

8-bit Atmel tinyAVR Microcontroller with 16K Bytes In-System Programmable Flash

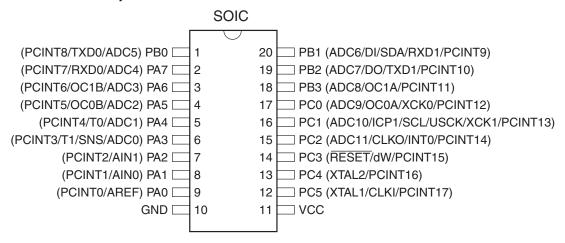
ATtiny1634 **DATASHEET SUMMARY**

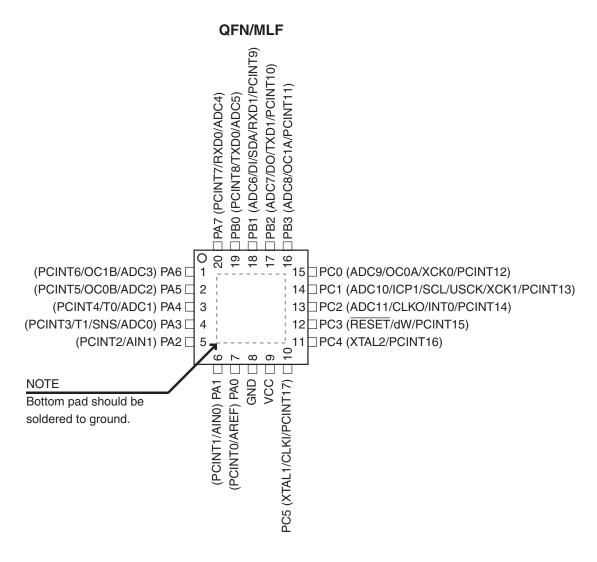
Features

- High Performance, Low Power AVR® 8-bit Microcontroller
- **Advanced RISC Architecture**
 - 125 Powerful Instructions Most Single Clock Cycle Execution
 - 32 x 8 General Purpose Working Registers
 - Fully Static Operation
- High Endurance, Non-volatile Memory Segments
 - 16K Bytes of In-System, Self-Programmable Flash Program Memory
 - Endurance: 10,000 Write/Erase Cycles
 - 256 Bytes of In-System Programmable EEPROM
 - Endurance: 100,000 Write/Erase Cycles
 - 1K Byte of Internal SRAM
 - Data retention: 20 years at 85°C / 100 years at 25°C
 - Programming Lock for Self-Programming Flash & EEPROM Data Security
- · Peripheral Features
 - Dedicated Hardware and QTouch® Library Support for Capacitive Touch Sensing
 - One 8-bit and One 16-bit Timer/Counter with Two PWM Channels, Each
 - 12-channel, 10-bit ADC
 - Programmable Ultra Low Power Watchdog Timer
 - On-chip Analog Comparator
 - Two Full Duplex USARTs with Start Frame Detection
 - Universal Serial Interface
 - Slave I²C Serial Interface
- Special Microcontroller Features
 - debugWIRE On-chip Debug System
 - In-System Programmable via SPI Port
 - Internal and External Interrupt Sources • Pin Change Interrupt on 18 Pins
 - Low Power Idle, ADC Noise Reduction, Standby and Power-down Modes
 - Enhanced Power-on Reset Circuit
 - Programmable Brown-out Detection Circuit with Supply Voltage Sampling
 - Calibrated 8MHz Oscillator with Temperature Calibration Option
 - Calibrated 32kHz Ultra Low Power Oscillator
 - On-chip Temperature Sensor
- I/O and Packages
 - 18 Programmable I/O Lines
 - 20-pad QFN/MLF, and 20-pin SOIC
- Operating Voltage:
 - 1.8 5.5V
- Speed Grade:
 - 0 2MHz @ 1.8 5.5V
 - -0-8MHz @ 2.7-5.5V
 - 0 12MHz @ 4.5 5.5V
- Temperature Range: -40°C to +85°C
- **Low Power Consumption**
 - Active Mode: 0.2mA at 1.8V and 1MHz
 - Idle Mode: 30µA at 1.8V and 1MHz
 - Power-Down Mode (WDT Enabled): 1µA at 1.8V
 - Power-Down Mode (WDT Disabled): 100nA at 1.8V

1. Pin Configurations

Figure 1-1. Pinout of ATtiny1634







1.1 Pin Descriptions

1.1.1 VCC

Supply voltage.

