	0b	Reserved	

## Table 8. ChargeOption1 Register (I2C address = 30h) Field Descriptions

12C 30h	FIELD	TYPE	RESET	DESCRIPTION	
7	CMP_REF	R/W	0b	Independent Comparator Reference	
				Independent comparator internal reference.	
				0b: 2.4 V <default at="" por=""></default>	
				1b: 1.3 V	



# Table 8. ChargeOption1 Register (I2C address = 30h) Field Descriptions (continued)

12C 30h	FIELD	TYPE	RESET	DESCRIPTION					
6	CMP_POL	R/W	0b	Independent Comparator Polarity					
				Independent comparator output polarity					
				0b: When CMPIN is above internal threshold, CMPOUT is LOW (internal					
				hysteresis) <default at="" por=""></default>					
				1b: When CMPIN is below internal threshold, CMPOUT is LOW (external hysteresis)					
5-4	CMP_DEG	R/W	01b	Independent Comparator Deglitch Time					
				Independent comparator deglitch time, only applied to the falling edge of CMPOUT (HIGH $\rightarrow$ LOW).					
				00b: Independent comparator is disabled					
				01b: Independent comparator is enabled with output deglitch time 1 $\mu$ s <default a="" por=""></default>					
				10b: Independent comparator is enabled with output deglitch time of 2 ms					
				11b: Independent comparator is enabled with output deglitch time of 5 sec					
3	FORCE_LATCHOFF	R/W	0b	Force Power Path Off					
				When comparator triggers, charger turns off Q1 and Q4 (same as disable converter) so that the system is disconnected from the input source. At the same time, CHRG_OK signal goes to LOW to notify the system.					
				0b: Disable this function <default at="" por=""></default>					
				1b: Enable this function					
2	Reserved	R/W	0b	Reserved					
1	EN_SHIP_DCHG	R/W	0b	Discharge SRN for Shipping Mode					
				When this bit is 1, discharge SRN pin down below 3.8 V in 140 ms. When 140 ms is over, this bit is reset to 0.					
				0b: Disable shipping mode <default at="" por=""></default>					
				1b: Enable shipping mode					
0	AUTO_WAKEUP_EN	R/W	1b	Auto Wakeup Enable					
				When this bit is HIGH, if the battery is below minimum system voltage (REG0x0D/0C()), the device will automatically enable 128 mA charging current for 30 mins. When the battery is charged up above minimum system voltage, charge will terminate and the bit is reset to LOW.					
				0b: Disable					
				1b: Enable <default at="" por=""></default>					

## 8.6.1.3 ChargeOption2 Register (I2C address = 33h/32h) [reset = 2B7]

15	15 14 13		12	11	10	9	8
PKPWR_TC	OVLD_DEG	EN_PKPWR_ IDPM	EN_PKPWR_ VSYS	PKPWR_ OVLD_STAT	PKPWR_ RELAX_STAT	PKPWR_	TMAX[1:0]
R/W		R/W	R/W	R/W	R/W	R/W	
7	6	5	4	3	2	1	0
EN_EXTILIM	EN_ICHG _IDCHG	Q2_OCP	ACX_OCP	EN_ACOC	ACOC_VTH	EN_BATOC BATOC_V	
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

# Figure 25. ChargeOption2 Register (I2C address = 33h/32h) [reset = 2B7]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 9. ChargeOption2 Register (I2C address = 33h) Field Descriptions

l2C 33h	FIELD	TYPE	RESET	DESCRIPTION			
7-6	PKPWR_ TOVLD_DEG	R/W	00b	Input Overload time in Peak Power Mode 00b: 1 ms <default at="" por=""> 01b: 2 ms 10b: 10 ms 11b: 20 ms</default>			
5	EN_PKPWR_IDPM	R/W	Ob	Enable Peak Power Mode triggered by input current overshoot If REG0x33[5:4] are 00b, peak power mode is disabled. Upon adapt removal, the bits are reset to 00b. 0b: Disable peak power mode triggered by input current overshoo <default at="" por=""> 1b: Enable peak power mode triggered by input current overshoot.</default>			
4	EN_PKPWR_VSYS	R/W	Ob	Enable Peak Power Mode triggered by input current overshoot. Enable Peak Power Mode triggered by system voltage under-shoot If REG0x33[5:4] are 00b, peak power mode is disabled. Upon adapter removal, the bits are reset to 00b. 0b: Disable peak power mode triggered by system voltage under-shoot default at POR> 1b: Enable peak power mode triggered by system voltage under-shoot			
3	PKPWR_ OVLD_STAT	R/W	Ob	Indicator that the device is in overloading cycle. Write 0 to get out of overloading cycle. 0b: Not in peak power mode. <default at="" por=""> 1b: In peak power mode.</default>			
2	PKPWR_ RELAX_STAT	R/W	Ob	Indicator that the device is in relaxation cycle. Write 0 to get out of relaxation cycle. 0b: Not in relaxation cycle. <default at="" por=""> 1b: In relaxation mode.</default>			
1-0	PKPWR_ TMAX[1:0]	R/W	10b	Peak power mode overload and relax cycle time. When REG0x33[7:6] is programmed longer than REG0x33[1:0], there is no relax time. 00b: 5 ms 01b: 10 ms 10b: 20 ms <default at="" por=""> 11b: 40 ms</default>			



# Table 10. ChargeOption2 Register (I2C address = 32h) Field Descriptions

l2C 32h	FIELD	ТҮРЕ	RESET	DESCRIPTION		
7	EN_EXTILIM	R/W	1b	Enable ILIM_HIZ pin to set input current limit 0b: Input current limit is set by REG0x0F/0E. 1b: Input current limit is set by the lower value of ILIM_HIZ pin an REG0x0F/0E. <default at="" por=""></default>		
6	EN_ICHG _IDCHG	R/W	0b	0b: IBAT pin as discharge current. <default at="" por=""> 1b: IBAT pin as charge current.</default>		
5	Q2_OCP	R/W	1b	Q2 OCP threshold by sensing Q2 VDS 0b: 210 mV 1b: 150 mV <default at="" por=""></default>		
4	ACX_OCP	R/W	1b	Input current OCP threshold by sensing ACP-ACN. 0b: 280 mV 1b: 150 mV <default at="" por=""></default>		
3	EN_ACOC	R/W	Ob	ACOC Enable Input overcurrent (ACOC) protection by sensing the voltage across ACP and ACN. Upon ACOC (after 100-µs blank-out time), converter is disabled. 0b: Disable ACOC <default at="" por=""> 1b: ACOC threshold 125% or 200% ICRIT</default>		
2	ACOC_VTH	R/W	1b	ACOC Limit Set MOSFET OCP threshold as percentage of IDPM with current sensed from R <sub>AC</sub> . 0b: 125% of ICRIT 1b: 210% of ICRIT		
1	EN_BATOC	R/W	1b	<ul> <li>BATOC Enable</li> <li>Battery discharge overcurrent (BATOC) protection by sensing the voltage across SRN and SRP. Upon BATOC, converter is disabled.</li> <li>Ob: Disable BATOC</li> <li>1b: BATOC threshold 125% or 200% PROCHOT IDCHG <default at="" por=""></default></li> </ul>		
0	BATOC_VTH	R/W	1b	Set battery discharge overcurrent threshold as percentage of PROCHOT battery discharge current limit. 0b: 125% of PROCHOT IDCHG 1b: 200% of PROCHOT IDCHG <default at="" por=""></default>		

## 8.6.1.4 ChargeOption3 Register (I2C address = 35h/34h) [reset = 0h]

15	14	13	12	11	10	9	8
EN_HIZ	RESET_REG	RESET_ VINDPM	EN_OTG	EN_ICO_MOD E		Reserved	
R/W	R/W	R/W	R/W	R/W		R/W	
7	6	5	4	3	2	1	0
			BATFETOFF_ HIZ	PSYS_OTG_ IDCHG			
		R/W	R/W				

#### Figure 26. ChargeOption3 Register (I2C address = 35h/34h) [reset = 0h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

### Table 11. ChargeOption3 Register (I2C address = 35h) Field Descriptions

l2C 35h	FIELD	ТҮРЕ	RESET	DESCRIPTION			
7	EN_HIZ	R/W	Ob	Device Hi-Z Mode Enable When the charger is in Hi-Z mode, the device draws minimal quiescent current. With VBUS above UVLO. REGN LDO stays on, and system powers from battery. 0b: Device not in Hi-Z mode <default at="" por=""> 1b: Device in Hi-Z mode</default>			
6	RESET_REG	R/W	Ob	Reset Registers All the registers go back to the default setting except the VINDPM register. 0b: Idle <default at="" por=""> 1b: Reset all the registers to default values. After reset, this bit goes ba to 0.</default>			
5	RESET_VINDPM	R/W	Ob	Reset VINDPM Threshold 0b: Idle 1b: Converter is disabled to measure VINDPM threshold. After VINDPM measurement is done, this bit goes back to 0 and converter starts.			
4	EN_OTG	R/W	Ob	OTG Mode Enable Enable device in OTG mode when EN_OTG pin is HIGH. 0b: Disable OTG <default at="" por=""> 1b: Enable OTG mode to supply VBUS from battery.</default>			
3	EN_ICO_MODE	R/W	Ob	Enable ICO Algorithm 0b: Disable ICO algorithm. <default at="" por=""> 1b: Enable ICO algorithm.</default>			
2-0	Reserved	R/W	0b	Reserved			

