

FSBF15CH60BT Motion SPM[®] 3 Series

Features

- UL Certified No. E209204
- 600 V 15 A 3 Phase IGBT Inverter Bridge Including Control ICs for Gate Driving And Protection
- Easy PCB Layout Thanks to Built In Bootstrap Diodes
- Three Separate Negative DC link Terminals for Inverter Current Sensing Applications
- Single Grounded Power Supply for Built In HVICs
- Isolation Rating of 2500 Vrms / min.

Applications

• Motion Control - Home Appliance / Industrial Motor

Related Resources

AN - 9044 Motion SPM® 3 Series Users Guide

April 2013

General Description

FSBF15CH60BT Is An Advacned Motion SPM 3 Series that Fairchild Has Newly Developed to Provide A Very Compact and High Performance Inverter Solution for AC Motor Drives in Low - Power Applications such as Air Conditioners and Washing Machines. It Combines Optimized Circuit Protections and Drives Matched to Low -Loss IGBTs. The System Reliability Is Further Enhanced by The Integrated Under - Voltage Lock - Out and Over -Current Protection. The High Speed Built - In HVIC Provides Optocoupler - Less Single - Supply IGBT Gate Driving Capability that Further Reduces The Overall Size of The Inverter System. Each Phase Leg Current of The Inverter Can Be Monitored Thanks to Three Separate Negative DC Terminals.

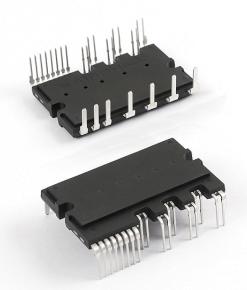


Figure 1. Package Overview

Package Marking and Ordering Information

Device Marking	Device	Package	Packing Type	Reel Size	Tape Width	Quantity
FSBF15CH60BT	FSBF15CH60BT	SPMJA - 027	RAIL	-	-	10

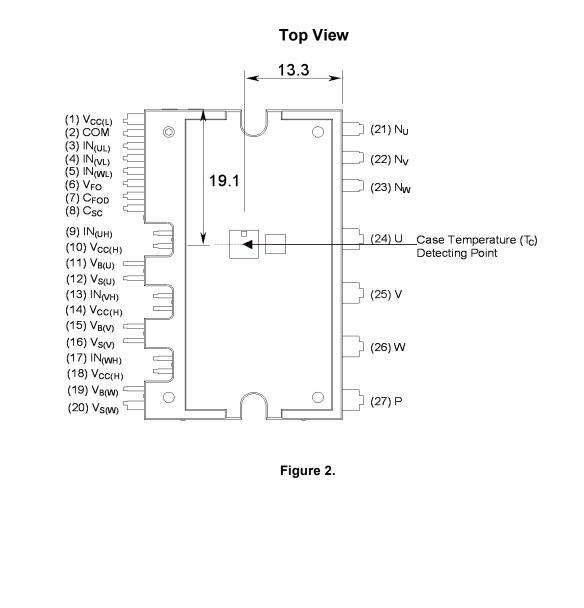
Integrated Power Functions

• 600 V - 15 A IGBT inverter for three - phase DC / AC power conversion (Please refer to Figure 3)

Integrated Drive, Protection and System Control Functions

- For inverter high side IGBTs: Gate drive circuit, High voltage isolated high speed level shifting
 Control circuit under voltage (UV) protection
 Note) Available bootstrap circuit example is given in Figures 12 and 13.
- For inverter low side IGBTs: Gate drive circuit, Short circuit protection (SC) Control supply circuit under - voltage (UV) protection
- Fault signaling: Corresponding to UV (low side supply) and SC faults
- Input interface: Active high interface, can work with 3.3 / 5 V logic