1.1.2 GND

Ground.

1.1.3 XTAL1

Input to the inverting amplifier of the oscillator and the internal clock circuit. This is an alternative pin configuration of PC5.

1.1.4 XTAL2

Output from the inverting amplifier of the oscillator. Alternative pin configuration of PC4.

1.1.5 RESET

Reset input. A low level on this pin for longer than the minimum pulse length will generate a reset, even if the clock is not running and provided the reset pin has not been disabled. The minimum pulse length is given in Table 24-5 on page 231. Shorter pulses are not guaranteed to generate a reset.

The reset pin can also be used as a (weak) I/O pin.

1.1.6 Port A (PA7:PA0)

This is an 8-bit, bi-directional I/O port with internal pull-up resistors (selected for each bit). Output buffers have the following drive characteristics:

- PA7, PA4:PA0: Symmetrical, with standard sink and source capability
- PA6, PA5: Asymmetrical, with high sink and standard source capability

As inputs, port pins that are externally pulled low will source current provided that pull-up resistors are activated. Port pins are tri-stated when a reset condition becomes active, even if the clock is not running.

This port has alternate pin functions to serve special features of the device. See "Alternate Functions of Port A" on page 62.

1.1.7 Port B (PB3:PB0)

This is a 4-bit, bi-directional I/O port with internal pull-up resistors (selected for each bit). Output buffers have the following drive characteristics:

- PB3: Asymmetrical, with high sink and standard source capability
- PB2:PB0: Symmetrical, with standard sink and source capability

As inputs, port pins that are externally pulled low will source current provided that pull-up resistors are activated. Port pins are tri-stated when a reset condition becomes active, even if the clock is not running.

This port has alternate pin functions to serve special features of the device. See "Alternate Functions of Port B" on page 65.

1.1.8 Port C (PC5:PC0)

This is a 6-bit, bi-directional I/O port with internal pull-up resistors (selected for each bit). Output buffers have the following drive characteristics:



- PC5:PC1: Symmetrical, with standard sink and source capability
- PC0: Asymmetrical, with high sink and standard source capability

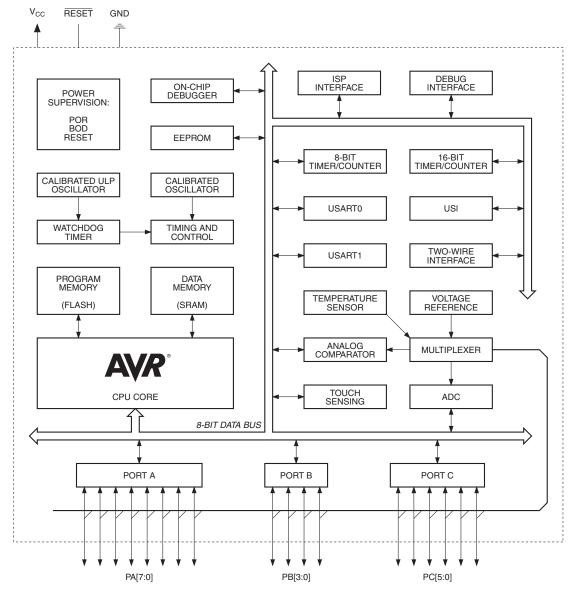
As inputs, port pins that are externally pulled low will source current provided that pull-up resistors are activated. Port pins are tri-stated when a reset condition becomes active, even if the clock is not running.

This port has alternate pin functions to serve special features of the device. See "Alternate Functions of Port C" on page 67.