Table 12. ChargeOption3 Register (I2C address = 34h) Field Descriptions

l2C 34h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-2	Reserved	R/W	0b	Reserved
1	BATFETOFF_ HIZ	R/W	Ob	Control BATFET during HIZ mode. 0b: BATFET on during Hi-Z 1b: BATFET off during Hi-Z
0	PSYS_OTG_ IDCHG	R/W	Ob	PSYS function during OTG mode. 0b: PSYS as battery discharge power minus OTG output power 1b: PSYS as battery discharge power only

## 8.6.1.5 ProchotOption0 Register (I2C address = 37h/36h) [reset = 04A54h]

	15-11	10	8		
	ILIM2_VTH	ICRIT	Reserved		
	R/W	R/	R/W		
7-6	5	4-3	2	1	0
VSYS_VTH	EN_PROCHOT _EXT	PROCHOT_WIDTH	PROCHOT_ CLEAR	INOM_DEG	Reserved
R/W	R/W	R/W	R/W	R/W	R/W

## Figure 27. ProchotOption0 Register (I2C address = 37h/36h) [reset = 04A54h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 13. ProchotOption0 Register (I2C address = 37h) Field Descriptions

l2C 37h	FIELD	TYPE	RESET	DESCRIPTION
7-3	ILIM2_VTH	R/W	01001Ь	I <sub>LIM2</sub> Threshold 5 bits, percentage of IDPM in 0x0F/0EH. Measure current between ACP and ACN. Trigger when the current is above this threshold: 00001b - 11001b: 110% - 230%, step 5% 11010b - 11110b: 250% - 450%, step 50% 11111b: Out of Range (Ignored) Default 150%, or 01001
2-1	ICRIT_DEG	R/W	01b	ICRIT Deglitch time ICRIT is set to be 110% of <sub>ILIM2</sub> . Typical ICRIT deglitch time to trigger PROCHOT. 00b: 15 μs 01b: 100 μs <default at="" por=""> 10b: 400 μs (max 500 us) 11b: 800 μs (max 1 ms)</default>
0	Reserved	R/W	0b	Reserved

#### Table 14. ProchotOption0 Register (I2C address = 36h) Field Descriptions

12C 36h	FIELD	TYPE	RESET	DESCRIPTION			
7-6	VSYS_VTH	R/W	01b	VSYS Threshold			
				Measure on VSYS with fixed 20- $\mu s$ deglitch time. Trigger when SYS pin voltage is below the threshold.			
				00b: 5.75 V (2-4 s) or 2.85 V (1 s)			
				01b: 6 V (2-4 s) or 3.1 V (1 s) <default at="" por=""></default>			
				10b: 6.25 V (2-4 s) or 3.35 V (1 s)			
				11b: 6.5 V (2-4 s) or 3.6 V (1 s)			
5	EN_PROCHOT _EXT	R/W	0b	When pulse extension is enabled, keep the $\overrightarrow{\text{PROCHOT}}$ pin voltage LOW until host writes $0x36[2] = 0$ .			
				0b: Disable pulse extension <default at="" por=""></default>			
				1b: Enable pulse extension			
4-3	PROCHOT	R/W	10b	PROCHOT Pulse Width			
	_WIDTH			PROCHOT Pulse Extension Enable			
				Minimum $\overrightarrow{PROCHOT}$ pulse width when REG0x36[5] = 0			
				00b: 100 µs			
				01b: 1 ms			
				10b: 10 ms <default at="" por=""></default>			
				11b: 5 ms			

# Table 14. ProchotOption0 Register (I2C address = 36h) Field Descriptions (continued)

12C 36h	FIELD	TYPE	RESET	DESCRIPTION
2	PROCHOT CLEAR	R/W	1b	PROCHOT Pulse Clear
				Clear $\overrightarrow{PROCHOT}$ pulse when 0x36[5] = 1.
				0b: Clear PROCHOT pulse and drive PROCHOT pin HIGH.
				1b: Idle <default at="" por=""></default>
1	INOM_DEG	R/W	0b	INOM Deglitch Time
				INOM is always 10% above IDPM in 0x0F/0EH. Measure current between ACP and ACN.
				Trigger when the current is above this threshold.
				0b: 1 ms (must be max) <default at="" por=""></default>
				1b: 50 ms (max 60 ms)
0	Reserved	R/W	0b	Reserved



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## 8.6.1.6 ProchotOption1 Register (I2C address = 39h/38h) [reset = 8120h]

### Figure 28. ProchotOption1 Register (I2C address = 39h/38h) [reset = 8120h]

		9-8					
		IDCHG_DEG					
		R/W					
7	6	5	4	3	2	1	0
Reserved	PROCHOT_PR OFILE_IC	PP_ICRIT	PP_INOM	PP_IDCHG	PP_VSYS	PP_BATPRES	PP_ACOK
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

### Table 15. ProchotOption1 Register (I2C address = 39h) Field Descriptions

12C 39h	FIELD	TYPE	RESET	DESCRIPTION
7-2	IDCHG_VTH	R/W	000000b IDCHG Threshold 6 bit, range, range 0 A to 32256 mA, step 512 mA.	
				Measure current between SRN and SRP.
				Trigger when the discharge current is above the threshold.
				If the value is programmed to 0 mA, PROCHOT is always triggered.
				Default: 16384 mA or 100000
1-0	IDCHG_DEG	R/W	01b	IDCHG Deglitch Time
				00b: 1.6 ms
				01b: 100 μs <default at="" por=""></default>
				10b: 6 ms
				11b: 12 ms

## Table 16. ProchotOption1 Register (I2C address = 38h) Field Descriptions

l2C 38h	FIELD	TYPE	RESET	DESCRIPTION			
7	Reserved	R/W	0b	Reserved			
6	PROCHOT _PROFILE_COMP	R/W	0b       PROCHOT Profile         When all the REG0x34[6:0] bits are 0, PROCHOT function is disable         Bit6 Independent comparator         0b: disable <default at="" por="">         1b: enable</default>				
5	PROCHOT _PROFILE_ICRIT	R/W	1b				
4	PROCHOT _PROFILE_INOM	R/W	0b	0b: disable <default at="" por=""> 1b: enable</default>			
3	PROCHOT _PROFILE_IDCHG	R/W	0b	0b: disable <default at="" por=""> 1b: enable</default>			
2	PROCHOT _PROFILE_VSYS	R/W	0b	0b: disable <default at="" por=""> 1b: enable</default>			
1	PROCHOT _PROFILE_BATPRES	R/W	Ob	0b: disable <default at="" por="">         1b: enable (one-shot falling edge triggered)         If BATPRES is enabled in PROCHOT after the battery is removed, it will immediately send out one-shot PROCHOT pulse.</default>			

# Table 16. ProchotOption1 Register (I2C address = 38h) Field Descriptions (continued)

12C 38h	FIELD	TYPE	RESET	DESCRIPTION
0	PROCHOT _PROFILE_ACOK	R/W	0b	0b: disable <default at="" por=""> 1b: enable</default>
				ChargeOption0[15] = 0 to assert PROCHOT pulse after adapter removal. If PROCHOT_PROFILE_ACOK is enabled in PROCHOT after the adapter is
				removed, it will be pulled low.

#### 8.6.1.7 ADCOption Register (I2C address = 3B/3Ah) [reset = 2000h]

15	14	13			12-8			
ADC_CONV	ADC_START	ADC_ FULLSCALE	Reserved					
R/W	R/W	R/W			R/W			
7	6	5	4	3	2	1	0	
EN_ADC_ CMPIN	EN_ADC_ VBUS	EN_ADC_ PSYS	EN_ADC_ IIN	EN_ADC_ IDCHG	EN_ADC_ ICHG	EN_ADC_ VSYS	EN_ADC_ VBAT	
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	

#### Figure 29. ADCOption Register (I2C address = 3B/3Ah) [reset = 2000h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

The ADC registers are read in the following order: VBAT, VSYS, ICHG, IDCHG, IIN, PSYS, VBUS, CMPIN. ADC is disabled in low power mode. When enabling ADC, the device exit low power mode at battery only.

#### Table 17. ADCOption Register (I2C address = 3Bh) Field Descriptions

I2C 3Bh	FIELD	TYPE	RESET	DESCRIPTION
7	ADC_CONV	R/W	Ob	Typical ADC conversion time is 10 ms. Ob: One-shot update. Do one set of conversion updates to registers REG0x27/26(), REG0x29/28(), REG0x2B/2A(), and REG0x2D/2C() after ADC_START = 1. 1b: Continuous update. Do a set of conversion updates to registers REG0x27/26(), REG0x29/28(), REG0x2B/2A(), and REG0x2D/2C() every 1 sec.
6	ADC_START	R/W	0b	0b: No ADC conversion 1b: Start ADC conversion. After the one-shot update is complete, this bit
				automatically resets to zero
5	ADC_ FULLSCALE	R/W	1b	ADC input voltage range. When input voltage is below 5 V, or battery is 1S, full scale 2.04 V is recommended.
				0b: 2.04 V
				1b: 3.06 V <default at="" por=""></default>
4-0	Reserved	R/W	00000b	Reserved