Pin Configuration



Pin Number	Pin Name	Pin Description
1	V _{CC(L)}	Low - Side Common Bias Voltage for IC and IGBTs Driving
2	СОМ	Common Supply Ground
3	IN _(UL)	Signal Input for Low - Side U Phase
4	IN _(VL)	Signal Input for Low - Side V Phase
5	IN _(WL)	Signal Input for Low - Side W Phase
6	V _{FO}	Fault Output
7	C _{FOD}	Capacitor for Fault Output Duration Time Selection
8	C _{SC}	Capacitor (Low - Pass Filter) for Short - Current Detection Input
9	IN _(UH)	Signal Input for High - Side U Phase
10	V _{CC(H)}	High - Side Common Bias Voltage for IC and IGBTs Driving
11	V _{B(U)}	High - Side Bias Voltage for U Phase IGBT Driving
12	V _{S(U)}	High - Side Bias Voltage Ground for U Phase IGBT Driving
13	IN _(VH)	Signal Input for High - Side V Phase
14	V _{CC(H)}	High - Side Common Bias Voltage for IC and IGBTs Driving
15	V _{B(V)}	High - Side Bias Voltage for V Phase IGBT Driving
16	V _{S(V)}	High - Side Bias Voltage Ground for V Phase IGBT Driving
17	IN _(WH)	Signal Input for High - Side W Phase
18	V _{CC(H)}	High - Side Common Bias Voltage for IC and IGBTs Driving
19	V _{B(W)}	High - Side Bias Voltage for W Phase IGBT Driving
20	V _{S(W)}	High - Side Bias Voltage Ground for W Phase IGBT Driving
21	NU	Negative DC - Link Input for U Phase
22	N _V	Negative DC - Link Input for V Phase
23	N _W	Negative DC - Link Input for W Phase
24	U	Output for U Phase
25	V	Output for V Phase
26	W	Output for W Phase
27	Р	Positive DC - Link Input

P (27) (19) \ VB (18) V_{CC} VCC OUT СОМ (17) IN_M W (26) VS IN (20) V_{S(W)} (15) V_{B(1} VB (14) V_c VCC OUT COM (13) IN_{(VF} vs IN V (25) (16) V_{S(V)} (11) V_B VB (10) V_{cci} vcc OUT СОМ (9) IN_{(UH} vs U (24), IN (12) V_{S(U)} (8) C_{SC} C(SC) OUT(WL) (7) C_{FOD} C(FOD) N_w (23) (6) V_{FC} VFO (5) IN(WL) IN(WL) OUT(VL) (4) IN_(VL) IN(VL) N_v (22) (3) IN_(UL) IN(UL) (2) COM сом OUT(UL) (1) V_{CC(L)} VCC V_{SL} N_U (21)

Note:

1. Inverter low - side is composed of three IGBTs, freewheeling diodes for each IGBT and one control IC. It has gate drive and protection functions.

2. Inverter power side is composed of four inverter dc - link input terminals and three inverter output terminals.

Internal Equivalent Circuit and Input/Output Pins

3. Inverter high - side is composed of three IGBTs, freewheeling diodes and three drive ICs for each IGBT.



Absolute Maximum Ratings (T_J = 25°C, Unless Otherwise Specified)

Inverter Part

Symbol	Parameter	Conditions	Rating	Unit
V _{PN}	Supply Voltage	Applied between P - N _U , N _V , N _W	450	V
V _{PN(Surge)}	Supply Voltage (Surge)	Applied between P - N_U , N_V , N_W	500	V
V _{CES}	Collector - Emitter Voltage		600	V
± I _C	Each IGBT Collector Current	$T_C = 25^{\circ}C, T_J \le 150^{\circ}C$	15	А
± I _{CP}	Each IGBT Collector Current (Peak)	T_{C} = 25°C, $T_{J} \leq$ 150°C, Under 1 ms Pulse Width	30	A
P _C	Collector Dissipation	T _C = 25°C per One Chip	25	W
TJ	Operating Junction Temperature	(Note 1)	- 40 ~ 150	°C

Note:

1. The maximum junction temperature rating of the power chips integrated within the Motion SPM 3 product is $150^{\circ}C$ (@T_C $\leq 125^{\circ}C$).

Control Part

Symbol	Parameter	Conditions	Rating	Unit
V _{CC}	Control Supply Voltage	Applied between V _{CC(H)} , V _{CC(L)} - COM	20	V
V_{BS}	High-side Control Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)},V_{B(V)}$ - $V_{S(V)},V_{B(W)}$ - $V_{S(W)}$	20	V
V _{IN}	Input Signal Voltage	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	- 0.3 ~ V _{CC} + 0.3	V
V _{FO}	Fault Output Supply Voltage	Applied between V _{FO} - COM	$-0.3 \sim V_{CC} + 0.3$	V
I _{FO}	Fault Output Current	Sink Current at V _{FO} pin	5	mA
V_{SC}	Current Sensing Input Voltage	Applied between C _{SC} - COM	$-0.3 \sim V_{CC} + 0.3$	V