2. Overview

ATtiny1634 is a low-power CMOS 8-bit microcontrollers based on the AVR enhanced RISC architecture. By executing powerful instructions in a single clock cycle, the ATtiny1634 achieves throughputs approaching 1 MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

Figure 2-1. Block Diagram





The AVR core combines a rich instruction set with 32 general purpose working registers. All 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in a single instruction, executed in one clock cycle. The resulting architecture is compact and code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

ATtiny1634 provides the following features:

- 16K bytes of in-system programmable Flash
- 1K bytes of SRAM data memory
- 256 bytes of EEPROM data memory
- 18 general purpose I/O lines
- 32 general purpose working registers
- An 8-bit timer/counter with two PWM channels
- A16-bit timer/counter with two PWM channels
- · Internal and external interrupts
- A 10-bit ADC with 5 internal and 12 external channels
- An ultra-low power, programmable watchdog timer with internal oscillator
- Two programmable USART's with start frame detection
- A slave Two-Wire Interface (TWI)
- · A Universal Serial Interface (USI) with start condition detector
- A calibrated 8MHz oscillator
- A calibrated 32kHz, ultra low power oscillator
- Four software selectable power saving modes.

The device includes the following modes for saving power:

- Idle mode: stops the CPU while allowing the timer/counter, ADC, analog comparator, SPI, TWI, and interrupt system to continue functioning
- ADC Noise Reduction mode: minimizes switching noise during ADC conversions by stopping the CPU and all I/O modules except the ADC
- Power-down mode: registers keep their contents and all chip functions are disabled until the next interrupt or hardware reset
- Standby mode: the oscillator is running while the rest of the device is sleeping, allowing very fast start-up combined with low power consumption.

The device is manufactured using Atmel's high density non-volatile memory technology. The Flash program memory can be re-programmed in-system through a serial interface, by a conventional non-volatile memory programmer or by an on-chip boot code, running on the AVR core.

The ATtiny1634 AVR is supported by a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators and evaluation kits.



3. General Information

3.1 Resources

A comprehensive set of drivers, application notes, data sheets and descriptions on development tools are available for download at http://www.atmel.com/avr.

3.2 Code Examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C compiler documentation for more details.

For I/O Registers located in the extended I/O map, "IN", "OUT", "SBIS", "SBIC", "CBI", and "SBI" instructions must be replaced with instructions that allow access to extended I/O. Typically, this means "LDS" and "STS" combined with "SBRS", "SBRC", "SBR", and "CBR". Note that not all AVR devices include an extended I/O map.

3.3 Capacitive Touch Sensing

Atmel QTouch Library provides a simple to use solution for touch sensitive interfaces on Atmel AVR microcontrollers. The QTouch Library includes support for QTouch[®] and QMatrix[®] acquisition methods.

Touch sensing is easily added to any application by linking the QTouch Library and using the Application Programming Interface (API) of the library to define the touch channels and sensors. The application then calls the API to retrieve channel information and determine the state of the touch sensor.

The QTouch Library is free and can be downloaded from the Atmel website. For more information and details of implementation, refer to the QTouch Library User Guide – also available from the Atmel website.

3.4 Data Retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C or 100 years at 25°C.

4. CPU Core

This section discusses the AVR core architecture in general. The main function of the CPU core is to ensure correct program execution. The CPU must therefore be able to access memories, perform calculations, control peripherals, and handle interrupts.