#### Table 18. ADCOption Register (I2C address = 3Ah) Field Descriptions

I2C 3Ah	FIELD	TYPE	RESET	DESCRIPTION
7	EN_ADC_CMPIN	R/W	Ob	0b: Disable <default at="" por=""> 1b: Enable</default>
6	EN_ADC_VBUS	R/W	Ob	0b: Disable <default at="" por=""> 1b: Enable</default>
5	EN_ADC_PSYS	R/W	Ob	0b: Disable <default at="" por=""> 1b: Enable</default>
4	EN_ADC_IIN	R/W	Ob	0b: Disable <default at="" por=""> 1b: Enable</default>
3	EN_ADC_IDCHG	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>
2	EN_ADC_ICHG	R/W	0b	0b: Disable <default at="" por=""> 1b: Enable</default>
1	EN_ADC_VSYS	R/W	Ob	0b: Disable <default at="" por=""> 1b: Enable</default>

# Table 18. ADCOption Register (I2C address = 3Ah) Field Descriptions (continued)

I2C 3Ah	FIELD	TYPE	RESET	DESCRIPTION
0	EN_ADC_VBAT	R/W	0b 0b: Disable <default at="" por=""></default>	
				1b: Enable

## 8.6.2 Charge and PROCHOT Status

#### 8.6.2.1 ChargerStatus Register (I2C address = 21/20h) [reset = 0000h]

#### Figure 30. ChargerStatus Register (I2C address = 21/20h) [reset = 0000h]

15	14	13	12	11	10	9	8
AC_STAT	ICO_DONE	Reserved	IN_VINDPM	IN_IINDPM	IN_FCHRG	IN_PCHRG	IN_OTG
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
Fault ACOV	Fault BATOC	Fault ACOC	SYSOVP_ STAT	Reserved	Fault Latchoff	Fault_OTG_ OVP	Fault_OTG_ OCP
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 19. ChargerStatus Register (I2C address = 21h) Field Descriptions

l2C 21h	FIELD	TYPE	RESET	DESCRIPTION	
7	AC_STAT	R	Ob	Input source status, same as CHRG_OK bit 0b: Input not present 1b: Input is present	
6	ICO_DONE	R	Ob	After the ICO routine is successfully executed, the bit goes 1. 0b: ICO is not complete 1b: ICO is complete	
5	Reserved	R	0b	Reserved	
4	IN_VINDPM	R	Ob	<ul><li>0b: Charger is not in VINDPM during forward mode, or voltage regulation during OTG mode</li><li>1b: Charger is in VINDPM during forard mode, or voltage regulation during OTG mode</li></ul>	
3	IN_IINDPM	R	0b	0b: Charger is not in IINDPM 1b: Charger is in IINDPM	
2	IN_FCHRG	R	Ob	0b: Charger is not in fast charge 1b: Charger is in fast charger	
1	IN_PCHRG	R	0b	0b: Charger is not in pre-charge 1b: Charger is in pre-charge	
0	IN_OTG	R	0b	0b: Charger is not in OTG 1b: Charge is in OTG	

## Table 20. ChargerStatus Register (I2C address = 20h) Field Descriptions

l2C 20h	FIELD	TYPE	RESET	DESCRIPTION
7	Fault ACOV	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: ACOV
6	Fault BATOC	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: BATOC
5	Fault ACOC	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: ACOC

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# Table 20. ChargerStatus Register (I2C address = 20h) Field Descriptions (continued)

l2C 20h	FIELD	TYPE	RESET	DESCRIPTION
4	SYSOVP_STAT	R	0b	SYSOVP Status and Clear
				When the SYSOVP occurs, this bit is HIGH. During the SYSOVP, the converter is disabled.
				After the SYSOVP is removed, the user must write a 0 to this bit or unplug the adapter to clear the SYSOVP condition to enable the converter again.
				0b: Not in SYSOVP <default at="" por=""></default>
				1b: In SYSOVP. When SYSOVP is removed, write 0 to clear the SYSOVP latch.
3	Reserved	R	0b	Reserved
2	Fault Latchoff	R	0b	The faults are latched until a read from host. 0b: No fault 1b: Latch off (REG0x30[3])
1	Fault_OTG_OVP	R	0b	The faults are latched until a read from host. 0b: No fault 1b: OTG OVP
0	Fault_OTG_UCP	R	Ob	The faults are latched until a read from host. 0b: No fault 1b: OTG OCP



### 8.6.2.2 ProchotStatus Register (I2C address = 23/22h) [reset = 0h]

	15-8										
	Reserved										
	R										
7	6	5	4	3	2	1	0				
Reserved	STAT_COMP	STAT_ICRIT	STAT_INOM	STAT_IDCHG	STAT_VSYS	STAT_Battery_ Removal	STAT_Adapter _Removal				
R	R	R	R	R	R	R	R				

#### Figure 31. ProchotStatus Register (I2C address = 23/22h) [reset = 0h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 21. ProchotStatus Register (I2C address = 23h) Field Descriptions

12C 23h	FIELD	TYPE	RESET	DESCRIPTION					
_	Reserved	R	0b	Reserved					
	Table 22. ProchotStatus Register (I2C address = 22h) Field Descriptions								
l2C 22h	FIELD	TYPE	RESET	DESCRIPTION					
-	Reserved	R	0b	Reserved					
6	STAT_COMP	R	0b	0b: Not triggered 1b: Triggered					
5	STAT_ICRIT	R	0b	0b: Not triggered 1b: Triggered					
4	STAT_INOM	R	0b	0b: Not triggered 1b: Triggered					
3	STAT_IDCHG	R	0b	0b: Not triggered 1b: Triggered					
2	STAT_VSYS	R	0b	0b: Not triggered 1b: Triggered					
1	STAT_Battery_Removal	R	0b	0b: Not triggered 1b: Triggered					
0	STAT_Adapter_Removal	R	0b	0b: Not triggered 1b: Triggered					



#### 8.6.3 ChargeCurrent Register (I2C address = 03/02h) [reset = 0h]

To set the charge current, write a 16-bit ChargeCurrent() command (REG0x03/02()) using the data format listed in Table 23 and Table 24.

With 10-m $\Omega$  sense resistor, the charger provides charge current range of 64 mA to 8.128 A, with a 64-mA step resolution. Upon POR, ChargeCurrent() is 0 A. Any conditions for CHRG\_OK low except ACOV will reset ChargeCurrent() to zero. CELL\_BATPRESZ going LOW (battery removal) will reset the ChargeCurrent() register to 0 A.

Charge current is not reset in ACOC, TSHUT, power path latch off (REG0x30[1]), and SYSOVP.

A 0.1- $\mu$ F capacitor between SRP and SRN for differential mode filtering is recommended; an optional 0.1- $\mu$ F capacitor between SRN and ground, and an optional 0.1- $\mu$ F capacitor between SRP and ground for common mode filtering. Meanwhile, the capacitance on SRP should not be higher than 0.1  $\mu$ F in order to properly sense the voltage across SRP and SRN for cycle-by-cycle current detection.

The SRP and SRN pins are used to sense voltage drop across RSR with default value of 10 m $\Omega$ . However, resistors of other values can also be used. For a larger sense resistor, a larger sense voltage is given, and a higher regulation accuracy; but, at the expense of higher conduction loss. If current sensing resistor value is too high, it may trigger an over current protection threshold because the current ripple voltage is too high. In such a case, either a higher inductance value or a lower current sensing resistor value should be used to limit the current ripple voltage level. A current sensing resistor value no more than 20 m $\Omega$  is suggested.

#### Figure 32. ChargeCurrent Register With 10-m $\Omega$ Sense Resistor (I2C address = 03/02h) [reset = 0h]

15	14	13	12	11	10	9	8
	Reserved		Charge Current, bit 6	Charge Current, bit 5	Charge Current, bit 4	Charge Current, bit 3	Charge Current, bit 2
	R/W		R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Charge Current, bit 1	Charge Current, bit 0	Reserved			Reserved		
R/W	R/W	R/W			R/W		

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

# Table 23. Charge Current Register (14h) With 10-m $\Omega$ Sense Resistor (I2C address = 03h) Field Descriptions

l2C 03h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-5	Reserved	R/W	000b	Not used. 1 = invalid write.
4	Charge Current, bit 6	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 4096 mA of charger current.
3	Charge Current, bit 5	R/W	0b	<ul><li>0 = Adds 0 mA of charger current.</li><li>1 = Adds 2048 mA of charger current.</li></ul>
2	Charge Current, bit 4	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 1024 mA of charger current.
1	Charge Current, bit 3	R/W	Ob	0 = Adds 0 mA of charger current. 1 = Adds 512 mA of charger current.
0	Charge Current, bit 2	R/W	0b	<ul><li>0 = Adds 0 mA of charger current.</li><li>1 = Adds 256 mA of charger current.</li></ul>

# Table 24. Charge Current Register (14h) With 10-m $\Omega$ Sense Resistor (I2C address = 02h) Field Descriptions

l2C 02h	FIELD	TYPE	RESET	DESCRIPTION
7	Charge Current, bit 1	R/W	0b	0 = Adds 0 mA of charger current. 1 = Adds 128 mA of charger current.



# Table 24. Charge Current Register (14h) With 10-m $\Omega$ Sense Resistor (I2C address = 02h) Field Descriptions (continued)

l2C 02h	FIELD	TYPE	RESET	DESCRIPTION
6	Charge Current, bit 0	R/W	Ob	0 = Adds 0 mA of charger current. 1 = Adds 64 mA of charger current.
5-0	Reserved	R/W	00000b	Not used. Value Ignored.