Bootstrap Diode Part

Symbol	Parameter	Conditions	Rating	Unit
V _{RRM}	Maximum Repetitive Reverse Voltage		600	V
۱ _F	Forward Current	$T_C = 25^{\circ}C, \ T_J \leq 150^{\circ}C$	0.5	А
I _{FP}	Forward Current (Peak)	T_{C} = 25°C, T_{J} \leq 150°C, Under 1 ms Pulse Width	2.0	A
Τ _J	Operating Junction Temperature		- 40 ~ 150	°C

Total System

Symbol	Parameter	Conditions	Rating	Unit
V _{PN(PROT)}	Self Protection Supply Voltage Limit (Short Circuit Protection Capability)	V_{CC} = V _{BS} = 13.5 ~ 16.5 V, T _J = 150°C, Non - repetitive, less than 2 µs	400	V
T _C	Module Case Operation Temperature	- 40°C $\leq T_J \leq$ 150°C, See Figure 2	- 40 ~ 125	°C
T _{STG}	Storage Temperature		- 40 ~ 125	°C
V _{ISO}	Isolation Voltage	60 Hz, Sinusoidal, AC 1 minute, Connection pins to heat sink plate	2500	V _{rms}

Thermal Resistance

	Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
ſ	R _{th(j-c)Q}	Junction to Case Thermal Resistance	Inverter IGBT part (per 1 / 6 module)	-	-	4.9	°C / W
	R _{th(j-c)F}		Inverter FWD part (per 1 / 6 module)	-	-	5.7	°C / W

Note:

2. For the measurement point of case temperature (T_C), please refer to Figure 2.

Electrical Characteristics (T_J = 25°C, Unless Otherwise Specified)

Inverter Part

S	ymbol	Parameter	Condi	tions	Min.	Тур.	Max.	Unit
V	CE(SAT)	Collector - Emitter Saturation Voltage	V _{CC} = V _{BS} = 15 V V _{IN} = 5 V	I _C = 15 A, T _J = 25°C	-	-	2.2	V
	V _F	FWD Forward Voltage	V _{IN} = 0 V	I _F = 15 A, T _J = 25°C	-	-	2.5	V
HS	t _{ON}	Switching Times	V_{PN} = 300 V, V_{CC} = V_{B}	_S = 15 V	-	0.75	-	μs
	t _{C(ON)}		$I_{C} = 15 \text{ A}$ $V_{IN} = 0 \text{ V} \leftrightarrow 5 \text{ V}$, Induc	tive load	-	0.20	-	μS
	t _{OFF}		(Note 3) $($ Note 3)	live load	-	0.55	-	μS
	t _{C(OFF)}				-	0.10	-	μS
	t _{rr}				-	0.10	-	μS
LS	t _{ON}		V _{PN} = 300 V, V _{CC} = V _B	_S = 15 V	-	0.45	-	μS
	t _{C(ON)}		$I_{C} = 15 \text{ A}$ $V_{IN} = 0 \text{ V} \leftrightarrow 5 \text{ V}$, Induc	tive load	-	0.25	-	μS
	t _{OFF}		(Note 3)		-	0.55	-	μS
	t _{C(OFF)}				-	0.10	-	μS
	t _{rr}				-	0.10	-	μS
	I _{CES}	Collector - Emitter Leakage Current	V _{CE} = V _{CES}		-	-	1	mA

Note:

3. t_{ON} and t_{DFF} include the propagation delay time of the internal drive IC. t_{C(ON)} and t_{C(OFF)} are the switching time of IGBT itself under the given gate driving condition internally. For the detailed information, please see Figure 4.