5. Register Summary

Disparage Control Co	127 127 127 128 130 130 130
CodPD Reserved	127 127 128 130 130 130
(0xFC) Reserved	127 127 128 130 130 130
(0xFg)	127 127 128 130 130 130
(0)(FA) Reserved	127 127 128 130 130 130
(0xF9)	127 127 128 130 130 130
(0x84) Reserved - - - - - - - - -	127 127 128 130 130 130
(0x85)	127 127 128 130 130 130
(0x84) Reserved	127 128 130 130 130
(0x82) Reserved -	127 128 130 130 130
(0x82) Reserved	127 128 130 130 130
(0x7E) TWSCRA TWSHE - TWDIE TWASIE TWEN TWSME TWSME TWSKE	127 128 130 130 130
(0x7F)	127 128 130 130 130
(0x7E)	127 128 130 130 130
(0x7D) TWSSRA TWDIF TWASIF TWCH TWRA TWC TWBE TWDIR TWAS (0x7C) TWSA TWSA TWI Slave Address Register TWI Slave Address Register (0x7A) TWSAM TWI Slave Address Register TWI Slave Address Mask Register TWI Slave Data Register TWI Slave Slave TWI Slave Data Register Slave TWI Sla	128 130 130 130
(0x7C) TWSA	130 130 130
(0x7B) TWSAM	130 130
(0x7A)	130
(0x79)	
(0x78)	107
(0x77)	168
(0x76)	169
USART1 Baud Rate Register High Byte	171
USART1 Baud Rate Register Low Byte	172
(0x72) TCCR1A COM1A1 COM1A0 COM1B1 COM1B0 -	172
(0x71) TCCR1B ICNC1 ICES1 - WGM13 WGM12 CS12 CS11 CS10	167
(0x70) TCCR1C FOC1A FOC1B - - - - - -	111
(0x6F) TCNT1H Timer/Counter1 - Counter Register High Byte (0x6E) TCNT1L Timer/Counter1 - Counter Register Low Byte (0x6D) OCR1AH Timer/Counter1 - Compare Register A High Byte (0x6C) OCR1AL Timer/Counter1 - Compare Register A Low Byte (0x6B) OCR1BH Timer/Counter1 - Compare Register A Low Byte (0x6B) OCR1BH Timer/Counter1 - Compare Register B High Byte (0x6A) OCR1BL Timer/Counter1 - Compare Register B Low Byte (0x69) ICR1H Timer/Counter1 - Input Capture Register B Low Byte (0x68) ICR1L Timer/Counter1 - Input Capture Register Low Byte (0x67) GTCCR TSM -	113
Timer/Counter1 - Counter Register Low Byte	114
Ox6D OCR1AH	114
Ox6C OCR1AL Timer/Counter1 - Compare Register A Low Byte	114
Ox6B OCR1BH Timer/Counter1 - Compare Register B High Byte Ox6A OCR1BL Timer/Counter1 - Compare Register B Low Byte Ox6B ICR1H Timer/Counter1 - Input Capture Register High Byte Ox6B ICR1L Timer/Counter1 - Input Capture Register Low Byte Ox6B ICR1L Timer/Counter1 - Input Capture Register Low Byte Ox6B Ox6CAL1 Ox6B OXCCAL1 OXCCAL2 OXCCAL3 O	114
Commonwealth Comm	114 115
Combination Composition	115
Combination Composition	115
(0x67) GTCCR TSM - - - - - - PSR10 (0x66) OSCCAL1 - - - - - - CAL11 CAL10 (0x65) OSCTCAL0B OSCIIlator Temperature Compensation Register B OSCIII Temperature Compensation Register A OSCIII CAL0A OSCIII CAL0A CAL03 CAL02 CAL01 CAL00 (0x63) OSCCAL0 CAL07 CAL06 CAL05 CAL04 CAL03 CAL02 CAL01 CAL00 (0x62) DIDR2 - - - - ADC11D ADC10D ADC9D (0x61) DIDR1 - - - - ADC8D ADC7D ADC6D ADC5D (0x60) DIDR0 ADC4D ADC3D ADC2D ADC1D ADC0D AIN1D AIN0D AREFD 0x3F (0x5F) SREG I T H S V N Z C 0x3E (0x5E) SPH - <td>115</td>	115