### 8.6.3.1 Battery Pre-Charge Current Clamp

During pre-charge, BATFET works in linear mode or LDO mode (default REG0x00[2] = 1). For 2-4 cell battery, the system is regulated at minimum system voltage in REG0x0D/0C() and the pre-charge current is clamped at 384 mA. For 1 cell battery, the pre-charge to fast charge threshold is 3 V, and the pre-charge current is clamped at 384 mA. However, the BATFET stays in LDO mode operation till battery voltage is above minimum system voltage (~3.6 V). During battery voltage from 3 V to 3.6 V, the fast charge current is clamped at 2 A.



# 8.6.4 MaxChargeVoltage Register (I2C address = 05/04h) [reset value based on CELL\_BATPRESZ pin setting]

To set the output charge voltage, write a 16-bit ChargeVoltage register command (REG0x05/04()) using the data format listed in Table 25 and Table 26. The charger provides charge voltage range from 1.024 V to 19.200 V, with 16-mV step resolution. Any write below 1.024 V or above 19.200 V is ignored. Upon POR or when charge is disabled, the system is regulated at the MaxChargeVoltage register.

Upon POR, REG0x05/04() is by default set as 4192 mV for 1 s, 8400 mV for 2 s, 12592 mV for 3 s or 16800 mV for 4 s. After CHRG\_OK, if host writes REG0x03/02() before REG0x05/04(), the charge will start after the write to REG0x03/02(). If the battery is different from 4.2 V/cell, the host has to write to REG0x05/04() before REG0x03/02() for correct battery voltage setting. Writing REG0x05/04() to 0 will set REG0x05/04() to default value on CELL\_BATPRESZ pin, and force REG0x03/02() to zero to disable charge.

The SRN pin is used to sense the battery voltage for voltage regulation and should be connected as close to the battery as possible, and directly place a decoupling capacitor (0.1  $\mu$ F recommended) as close to the device as possible to decouple high frequency noise.

# Figure 33. MaxChargeVoltage Register (I2C address = 05/04h) [reset value based on CELL\_BATPRESZ pin setting]

15	14	13	12	11	10	9	8
Reserved	Max Charge Voltage, bit 10	Max Charge Voltage, bit 9	Max Charge Voltage, bit 8	Max Charge Voltage, bit 7	Max Charge Voltage, bit 6	Max Charge Voltage, bit 5	Max Charge Voltage, bit 4
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
Max Charge Voltage, bit 3	Max Charge Voltage, bit 2	Max Charge Voltage, bit 1	Max Charge Voltage, bit 0	Reserved			
R/W	R/W	R/W	R/W		R/	W	

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 25. MaxChargeVoltage Register (I2C address = 05h) Field Descriptions

l2C 05h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	Max Charge Voltage, bit 10	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 16384 mV of charger voltage.
5	Max Charge Voltage, bit 9	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 8192 mV of charger voltage
4	Max Charge Voltage, bit 8	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 4096 mV of charger voltage.
3	Max Charge Voltage, bit 7	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 2048 mV of charger voltage.
2	Max Charge Voltage, bit 6	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 1024 mV of charger voltage.
1	Max Charge Voltage, bit 5	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 512 mV of charger voltage.
0	Max Charge Voltage, bit 4	R/W	0b	0 = Adds 0 mV of charger voltage. 1 = Adds 256 mV of charger voltage.

#### Table 26. MaxChargeVoltage Register (I2C address = 04h) Field Descriptions

l2C 04h	FIELD	TYPE	RESET	DESCRIPTION
7	Max Charge Voltage, bit 3	R/W	0b	0 = Adds 0 mV of charger voltage.
				1 = Adds 128 mV of charger voltage.



# Table 26. MaxChargeVoltage Register (I2C address = 04h) Field Descriptions (continued)

l2C 04h	FIELD	TYPE	RESET	DESCRIPTION
6	Max Charge Voltage, bit 2	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 64 mV of charger voltage.
5	Max Charge Voltage, bit 1	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 32 mV of charger voltage.
4	Max Charge Voltage, bit 0	R/W	Ob	0 = Adds 0 mV of charger voltage. 1 = Adds 16 mV of charger voltage.
3-0	Reserved	R/W	0000b	Not used. Value Ignored.



# 8.6.5 MinSystemVoltage Register (I2C address = 0D/0Ch) [reset value based on CELL\_BATPRESZ pin setting]

To set the minimum system voltage, write a 16-bit MinSystemVoltage register command (REG0x0D/0C()) using the data format listed in Table 27 and Table 28. The charger provides minimum system voltage range from 1.024 V to 16.128 V, with 256-mV step resolution. Any write below 1.024 V or above 16.128 V is ignored. Upon POR, the MinSystemVoltage register is 3.584 V for 1 S, 6.144 V for 2 S and 9.216 V for 3 S, and 12.288 V for 4 S.

# Figure 34. MinSystemVoltage Register (I2C address = 0D/0Ch) [reset value based on CELL\_BATPRESZ pin setting]

15	14	13	12	11	10	9	8	
Rese	rved	Min System Voltage, bit 5	Min System Voltage, bit 4	Min System Voltage, bit 3	Min System Voltage, bit 2	Min System Voltage, bit 1	Min System Voltage, bit 0	
R/	W	R/W	R/W	R/W	R/W	R/W	R/W	
7	6	5	4	3	2	1	0	
Reserved								
	R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 27. MinSystemVoltage Register (I2C address = 0Dh) Field Descriptions

I2C 0Dh	FIELD	TYPE	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	Min System Voltage, bit 5	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 8192 mV of system voltage.
4	Min System Voltage, bit 4	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 4096mV of system voltage.
3	Min System Voltage, bit 3	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 2048 mV of system voltage.
2	Min System Voltage, bit 2	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 1024 mV of system voltage.
1	Min System Voltage, bit 1	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 512 mV of system voltage.
0	Min System Voltage, bit 0	R/W	0b	0 = Adds 0 mV of system voltage. 1 = Adds 256 mV of system voltage.

#### Table 28. MinSystemVoltage Register (I2C address = 0Ch) Field Descriptions

I2C 0Ch	FIELD	TYPE	RESET	DESCRIPTION
7-0	Reserved	R/W	0000000 0b	Not used. Value Ignored.

#### 8.6.5.1 System Voltage Regulation

The device employs Narrow VDC architecture (NVDC) with BATFET separating system from battery. The minimum system voltage is set by REG0x0D/0C(). Even with a deeply depleted battery, the system is regulated above the minimum system voltage with BATFET.

When the battery is below minimum system voltage setting, the BATFET operates in linear mode (LDO mode), and the system is regulated above the minimum system voltage setting. As the battery voltage rises above the minimum system voltage, BATFET is fully on when charging or in supplement mode and the voltage difference between the system and battery is the VDS of BATFET. System voltage is regulated 160 mV above battery voltage when BATFET is off (no charging or no supplement current).

When BATFET is removed, the system node VSYS is shorted to SRP. Before the converter starts operation, LDO mode needs to be disabled. The following sequence is required to configure charger without BATFET.

1. Before adapter plugs in, put the charger into HIZ mode. (either pull pin 6 ILIM\_HIZ to ground, or set



(2)

REG0x35[7] to 1)

- 2. Set 0x00[2] to 0 to disable LDO mode.
- 3. Set 0x30[0] to 0 to disable auto-wakeup mode.
- 4. Check if battery voltage is properly programmed (REG0x05/04)
- 5. Set pre-charge/charge current (REG0x03/02)
- 6. Put the device out of HIZ mode. (Release ILIM\_HIZ from ground and set REG0x35[7]=0).

In order to prevent any accidental SW mistakes, the host sets low input current limit (a few hundred milliamps) when device is out of HIZ.

#### 8.6.6 Input Current and Input Voltage Registers for Dynamic Power Management

The charger supports Dynamic Power Management (DPM). Normally, the input power source provides power for the system load or to charge the battery. When the input current exceeds the input current setting, or the input voltage falls below the input voltage setting, the charger decreases the charge current to provide priority to the system load. As the system current rises, the available charge current drops accordingly toward zero. If the system load keeps increasing after the charge current drops down to zero, the system voltage starts to drop. As the system voltage drops below the battery voltage, the battery will discharge to supply the heavy system load.

#### 8.6.6.1 Input Current Registers

To set the maximum input current limit, write a 16-bit IIN\_HOST register command (REG0x0F/0E()) using the data format listed in Table 29 and Table 30. When using a 10-m $\Omega$  sense resistor, the charger provides an inputcurrent limit range of 50 mA to 6400 mA, with 50-mA resolution. The default current limit is 3.3 A. Due to the USB current setting requirement, the register setting specifies the maximum current instead of the typical current. Upon adapter removal, the input current limit is reset to the default value of 3.3 A. The register offset is 50 mA. With code 0, the input current limit is 50 mA.

The ACP and ACN pins are used to sense  $R_{AC}$  with the default value of 10 m $\Omega$ . However, resistors of other values can also be used. For a larger sense resistor, a larger sense voltage is given and a higher regulation accuracy, but at the expense of higher conduction loss.

Instead of using the internal DPM loop, the user can build up an external input current regulation loop and have the feedback signal on the ILIM\_HIZ pin.

$$V_{ILIM HIZ} = 1V + 40 \times (V_{ACP} - V_{ACN}) = 1 + 40 \times I_{DPM} \times R_{AC}$$

In order to disable ILIM\_HIZ pin, the host can write to 0x32[7] to disable ILIM\_HIZ pin, or pull ILIM\_HIZ pin above 4.0 V.