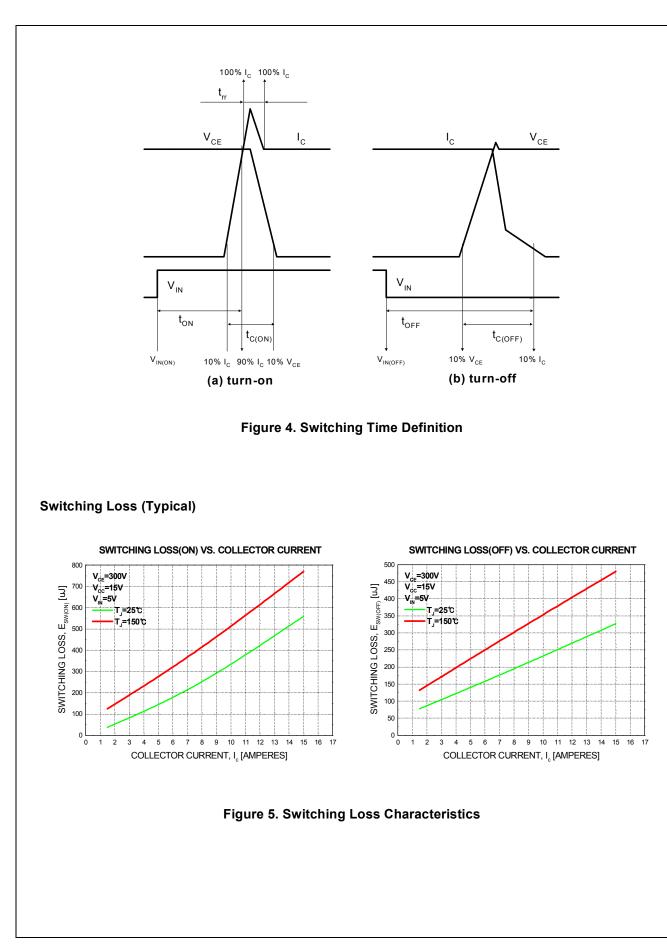
Control Part

Symbol	Parameter	Co	nditions	Min.	Тур.	Max.	Unit
IQCCL	Quiescent V _{CC} Supply Current	V _{CC} = 15 V IN _(UL, VL, WL) = 0 V	V _{CC(L)} - COM	-	-	23	mA
IQCCH	*	V _{CC} = 15 V IN _(UH, VH, WH) = 0 V	V _{CC(H)} - COM	-	-	600	μA
I _{QBS}	Quiescent V _{BS} Supply Current	V _{BS} = 15 V IN _(UH, VH, WH) = 0 V		-	-	500	μA
V _{FOH}	Fault Output Voltage	V _{SC} = 0 V, V _{FO} Circu	iit: 4.7 kΩ to 5 V Pull - up	4.5	-	-	V
V _{FOL}		V _{SC} = 1 V, V _{FO} Circu	iit: 4.7 k Ω to 5 V Pull - up	-	-	0.8	V
V _{SC(ref)}	Short Circuit Trip Level	V _{CC} = 15 V (Note 4)		0.45	0.5	0.55	V
TSD	Over - Temperature Protec- tion	Temperature at LVIC	;	-	160	-	°C
∆TSD	Over - Temperature Protec- tion Hysterisis	Temperature at LVIC	;	-	5	-	°C
UV _{CCD}	Supply Circuit Under -	Detection Level		10.7	11.9	13.0	V
UV _{CCR}	Voltage Protection	Reset Level		11.2	12.4	13.4	V
UV _{BSD}		Detection Level		10	11	12	V
UV _{BSR}	1	Reset Level		10.5	11.5	12.5	V
t _{FOD}	Fault - Out Pulse Width	C _{FOD} = 33 nF (Note	5)	1.0	1.8	-	ms
V _{IN(ON)}	ON Threshold Voltage		_(UH) , IN _(VH) , IN _(WH) , IN _(UL) ,	2.8	-	-	V
V _{IN(OFF)}	OFF Threshold Voltage	$IN_{(VL)}$, $IN_{(WL)}$ - COM	, . ,	-	-	0.8	V

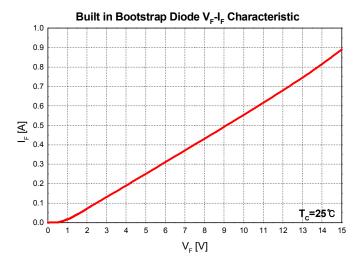
Note:

4. Short - circuit current protection is functioning only at the low - sides.

5. The fault - out pulse width t_{FOD} depends on the capacitance value of C_{FOD} according to the following approximate equation: C_{FOD} = 18.3 x 10⁶ x t_{FOD} [F]



Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V _F	Forward Voltage	I _F = 0.1 A, T _C = 25°C	-	2.5	-	V
t _{rr}	Reverse Recovery Time	I _F = 0.1 A, T _C = 25°C	-	80	-	ns



Note:

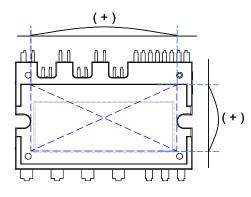
6. Built in bootstrap diode includes around 15 Ω resistance characteristic.