(0x65) OSCTCAL0B Oscillator Temperature Compensation Register B (0x64) OSCTCAL0A OSCIDATOR (0x63) OSCCAL0 CAL07 CAL06 CAL05 CAL04 CAL03 CAL02 CAL01 CAL00 (0x62) DIDR2 - - - - ADC11D ADC10D ADC9D (0x61) DIDR1 - - - ADC8D ADC7D ADC6D ADC5D (0x60) DIDR0 ADC4D ADC3D ADC2D ADC1D ADC0D AIN1D AIN0D AREFD 0x3F (0x5F) SREG I T H S V N Z C 0x3E (0x5E) SPH - - - - - SP10 SP9 SP8	118
(0x64) OSCTCALOA Oscillator Temperature Compensation Register A (0x63) OSCCALO CAL07 CAL06 CAL05 CAL04 CAL03 CAL02 CAL01 CAL00 (0x62) DIDR2 - - - - - ADC11D ADC10D ADC9D (0x61) DIDR1 - - - - ADC8D ADC7D ADC6D ADC5D (0x60) DIDR0 ADC4D ADC3D ADC2D ADC1D ADC0D AIN1D AIN0D AREFD 0x3F (0x5F) SREG I T H S V N Z C 0x3E (0x5E) SPH - - - - - SP10 SP9 SP8	33
(0x63) OSCCAL0 CAL07 CAL06 CAL05 CAL04 CAL03 CAL02 CAL01 CAL00 (0x62) DIDR2 - - - - - ADC11D ADC10D ADC9D (0x61) DIDR1 - - - - ADC8D ADC7D ADC6D ADC5D (0x60) DIDR0 ADC4D ADC3D ADC2D ADC1D ADC0D AIN1D AIN0D AREFD 0x3F (0x5F) SREG I T H S V N Z C 0x3E (0x5E) SPH - - - - - SP10 SP9 SP8	33
(0x62) DIDR2 - - - - - - ADC10D ADC9D (0x61) DIDR1 - - - - - ADC8D ADC7D ADC6D ADC5D (0x60) DIDR0 ADC4D ADC3D ADC2D ADC1D ADC0D AIN1D AIN0D AREFD 0x3F (0x5F) SREG I T H S V N Z C 0x3E (0x5E) SPH - - - - SP10 SP9 SP8	33
(0x61) DIDR1 - - - - - ADC8D ADC7D ADC6D ADC5D (0x60) DIDR0 ADC4D ADC3D ADC2D ADC1D ADC0D AIN1D AIN0D AREFD 0x3F (0x5F) SREG I T H S V N Z C 0x3E (0x5E) SPH - - - - SP10 SP9 SP8	32
(0x60) DIDR0 ADC4D ADC3D ADC2D ADC1D ADC0D AIN1D AIN0D AREFD 0x3F (0x5F) SREG I T H S V N Z C 0x3E (0x5E) SPH - - - - SP10 SP9 SP8	200
0x3F (0x5F) SREG I T H S V N Z C 0x3E (0x5E) SPH - - - - SP10 SP9 SP8	200
0x3E (0x5E) SPH SP10 SP9 SP8	184, 200 14
	13
0x3D (0x5D)	13
0x3C (0x5C)	51
0x3B (0x5B)	52
0x3A (0x5A) TIMSK TOIE1 OCIE1A OCIE1B - ICIE1 OCIE0B TOIE0 OCIE0A	88, 115
0x39 (0x59) TIFR TOV1 OCF1A OCF1B - ICF1 OCF0B TOV0 OCF0A	
0x38 (0x58) QTCSR QTouch Control and Status Register	89, 116
0x37 (0x57) SPMCSR RSIG CTPB RFLB PGWRT PGERS SPMEN	6
0x36 (0x56) MCUCR - SM1 SM0 SE ISC01 ISC00	6 207
0x35 (0x55) MCUSR WDRF BORF EXTRF PORF	6 207 37, 51
0x34 (0x54) PRR - PRTWI PRTIMO PRTIMO PRUSI PRUSART1 PRUSART0 PRADC	6 207 37, 51 44
0x33 (0x53) CLKPR - - - CLKPS3 CLKPS2 CLKPS1 CLKPS0 0x32 (0x52) CLKSR OSCRDY CSTR CKOUT_IO SUT CKSEL3 CKSEL2 CKSEL1 CKSEL0	6 207 37, 51 44 38
0x32 (0x52) CLKSR OSCRDY CSTR CKOUT_IO SUT CKSEL3 CKSEL2 CKSEL1 CKSEL0 0x31 (0x51) Reserved - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - <t< td=""><td>6 207 37, 51 44 38 31</td></t<>	6 207 37, 51 44 38 31
0x31 (0x51) Reserved - - - - - - - - - - - - - - - - - - WDP1 WDP0	6 207 37, 51 44 38
0x2F (0x4F) CCP CPU Change Protection Register	6 207 37,51 44 38 31 29
0x2E (0x4E)	6 207 37,51 44 38 31 29
0x2D (0x4D) USIBR USI Buffer Register	6 207 37,51 44 38 31 29
0x2C (0x4C) USIDR USI Data Register	6 207 37,51 44 38 31 29 45



Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page(s)
0x2B (0x4B)	USISR	USISIF	USIOIF	USIPF	USIDC	USICNT3	USICNT2	USICNT1	USICNT0	142
0x2A (0x4A)	USICR	USISIE	USIOIE	USIWM1	USIWM0	USICS1	USICS0	USICLK	USITC	140
0x29 (0x49)	PCMSK2	-	-	PCINT17	PCINT16	PCINT15	PCINT14	PCINT13	PCINT12	52
0x28 (0x48)	PCMSK1	-	-	-	-	PCINT11	PCINT10	PCINT9	PCINT8	53
0x27 (0x47)	PCMSK0	PCINT7	PCINT6	PCINT5	PCINT4	PCINT3	PCINT2	PCINT1	PCINT0	53
0x26 (0x46)	UCSR0A	RXC0	TXC0	UDRE0	FE0	DOR0	UPE0	U2X0	MPCM	167
0x25 (0x45)	UCSR0B	RXCIE0	TXCIE0	UDRIE0	RXEN0	TXEN0	UCSZ02	RXB80	TXB80	168
0x24 (0x44)	UCSR0C	UMSEL01	UMSEL00	UPM01	UPM00	USBS0	UCSZ01	UCSZ00	UCPOL0	169
0x23 (0x43)	UCSR0D	RXCIE0	RXS0	SFDE0	-	-	_	_	-	171
0x22 (0x42)	UBRR0H	-	-	_	-	US	ART0 Baud Rate	Register High E	Byte	172
0x21 (0x41)	UBRR0L			US	ART0 Baud Rat	e Register Low I	Byte			172
0x20 (0x40)	UDR0				USART0 I/O	Data Register				167
0x1F (0x3F)	EEARH	-	_	_	_	-	_	_	-	
0x1E (0x3E)	EEARL				EEA	R[7:0]				22
0x1D (0x3D)	EEDR				EEPROM D	ata Register				22
0x1C (0x3C)	EECR	-	_	EEPM1	EEPM0	EERIE	EEMPE	EEPE	EERE	22
0x1B (0x3B)	TCCR0A	COM0A1	COM0A0	COM0B1	COM0B0	-	_	WGM01	WGM00	84
0x1A (0x3A)	TCCR0B	FOC0A	FOC0B	_	-	WGM02	CS02	CS01	CS00	86
0x19 (0x39)	TCNT0	Timer/Counter0							88	
0x18 (0x38)	OCR0A	Timer/Counter0 – Compare Register A						88		
0x17 (0x37)	OCR0B	Timer/Counter0 – Compare Register B						88		
0x16 (0x36)	GPIOR2	General Purpose Register 2						23		
0x15 (0x35)	GPIOR1	General Purpose Register 1						24		
0x14 (0x34)	GPIOR0		General Purpose Register 0						24	
0x13 (0x33)	PORTCR	-	_	_	_	-	BBMC	BBMB	BBMA	71
0x12 (0x32)	PUEA	PUEA7	PUEA6	PUEA5	PUEA4	PUEA3	PUEA2	PUEA1	PUEA0	71
0x11 (0x31)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	71
0x10 (0x30)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	71
0x0F (0x2F)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	71
0x0E (0x2E)	PUEB	-	-	_	-	PUEB3	PUEB2	PUEB1	PUEB0	72
0x0D (0x2D)	PORTB	-	-	_	-	PORTB3	PORTB2	PORTB1	PORTB0	72
0x0C (0x2C)	DDRB	-	-	_	-	DDB3	DDB2	DDB1	DDB0	72
0x0B (0x2B)	PINB	-	-	_	-	PINB3	PINB2	PINB1	PINB0	72
0x0A (0x2A)	PUEC	-	-	PUEC5	PUEC4	PUEC3	PUEC2	PUEC1	PUEC0	72
0x09 (0x29)	PORTC	-	-	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	72
0x08 (0x28)	DDRC	-	-	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	72
0x07 (0x27)	PINC	-	-	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	72
0x06 (0x26)	ACSRA	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	182
0x05 (0x25)	ACSRB	HSEL	HLEV	ACLP	-	ACCE	ACME	ACIRS1	ACIRS0	183
0x04 (0x24)	ADMUX	REFS1	REFS0	REFEN	ADC0EN	MUX3	MUX2	MUX1	MUX0	196
0x03 (0x23)	ADCSRA	ADEN	ADSC	ADATE	ADIF	ADIE	ADPS2	ADPS1	ADPS0	197
0x02 (0x22)	ADCSRB	VDEN	VDPD	-	-	ADLAR	ADTS2	ADTS1	ADTS0	199
0x01 (0x21)	ADCH				ADC Data Reg	gister High Byte	•	•		198
0x00 (0x20)	ADCL	ADC Data Register Flight Byte ADC Data Register Low Byte								198