## 8.6.6.1.1 IIN\_HOST Register With 10-m $\Omega$ Sense Resistor (I2C address = 0F/0Eh) [reset = 4000h]

15	14	13	12	11	10	9	8		
Reserved	Input Current set by host, bit 6	Input Current set by host, bit 5	Input Current set by host, bit 4	Input Current set by host, bit 3	Input Current set by host, bit 2	Input Current set by host, bit 1	Input Current set by host, bit 0		
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W		
7	6	5	4	3	2	1	0		
	Reserved								
R									

## Figure 35. IIN\_HOST Register With 10-m $\Omega$ Sense Resistor (I2C address = 0F/0Eh) [reset = 4100h]

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

## Table 29. IIN\_HOST Register With 10-m $\Omega$ Sense Resistor (I2C address = 0Fh) Field Descriptions

l2C 0Fh	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	Input Current set by host, bit 6	R/W	1b	0 = Adds 0 mA of input current. 1 = Adds 3200 mA of input current.
5	Input Current set by host, bit 5	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 1600 mA of input current.
4	Input Current set by host, bit 4	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 800 mA of input current.
3	Input Current set by host, bit 3	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 400 mA of input current.
2	Input Current set by host, bit 2	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 200 mA of input current.
1	Input Current set by host, bit 1	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 100 mA of input current.
0	Input Current set by host, bit 0	R/W	0b	0 = Adds 0 mA of input current. 1 = Adds 50 mA of input current. (12C address = 0Eb) Field Descriptions

## Table 30. IIN\_HOST Register With 10-m $\Omega$ Sense Resistor (I2C address = 0Eh) Field Descriptions

I2C 0Eh	FIELD	TYPE	RESET	DESCRIPTION
7-0	Reserved	R	0000000 0b	Not used. Value Ignored.



#### 8.6.6.1.2 IIN\_DPM Register With 10-m $\Omega$ Sense Resistor (I2C address = 25/24h) [reset = 0h]

IIN\_DPM register reflects the actual input current limit programmed in the register, either from host or from ICO.

After ICO, the current limit used by DPM regulation may differ from the IIN\_HOST register settings. The actual DPM limit is reported in REG0x25/24(). The register offset is 50 mA. With code 0, the input current limit read-back is 50 mA.

#### Figure 36. IIN\_DPM Register With 10-m $\Omega$ Sense Resistor (I2C address = 25/24h) [reset = 0h]

15	14	13	12	11	10	9	8		
Reserved	Input Current in DPM, bit 6	Input Current in DPM, bit 5	Input Current in DPM, bit 4	Input Current in DPM, bit 3	Input Current in DPM, bit 2	Input Current in DPM, bit 1	Input Current in DPM, bit 0		
R	R	R	R	R	R	R	R		
7	6	5	4	3	2	1	0		
	Reserved								
	R								

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 31. IIN\_DPM Register With 10-m $\Omega$ Sense Resistor (I2C address = 25h) Field Descriptions

l2C 25h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R	0b	Not used. 1 = invalid write.
6	Input Current in DPM, bit 6	R	0b	0 = Adds 0 mA of input current. 1 = Adds 3200 mA of input current.
5	Input Current in DPM, bit 5	R	0b	0 = Adds 0 mA of input current. 1 = Adds 1600 mA of input current.
4	Input Current in DPM, bit 4	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 800mA of input current
3	Input Current in DPM, bit 3	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 400 mA of input current.
2	Input Current in DPM, bit 2	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 200 mA of input current.
1	Input Current in DPM, bit 1	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 100 mA of input current.
0	Input Current in DPM, bit 0	R	Ob	0 = Adds 0 mA of input current. 1 = Adds 50 mA of input current.

#### Table 32. IIN\_DPM Register with 10-m $\Omega$ Sense Resistor (I2C address = 24h) Field Descriptions

l2C 24h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-0	Reserved	R	0000000b	Not used. Value Ignored.

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#### 8.6.6.1.3 InputVoltage Register (I2C address = 0B/0Ah) [reset = VBUS-1.28V]

To set the input voltage limit, write a 16-bit InputVoltage register command (REG0x0B/0A()) using the data format listed in Table 33 and Table 34.

If the input voltage drops more than the InputVoltage register allows, the device enters DPM and reduces the charge current. The default offset voltage is 1.28 V below the no-load VBUS voltage. The DC offset is 3.2 V (0000000).

#### Figure 37. InputVoltage Register (I2C address = 0B/0Ah) [reset = VBUS-1.28V]

15	14	13	12	11	10	9	8	
Rese	erved	Input Voltage, bit 7	Input Voltage, bit 6	Input Voltage, bit 5	Input Voltage, bit 4	Input Voltage, bit 3	Input Voltage, bit 2	
R/	W	R/W	R/W	R/W	R/W	R/W	R/W	
7	6	5	4	3	2	1	0	
Input Voltage, bit 1	Input Voltage, bit 0		Reserved					
R/W	R/W	R/W						

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 33. InputVoltage Register (I2C address = 0Bh) Field Descriptions

I2C 0Bh	FIELD	TYPE	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	Input Voltage, bit 7	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 8192 mV of input voltage.
4	Input Voltage, bit 6	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 4096mV of input voltage.
3	Input Voltage, bit 5	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 2048 mV of input voltage.
2	Input Voltage, bit 4	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 1024 mV of input voltage.
1	Input Voltage, bit 3	R/W	0b	0 = Adds 0 mV of input voltage. 1 = Adds 512 mV of input voltage.
0	Input Voltage, bit 2	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 256 mV of input voltage.

Table 34. InputVoltage Register (I2C address = 0Ah) Field Descriptions

I2C 0Ah	FIELD	TYPE	RESET	DESCRIPTION
7	Input Voltage, bit 1	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 128 mV of input voltage.
6	Input Voltage, bit 0	R/W	Ob	0 = Adds 0 mV of input voltage. 1 = Adds 64 mV of input voltage
5-0	Reserved	R/W	00000b	Not used. Value Ignored.





#### 8.6.7 OTGVoltage Register (I2C address = 07/06h) [reset = 0h]

To set the OTG output voltage limit, write to REG0x07/06() using the data format listed in Table 35 and Table 36. The DC offset is 4.48 V (0000000).

#### Figure 38. OTGVoltage Register (I2C address = 07/06h) [reset = 0h]

15	14	13	12	11	10	9	8	
Rese	erved	OTG Voltage, bit 7	OTG Voltage, bit 6	OTG Voltage, bit 5	OTG Voltage, bit 4	OTG Voltage, bit 3	OTG Voltage, bit 2	
R	W	R/W	R/W	R/W	R/W	R/W	R/W	
7	6	5	4	3	2	1	0	
OTG Voltage, bit 1	OTG Voltage, bit 0		Reserved					
R/W	R/W		R/W					

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 35. OTGVoltage Register (I2C address = 07h) Field Descriptions

l2C 07h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-6	Reserved	R/W	00b	Not used. 1 = invalid write.
5	OTG Voltage, bit 7	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 8192 mV of OTG voltage.
4	OTG Voltage, bit 6	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 4096 mV of OTG voltage.
3	OTG Voltage, bit 5	R/W	0b	0 = Adds 0 mV of OTG voltage. 1 = Adds 2048 mV of OTG voltage.
2	OTG Voltage, bit 4	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 1024 mV of OTG voltage.
1	OTG Voltage, bit 3	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 512 mV of OTG voltage.
0	OTG Voltage, bit 2	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 256 mV of OTG voltage.

#### Table 36. OTGVoltage Register (I2C address = 06h) Field Descriptions

12C 06h	FIELD	TYPE	RESET	DESCRIPTION
7	OTG Voltage, bit 1	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 128 mV of OTG voltage.
6	OTG Voltage, bit 0	R/W	Ob	0 = Adds 0 mV of OTG voltage. 1 = Adds 64 mV of OTG voltage.
5-0	Reserved	R/W	00000b	Not used. Value Ignored.

## 8.6.8 OTGCurrent Register (I2C address = 09/08h) [reset = 0h]

To set the OTG output current limit, write to REG0x09/08() using the data format listed in Table 37 and Table 38.

### Figure 39. OTGCurrent Register (I2C address = 09/08h) [reset = 0h]

15	14	13	12	11	10	9	8
Reserved	OTG Current set by host, bit 6	OTG Current set by host, bit 5	OTG Current set by host, bit 4	OTG Current set by host, bit 3	OTG Current set by host, bit 2	OTG Current set by host, bit 1	OTG Current set by host, bit 0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
7	6	5	4	3	2	1	0
	Reserved						
			R/	/W			

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 37. OTGCurrent Register (I2C address = 09h) Field Descriptions

l2C 09h	FIELD	TYPE	RESET	DESCRIPTION
7	Reserved	R/W	0b	Not used. 1 = invalid write.
6	OTG Current set by host, bit 6	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 3200 mA of OTG current.
5	OTG Current set by host, bit 5	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 1600mA of OTG current.
4	OTG Current set by host, bit 4	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 800 mA of OTG current.
3	OTG Current set by host, bit 3	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 400 mA of OTG current.
2	OTG Current set by host, bit 2	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 200 mA of OTG current.
1	OTG Current set by host, bit 1	R/W	0b	0 = Adds 0 mA of OTG current. 1 = Adds 100 mA of OTG current.
0	OTG Current set by host, bit 0	R/W	Ob	0 = Adds 0 mA of OTG current. 1 = Adds 50 mA of OTG current. = 08h) Field Descriptions

#### Table 38. OTGCurrent Register (I2C address = 08h) Field Descriptions

I2C 08h	FIELD	ТҮРЕ	RESET	DESCRIPTION
7-0	Reserved	R/W	0000000b	Not used. Value Ignored.