Recommended Operating Conditions

Symbol	Parameter	Conditions		Value		Unit
Symbol	Faranieler	Conditions	Min.	Тур.	Max.	Unit
V _{PN}	Supply Voltage	Applied between P - N _U , N _V , N _W	-	300	400	V
V _{CC}	Control Supply Voltage	Applied between V _{CC(H)} , V _{CC(L)} - COM	13.5	15	16.5	V
V _{BS}	High - Side Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)}, ~V_{B(V)}$ - $V_{S(V)}, ~V_{B(W)}$ - $V_{S(W)}$	13.0	15	18.5	V
dV _{CC} / dt, dV _{BS} / dt	Control Supply Variation		- 1	-	1	V / μs
t _{dead}	Blanking Time for Preventing Arm - Short	For Each Input Signal	1.5	-	-	μS
f _{PWM}	PWM Input Signal	- 40°C \leq $T_C \leq$ 125°C, - 40°C \leq $T_J \leq$ 150°C	-	-	20	kHz
V _{SEN}	Voltage for Current Sensing	Applied between N _U , N _V , N _W - COM (Including surge voltage)	- 4		4	V

Parameter		Conditions			Limits			
Falametei		onutions	Min.	Тур.	Max.	Unit		
Mounting Torque	Mounting Screw: M3	Recommended 0.62 N • m	0.51	0.62	1.00	N۰m		
Device Flatness		Note Figure 7	0	-	+ 120	μm		
Weight			-	15.4	-	g		





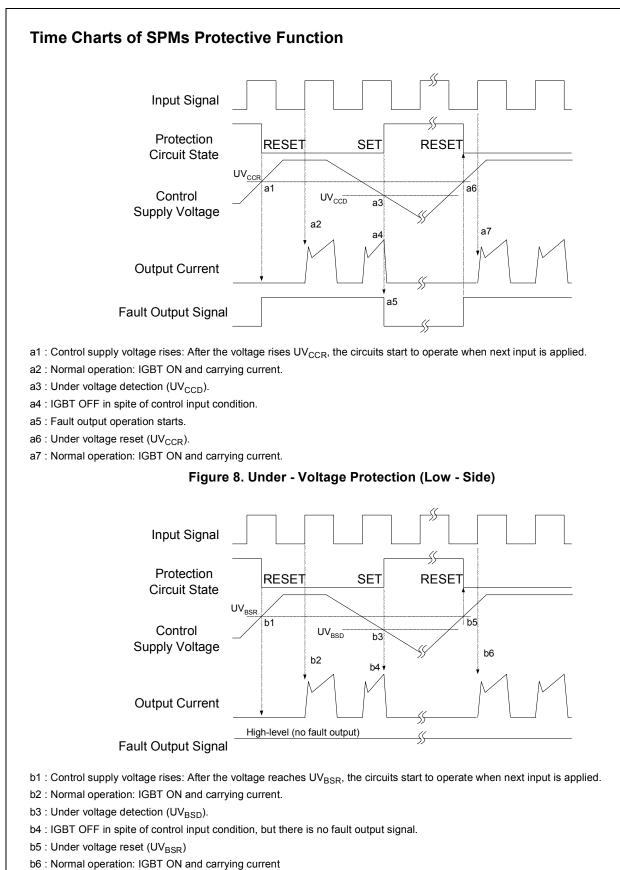
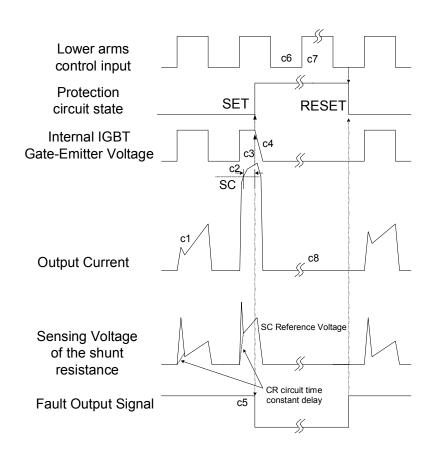