## 8.6.9 ADCVBUS/PSYS Register (I2C address = 27h)

- PSYS: Full range: 3.06 V, LSB: 12 mV
- VBUS: Full range: 3200 mV to 19520 mV, LSB: 64 mV

#### Figure 40. ADCVBUS/PSYS Register (I2C address = 27h)

15	14	13	12	11	10	9	8
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 39. ADCVBUS/PSYS Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15-8		R		8-bit Digital Output of Input Voltage
7-0		R		8-bit Digital Output of System Power

## 8.6.10 ADCIBAT Register (I2C address = 29h)

- ICHG: Full range: 8.128 A, LSB 64: mA
- IDCHG: Full range: 32.512 A, LSB: 256 mA

### Figure 41. ADCIBAT Register (I2C address = 29h)

15	14	13	12	11	10	9	8
Reserved	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
Reserved	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 40. ADCIBAT Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15	Reserved	R		Not used. Value ignored.
14-8		R		7-bit Digital Output of Battery Charge Current
7	Reserved	R		Not used. Value ignored.
6-0		R		7-bit Digital Output of Battery Discharge Current

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### 8.6.11 ADCIINCMPIN Register (I2C address = 2Bh)

- IIN: Full range: 12.75 A, LSB: 50 mA
- CMPIN: Full range: 3.06 V, LSB: 12 mV

#### Figure 42. ADCIINCMPIN Register (I2C address = 2Bh)

15	14	13	12	11	10	9	8
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 41. ADCIINCMPIN Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15-8		R		8-bit Digital Output of Input Current
7-0		R		8-bit Digital Output of CMPIN voltage

## 8.6.12 ADCVSYSVBAT Register (I2C address = 2Dh) (reset = )

- VSYS: Full range: 2.88 V to 19.2 V, LSB: 64 mV
- VBAT: Full range: 2.88 V to 19.2 V, LSB: 64 mV

#### Figure 43. ADCVSYSVBAT Register (I2C address = 2Dh) (reset = )

15	14	13	12	11	10	9	8
R	R	R	R	R	R	R	R
7	6	5	4	3	2	1	0
R	R	R	R	R	R	R	R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 42. ADCVSYSVBAT Register Field Descriptions

BIT	FIELD	TYPE	RESET	DESCRIPTION
15-8		R		8-bit Digital Output of System Voltage
7-0		R		8-bit Digital Output of Battery Voltage



#### 8.6.13 ID Registers

#### 8.6.13.1 ManufactureID Register (I2C address = 2Eh) [reset = 0040h]

#### Figure 44. ManufactureID Register (I2C address = 2Eh) [reset = 0040h]

15-0
MANUFACTURE_ID
R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 43. ManufactureID Register Field Descriptions

l2C 2Eh	FIELD	ТҮРЕ	RESET	DESCRIPTION (READ ONLY)
7-0	MANUFACTURE_ID	R		40h

#### 8.6.13.2 Device ID (DeviceAddress) Register (I2C address = 2Fh) [reset = 0h]

#### Figure 45. Device ID (DeviceAddress) Register (I2C address = 2Fh) [reset = 0h]

15-8
Reserved
R
7-0
DEVICE_ID
R

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### Table 44. Device ID (DeviceAddress) Register Field Descriptions

I2C 2Fh	FIELD	TYPE	RESET	DESCRIPTION (READ ONLY)
15-8	Reserved	R	0b	Reserved
7-0	DEVICE_ID	R	0b	I2C:78h

## 9 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### 9.1 Application Information

The bq2570xEVM-732 evaluation module (EVM) is a complete charger module for evaluating the bq25703A. The application curves were taken using the bq2570xEVM-732. Refer to the EVM user's guide (SLUUBG6) for EVM information.

## 9.2 Typical Application

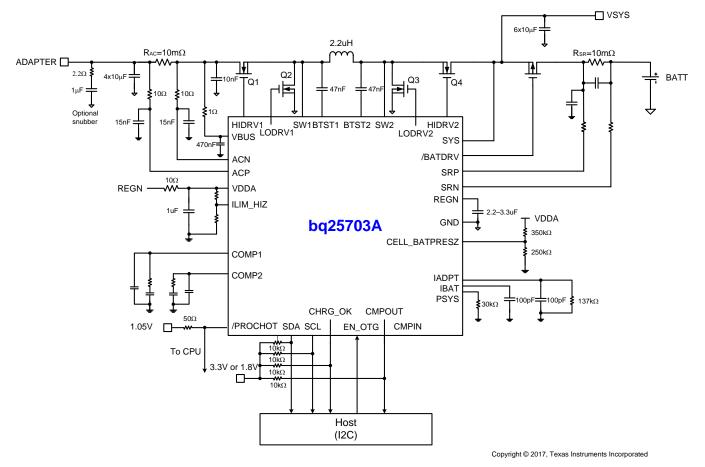


Figure 46. Application Diagram

#### 9.2.1 Design Requirements

DESIGN PARAMETER	EXAMPLE VALUE
Input Voltage <sup>(1)</sup>	3.5 V < Adapter Voltage < 24 V
Input Current Limit (1)	3.2 A for 65 W adapter
Battery Charge Voltage <sup>(2)</sup>	8400 mV for 2s battery

(1) Refer to adapter specification for settings for Input Voltage and Input Current Limit.

(2) Refer to battery specification for settings.

#### **Typical Application (continued)**

DESIGN PARAMETER	EXAMPLE VALUE				
Battery Charge Current <sup>(2)</sup>	3072 mA for 2s battery				
Minimum System Voltage <sup>(2)</sup>	614 mV for 2s battery				

#### 9.2.2 Detailed Design Procedure

The parameters are configurable using the evaluation software. The simplified application circuit (see Figure 46, as the application diagram) shows the minimum component requirements. Inductor, capacitor, and MOSFET selection are explained in the rest of this section. Refer to the EVM user's guide (SLUUBG6) for the complete application schematic.

#### 9.2.2.1 Input Snubber and Filter for Voltage Spike Damping

During adapter hot plug-in, the parasitic inductance and input capacitor from the adapter cable form a second order system. The voltage spike at VBUS pin maybe beyond IC maximum voltage rating and damage IC. The input filter must be carefully designed and tested to prevent over voltage event on VBUS pin.

There are several methods to damp or limit the over voltage spike during adapter hot plug-in. An electrolytic capacitor with high ESR as an input capacitor can damp the over voltage spike well below the IC maximum pin voltage rating. A high current capability TVS Zener diode can also limit the over voltage level to an IC safe level. However these two solutions may not have low cost or small size.

A cost effective and small size solution is shown in Figure 47. The R1 and C1 are composed of a damping RC network to damp the hot plug-in oscillation. As a result the over voltage spike is limited to a safe level. D1 is used for reverse voltage protection for VBUS pin. C2 is VBUS pin decoupling capacitor and it should be placed as close as possible to VBUS pin. C2 value should be less than C1 value so R1 can dominate the equivalent ESR value to get enough damping effect. R2 is used to limit inrush current of D1 to prevent D1 getting damage when adapter hot plug-in. R2 and C2 should have 10 µs time constant to limit the dv/dt on VBUS pin to reduce inrush current when adapter hot plug in. R1 has high inrush current. R1 package must be sized enough to handle inrush current power loss according to resistor manufacturer's data sheet. The filter components' value always need to be verified with real application and minor adjustments may need to fit in the real application circuit.

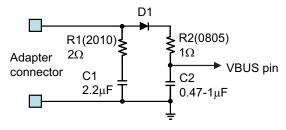


Figure 47. Input Filter

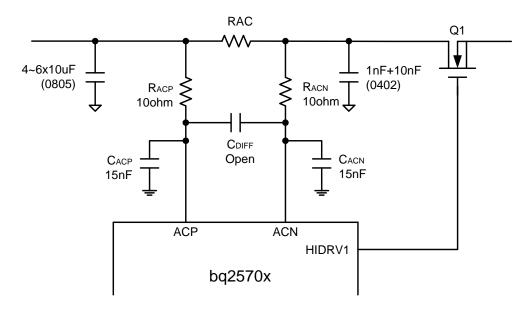
#### 9.2.2.2 ACP-ACN Input Filter

The bq25703A has average current mode control. The input current sensing through ACP/ACN is critical to recover inductor current ripple. Parasitic inductance on board will generate high frequency ringing on ACP-ACN which overwhelms converter sensed inductor current information, so it is difficult to manage parasitic inductance created based on different PCB layout. Bigger parasitic inductance will generate bigger sense current ringing which will cause the average current control loop to go into oscillation.

For real system board condition, we suggest to use below circuit design to get best result and filter noise induced from different PCB parasitic factor. With time constant of filter from 47 nsec to 200 nsec, the filtering on ringing is effective and in the meantime, the delay of on the sensed signal is small and therefore poses no concern for average current mode control.