Figure 9. Under - Voltage Protection (High - Side)



(with the external shunt resistance and CR connection)

c1 : Normal operation: IGBT ON and carrying current.

c2 : Short circuit current detection (SC trigger).

c3 : Hard IGBT gate interrupt.

c4 : IGBT turns OFF.

c5 : Fault output timer operation starts: The pulse width of the fault output signal is set by the external capacitor C_{FO} .

c6 : Input "L" : IGBT OFF state.

c7 : Input "H": IGBT ON state, but during the active period of fault output the IGBT doesn't turn ON.

c8 : IGBT OFF state

Figure 10. Short - Circuit Current Protection (Low - Side Operation only)

FSBF15CH60BT Motion SPM® 3 Series

SPM

 $\mathrm{IN}_{(\mathrm{UH})}, \ \mathrm{IN}_{(\mathrm{VH})}, \ \mathrm{IN}_{(\mathrm{WH})}$

 $IN_{(UL)}$, $IN_{(VL)}$, $IN_{(WL)}$

 $V_{\rm FO}$

COM



1) RC coupling at each input might change depending on the PWM control scheme used in the application and the wiring impedance of the application's printed circuit board. The input signal section of the Motion SPM 3 product integrates 5 kΩ (typ.) pull - down resistor. Therefore, when using an external filtering resistor, please pay attention to the signal voltage drop at input terminal.

1nF=

1nF÷

5V-Line

R_{PF}=4.7kΩ

 $C_{PF} = 1nF$

100Ω

100Ω

 \mathbb{N}

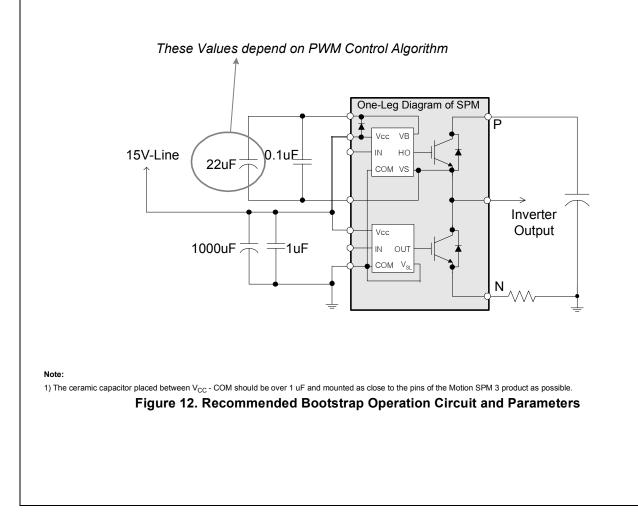
100Ω

1nF

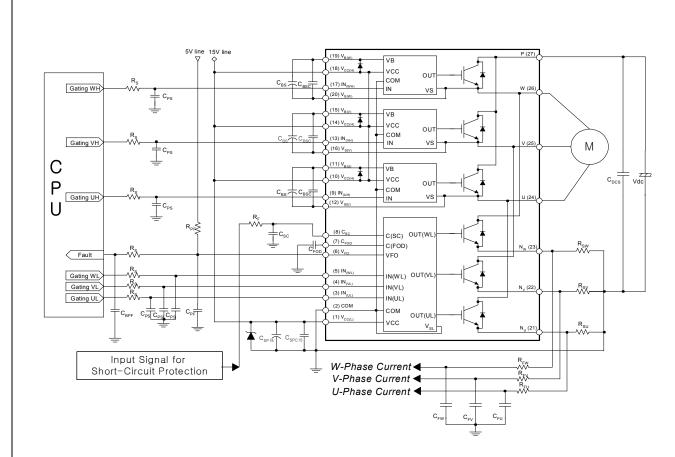
2) The logic input is compatible with standard CMOS or LSTTL outputs.

CPU

Figure 11. Recommended CPU I/O Interface Circuit



FSBF15CH60BT Motion SPM® 3 Series



Note:

1) To avoid malfunction, the wiring of each input should be as short as possible. (less than 2 - 3cm)

2) By virtue of integrating an application specific type HVIC inside the Motion SPM 3 product, direct coupling to CPU terminals without any opto - coupler or transformer isolation is possible.