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#### Figure 48. ACN-ACP Input Filter

#### 9.2.2.3 Inductor Selection

The bq25703A has two selectable fixed switching frequency. Higher switching frequency allows the use of smaller inductor and capacitor values. Inductor saturation current should be higher than the charging current ( $I_{CHG}$ ) plus half the ripple current ( $I_{RIPPLE}$ ):

$$I_{SAT} \geq I_{CHG} + (1/2) I_{RIPPLE}$$

(3)

(4)

The inductor ripple current in buck operation depends on input voltage ( $V_{IN}$ ), duty cycle ( $D_{BUCK} = V_{OUT}/V_{IN}$ ), switching frequency ( $f_S$ ) and inductance (L):

$$I_{\text{RIPPLE}\_\text{BUCK}} = \frac{V_{\text{IN}} \times \text{D} \times (1 - \text{D})}{f_{\text{S}} \times \text{L}}$$

During boost operation, the duty cycle is:

 $D_{BOOST} = 1 - (V_{IN}/V_{BAT})$ and the ripple current is:  $I_{RIPPLF, BOOST} = (VIN \times D_{BOOST}) / (f_S \times L)$ 

The maximum inductor ripple current happens with D = 0.5 or close to 0.5. For example, the battery charging voltage range is from 9 V to 12.6 V for 3-cell battery pack. For 20-V adapter voltage, 10-V battery voltage gives the maximum inductor ripple current. Another example is 4-cell battery, the battery voltage range is from 12 V to 16.8 V, and 12-V battery voltage gives the maximum inductor ripple current.

Usually inductor ripple is designed in the range of (20 - 40%) maximum charging current as a trade-off between inductor size and efficiency for a practical design.

#### 9.2.2.4 Input Capacitor

Input capacitor should have enough ripple current rating to absorb input switching ripple current. The worst case RMS ripple current is half of the charging current when duty cycle is 0.5 in buck mode. If the converter does not operate at 50% duty cycle, then the worst case capacitor RMS current occurs where the duty cycle is closest to 50% and can be estimated by Equation 5:

$$I_{CIN} = I_{CHG} \times \sqrt{D \times (1 - D)}$$

(5)



Low ESR ceramic capacitor such as X7R or X5R is preferred for input decoupling capacitor and should be placed to the drain of the high side MOSFET and source of the low side MOSFET as close as possible. Voltage rating of the capacitor must be higher than normal input voltage level. 25 V rating or higher capacitor is preferred for 19 V - 20 V input voltage. Minimum 4 - 6 pcs of  $10-\mu$ F 0805 size capacitor is suggested for 45 - 65 W adapter design.

Ceramic capacitors show a dc-bias effect. This effect reduces the effective capacitance when a dc-bias voltage is applied across a ceramic capacitor, as on the input capacitor of a charger. The effect may lead to a significant capacitance drop, especially for high input voltages and small capacitor packages. See the manufacturer's datasheet about the performance with a dc bias voltage applied. It may be necessary to choose a higher voltage rating or nominal capacitance value in order to get the required value at the operating point.

#### 9.2.2.5 Output Capacitor

Output capacitor also should have enough ripple current rating to absorb output switching ripple current. In buck mode the output capacitor RMS current is given:

To get good loop stability, the resonant frequency of the output inductor and output capacitor should be designed between 10 kHz and 20 kHz. The preferred ceramic capacitor is 25-V X7R or X5R for output capacitor. Minimum 6 pcs of 10- $\mu$ F 0805 size capacitor is suggested to be placed by the inductor. Place the capacitors after Q4 drain. Place minimum 10  $\mu$ F after the charge current sense resistor for best stability.

Ceramic capacitors show a dc-bias effect. This effect reduces the effective capacitance when a dc-bias voltage is applied across a ceramic capacitor, as on the output capacitor of a charger. The effect may lead to a significant capacitance drop, especially for high output voltages and small capacitor packages. See the manufacturer's data sheet about the performance with a dc bias voltage applied. It may be necessary to choose a higher voltage rating or nominal capacitance value in order to get the required value at the operating point.

#### 9.2.2.6 Power MOSFETs Selection

Four external N-channel MOSFETs are used for a synchronous switching battery charger. The gate drivers are internally integrated into the IC with 6 V of gate drive voltage. 30 V or higher voltage rating MOSFETs are preferred for 19 V - 20 V input voltage.

Figure-of-merit (FOM) is usually used for selecting proper MOSFET based on a tradeoff between the conduction loss and switching loss. For the top side MOSFET, FOM is defined as the product of a MOSFET's on-resistance,  $R_{DS(ON)}$ , and the gate-to-drain charge,  $Q_{GD}$ . For the bottom side MOSFET, FOM is defined as the product of the MOSFET's on-resistance,  $R_{DS(ON)}$ , and the total gate charge,  $Q_{G}$ .

$$FOM_{top} = R_{DS(on)} \times Q_{GD}; FOM_{bottom} = R_{DS(on)} \times Q_{G}$$
(6)

The lower the FOM value, the lower the total power loss. Usually lower  $R_{DS(ON)}$  has higher cost with the same package size.

The top-side MOSFET loss includes conduction loss and switching loss. It is a function of duty cycle  $(D=V_{OUT}/V_{IN})$ , charging current  $(I_{CHG})$ , MOSFET's on-resistance  $(R_{DS(ON)})$ , input voltage  $(V_{IN})$ , switching frequency  $(f_S)$ , turn on time  $(t_{on})$  and turn off time  $(t_{off})$ :

$$\mathsf{P}_{\mathsf{top}} = \mathsf{D} \times \mathsf{I}_{\mathsf{CHG}}^2 \times \mathsf{R}_{\mathsf{DS}(\mathsf{on})} + \frac{1}{2} \times \mathsf{V}_{\mathsf{IN}} \times \mathsf{I}_{\mathsf{CHG}} \times (\mathsf{t}_{\mathsf{on}} + \mathsf{t}_{\mathsf{off}}) \times f_{\mathsf{s}}$$
(7)

The first item represents the conduction loss. Usually MOSFET  $R_{DS(ON)}$  increases by 50% with 100°C junction temperature rise. The second term represents the switching loss. The MOSFET turn-on and turn-off times are given by:

$$t_{on} = \frac{Q_{SW}}{I_{on}}, \quad t_{off} = \frac{Q_{SW}}{I_{off}}$$
(8)

where  $Q_{sw}$  is the switching charge,  $I_{on}$  is the turn-on gate driving current and  $I_{off}$  is the turn-off gate driving current. If the switching charge is not given in MOSFET datasheet, it can be estimated by gate-to-drain charge ( $Q_{GD}$ ) and gate-to-source charge ( $Q_{GS}$ ):

$$Q_{SW} = Q_{GD} + \frac{1}{2} \times Q_{GS}$$
<sup>(9)</sup>

Gate driving current can be estimated by REGN voltage ( $V_{REGN}$ ), MOSFET plateau voltage ( $V_{plt}$ ), total turn-on gate resistance ( $R_{on}$ ) and turn-off gate resistance ( $R_{off}$ ) of the gate driver:

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(11)

$$I_{on} = \frac{V_{REGN} - V_{plt}}{R_{on}}, \quad I_{off} = \frac{V_{plt}}{R_{off}}$$
(10)

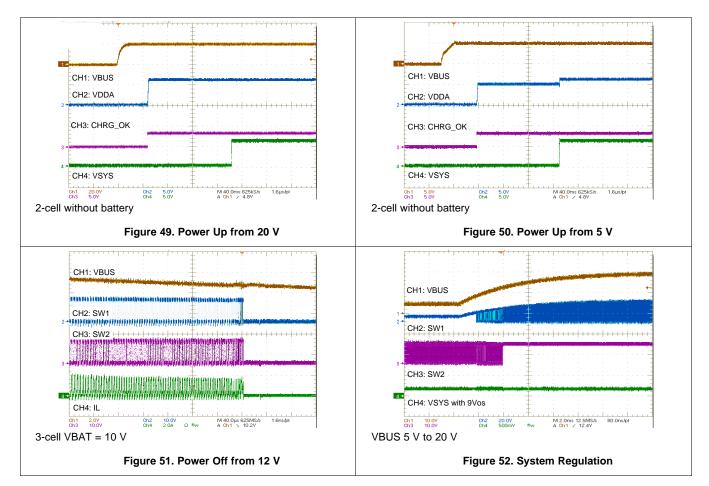
The conduction loss of the bottom-side MOSFET is calculated with the following equation when it operates in synchronous continuous conduction mode:

$$P_{bottom} = (1 - D) \times I_{CHG}^{2} \times R_{DS(on)}$$

When charger operates in non-synchronous mode, the bottom-side MOSFET is off. As a result all the freewheeling current goes through the body-diode of the bottom-side MOSFET. The body diode power loss depends on its forward voltage drop ( $V_F$ ), non-synchronous mode charging current ( $I_{NONSYNC}$ ), and duty cycle (D).

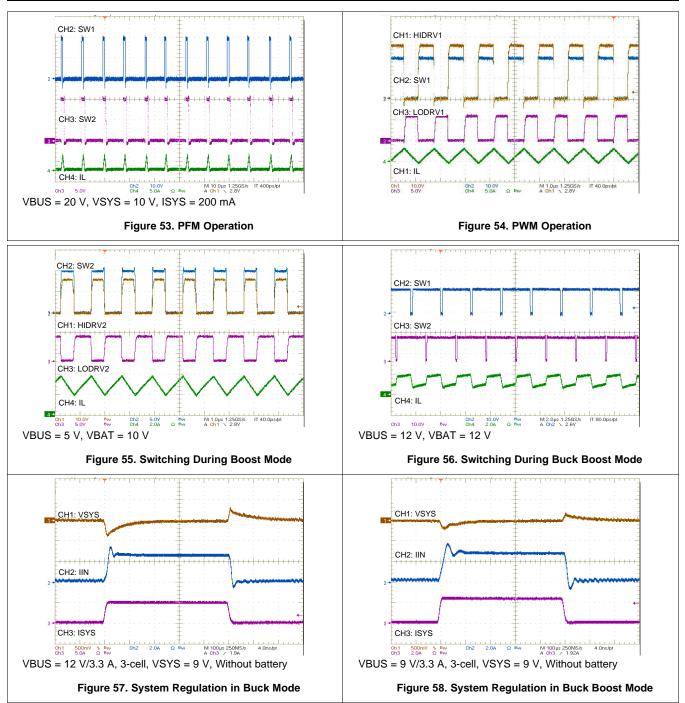
$$P_{\rm D} = V_{\rm F} \times I_{\rm NONSYNC} \times (1 - D) \tag{12}$$

The maximum charging current in non-synchronous mode can be up to 0.25 A for a  $10\text{-}m\Omega$  charging current sensing resistor or 0.5 A if battery voltage is below 2.5 V. The minimum duty cycle happens at lowest battery voltage. Choose the bottom-side MOSFET with either an internal Schottky or body diode capable of carrying the maximum non-synchronous mode charging current.



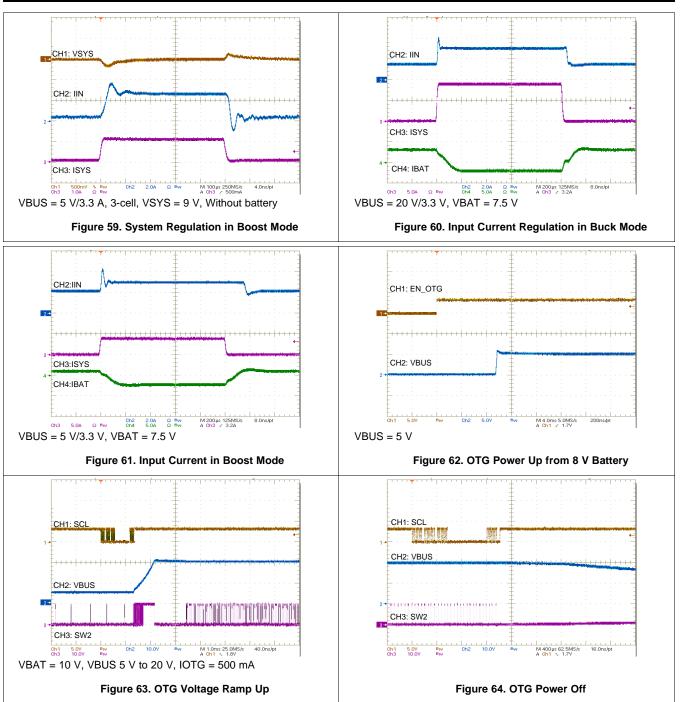
## 9.2.3 Application Curves



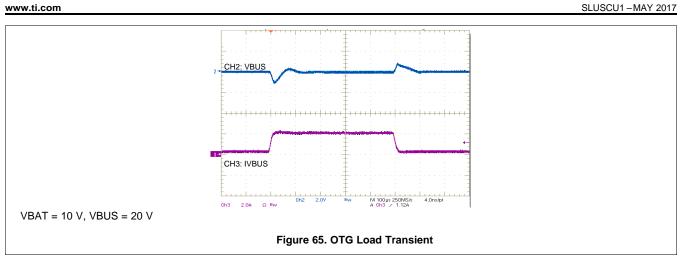


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# **10 Power Supply Recommendations**

The valid adapter range is from 3.5 V ( $V_{VBUS_CONVEN}$ ) to 24 V (ACOV) with at least 500-mA current rating. When CHRG\_OK goes HIGH, the system is powered from adapter through the charger. When adapter is removed, the system is connected to battery through BATFET. Typically the battery depletion threshold should be greater than the minimum system voltage so that the battery capacity can be fully utilized for maximum battery life.



## 11 Layout

#### 11.1 Layout Guidelines

The switching node rise and fall times should be minimized for minimum switching loss. Proper layout of the components to minimize high frequency current path loop (see *Layout Example* section) is important to prevent electrical and magnetic field radiation and high frequency resonant problems. Here is a PCB layout priority list for proper layout. Layout PCB according to this specific order is essential.

- 1. Place the input capacitor as close as possible to the supply of the switching MOSFET and ground connections. Use a short copper trace connection. These parts must be placed on the same layer of PCB using vias to make this connection.
- 2. The device must be placed close to the gate pins of the switching MOSFET. Keep the gate drive signal traces short for a clean MOSFET drive. The device can be placed on the other side of the PCB of switching MOSFETs.
- 3. Place an inductor input pin as close as possible to the output pin of the switching MOSFET. Minimize the copper area of this trace to lower electrical and magnetic field radiation but make the trace wide enough to carry the charging current. Do not use multiple layers in parallel for this connection. Minimize parasitic capacitance from this area to any other trace or plane.
- 4. The charging current sensing resistor should be placed right next to the inductor output. Route the sense leads connected across the sensing resistor back to the device in same layer, close to each other (minimize loop area) and do not route the sense leads through a high-current path (see Figure 67 for Kelvin connection for best current accuracy). Place a decoupling capacitor on these traces next to the device.
- 5. Place an output capacitor next to the sensing resistor output and ground.
- 6. Output capacitor ground connections must be tied to the same copper that connects to the input capacitor ground before connecting to system ground.
- 7. Use a single ground connection to tie the charger power ground to the charger analog ground. Just beneath the device, use analog ground copper pour but avoid power pins to reduce inductive and capacitive noise coupling.
- 8. Route analog ground separately from power ground. Connect analog ground and connect power ground separately. Connect analog ground and power ground together using power pad as the single ground connection point. Or using a  $0-\Omega$  resistor to tie analog ground to power ground (power pad should tie to analog ground in this case if possible).
- 9. Decoupling capacitors must be placed next to the device pins. Make trace connection as short as possible.
- 10. It is critical that the exposed power pad on the backside of the device package be soldered to the PCB ground.
- 11. The via size and number should be enough for a given current path. See the EVM design (SLUUBG6) for the recommended component placement with trace and via locations. For WQFN information, see SLUA271.

#### 11.2 Layout Example

#### 11.2.1 Layout Consideration of Current Path

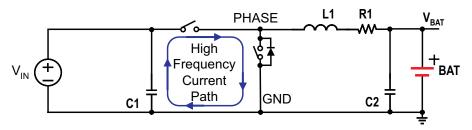


Figure 66. High Frequency Current Path

TEXAS INSTRUMENTS

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# Layout Example (continued)

# 11.2.2 Layout Consideration of Short Circuit Protection

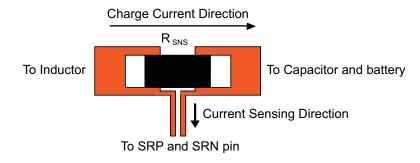


Figure 67. Sensing Resistor PCB Layout



# **12 Device and Documentation Support**

### 12.1 Device Support

#### 12.1.1 Third-Party Products Disclaimer

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#### **12.2 Documentation Support**

#### 12.2.1 Related Documentation

For related documentation see the following:

- Semiconductor and IC Package Thermal Metrics Application Report SPRA953
- bq2570x Evaluation Module User's Guide SLUUBG6
- QFN/SON PCB Attachment Application Report SLUA271

#### 12.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### **12.4 Community Resources**

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**Design Support TI's Design Support** Quickly find helpful E2E forums along with design support tools and contact information for technical support.

#### 12.5 Trademarks

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#### 12.6 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

# 12.7 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.



# 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



24-May-2017

# PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
BQ25703ARSNR	PREVIEW	QFN	RSN	32	3000	TBD	Call TI	Call TI	-40 to 85		
BQ25703ARSNT	PREVIEW	QFN	RSN	32	250	TBD	Call TI	Call TI	-40 to 85		

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

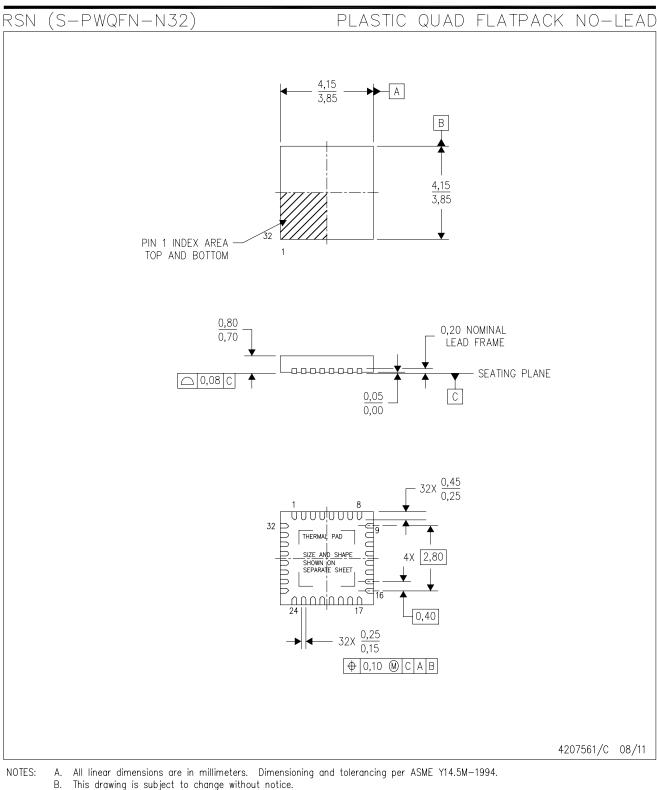
<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# **MECHANICAL DATA**



- C. QFN (Quad Flatpack No-Lead) Package configuration.
- D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.



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