3) V_{FO} output is open collector type. This signal line should be pulled up to the positive side of the 5V power supply with approximately 4.7 k Ω resistance. Please refer to Figure 11. 4) C_{SP15} of around 7 times larger than bootstrap capacitor C_{BS} is recommended.

5) V_{FO} output pulse width should be determined by connecting an external capacitor (C_{FOD}) between C_{FOD} (pin7) and COM (pin2). (Example: if C_{FOD} = 33 nF, then t_{FO} = 1.8 ms (typ.)) Please refer to the note 5 for calculation method.

6) Input signal is High - Active type. There is a 5 kΩ resistor inside the IC to pull down each input signal line to GND. RC coupling circuits should be adopted for the prevention of input signal oscillation. R_SC_{PS} time constant should be selected in the range 50 ~ 150 ns. C_{PS} should not be less than 1 nF.(Recommended R_S = 100 Ω, C_{PS} = 1 nF)

7) To prevent errors of the protection function, the wiring around R_F and C_{SC} should be as short as possible.

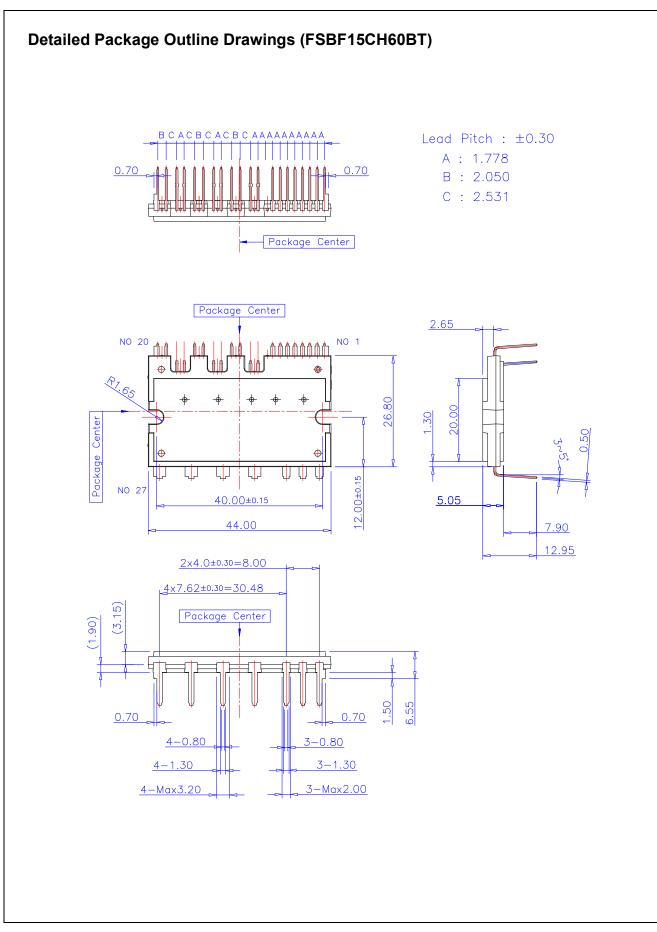
8) In the short - circuit protection circuit, please select the R_FC_{SC} time constant in the range 1.5 ~ 2 μ s.

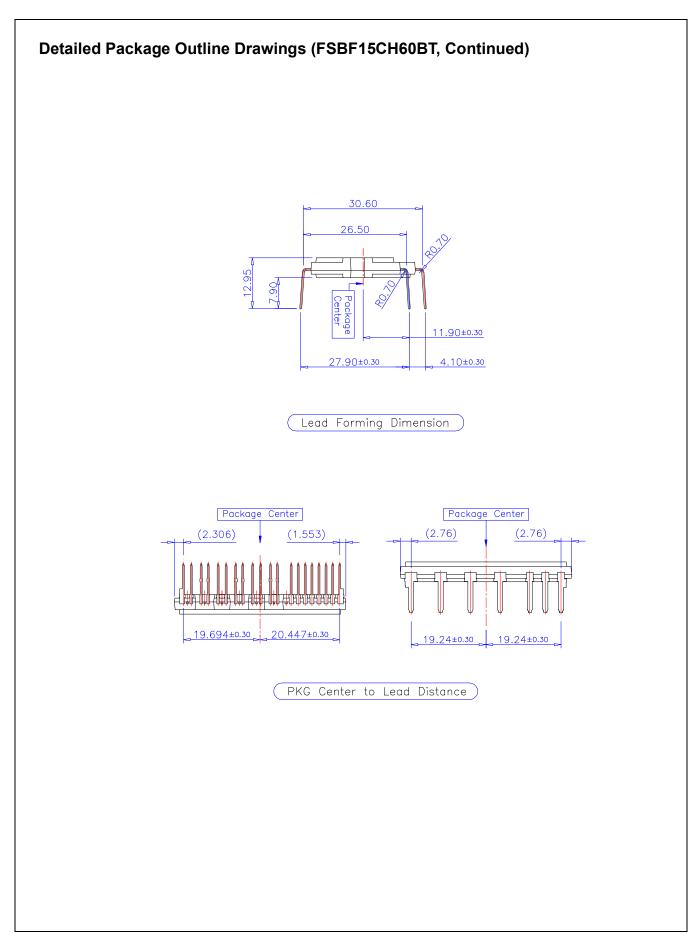
9) Each capacitor should be mounted as close to the pins of the Motion SPM 3 product as possible.

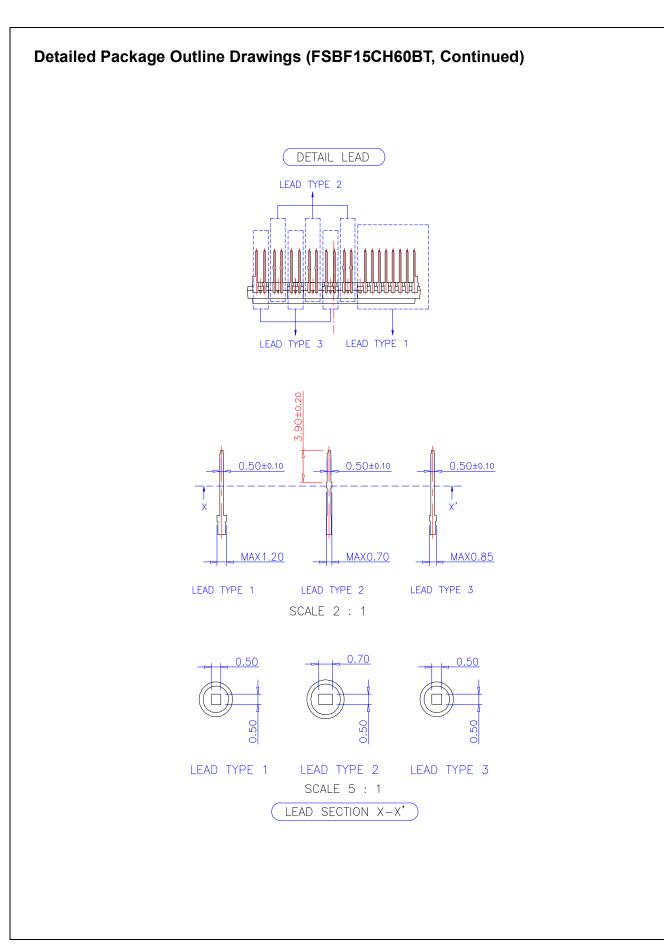
10) To prevent surge destruction, the wiring between the smoothing capacitor and the P & GND pins should be as short as possible. The use of a high frequency non - inductive capacitor of around 0.1 ~ 0.22µF between the P & GND pins is recommended.

11) Relays are used at almost every systems of electrical equipments of home appliances. In these cases, there should be sufficient distance between the CPU and the relays.
 12) C_{SPC15} should be over 1 µF and mounted as close to the pins of the Motion SPM 3 product as possible.

Figure 13. Typical Application Circuit







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Definition	of lerms

Datasheet Identification	Product Status	Definition
Advance Information	Formative / In Design	Datasheet contains the design specifications for product development. Specifications may change in any manner without notice.
Preliminary	First Production	Datasheet contains preliminary data; supplementary data will be published at a later date. Fairchild Semiconductor reserves the right to make changes at any time without notice to improve design.
No Identification Needed	Full Production	Datasheet contains final specifications. Fairchild Semiconductor reserves the right to make changes at any time without notice to improve the design.
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