Note:

- 1. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.
- 2. I/O Registers within the address range 0x00 0x1F are directly bit-accessible using the SBI and CBI instructions. In these registers, the value of single bits can be checked by using the SBIS and SBIC instructions.
- 3. Some of the Status Flags are cleared by writing a logical one to them. Note that, unlike most other AVRs, the CBI and SBI instructions will only operation the specified bit, and can therefore be used on registers containing such Status Flags. The CBI and SBI instructions work with registers 0x00 to 0x1F only.



6. Instruction Set Summary

Mnemonics	Operands	Description	Operation	Flags	#Clocks
ARITHMETIC AND I	OGIC INSTRUCTIONS	·			
ADD	Rd, Rr	Add two Registers	$Rd \leftarrow Rd + Rr$	Z,C,N,V,H	1
ADC	Rd, Rr	Add with Carry two Registers	$Rd \leftarrow Rd + Rr + C$	Z,C,N,V,H	1
ADIW	Rdl,K	Add Immediate to Word	Rdh:Rdl ← Rdh:Rdl + K	Z,C,N,V,S	2
SUB	Rd, Rr	Subtract two Registers	Rd ← Rd - Rr	Z,C,N,V,H	1
SUBI	Rd, K	Subtract Constant from Register	Rd ← Rd - K	Z,C,N,V,H	1
SBC	Rd, Rr	Subtract with Carry two Registers	Rd ← Rd - Rr - C	Z,C,N,V,H	1
SBCI	Rd, K	Subtract with Carry Constant from Reg.	$Rd \leftarrow Rd - K - C$	Z,C,N,V,H	1
SBIW	Rdl,K	Subtract Immediate from Word	Rdh:Rdl ← Rdh:Rdl - K	Z,C,N,V,S	2
AND	Rd, Rr	Logical AND Registers	$Rd \leftarrow Rd \bullet Rr$	Z,N,V	1
ANDI	Rd, K	Logical AND Register and Constant	$Rd \leftarrow Rd \bullet K$	Z,N,V	1
OR	Rd, Rr	Logical OR Registers	$Rd \leftarrow Rd v Rr$	Z,N,V	1
ORI	Rd, K	Logical OR Register and Constant	$Rd \leftarrow Rd \vee K$	Z,N,V	1
EOR	Rd, Rr	Exclusive OR Registers	$Rd \leftarrow Rd \oplus Rr$	Z,N,V	1
COM	Rd	One's Complement	$Rd \leftarrow 0xFF - Rd$	Z,C,N,V	1
NEG	Rd	Two's Complement	Rd ← 0x00 – Rd	Z,C,N,V,H	1
SBR	Rd,K	Set Bit(s) in Register	$Rd \leftarrow Rd \vee K$	Z,N,V	1
CBR	Rd,K	Clear Bit(s) in Register	$Rd \leftarrow Rd \bullet (0xFF - K)$	Z,N,V	1
INC	Rd	Increment	Rd ← Rd + 1	Z,N,V	1
DEC	Rd	Decrement	Rd ← Rd – 1	Z,N,V	1
TST	Rd	Test for Zero or Minus	Rd ← Rd • Rd	Z,N,V	1
CLR	Rd	Clear Register	$Rd \leftarrow Rd \oplus Rd$	Z,N,V	1
SER	Rd	Set Register	$Rd \leftarrow 0xFF$	None	1
BRANCH INSTRUCT	TIONS				
JMP	k	Direct Jump	PC ← k	None	3
RJMP	k	Relative Jump	PC ← PC + k + 1	None	2
IJMP		Indirect Jump to (Z)	PC ← Z	None	2
CALL	k	Direct Subroutine	PC ← k	None	4
RCALL	k	Relative Subroutine Call	PC ← PC + k + 1	None	3
ICALL		Indirect Call to (Z)	PC ← Z	None	3
RET		Subroutine Return	PC ← STACK	None	4
RETI		Interrupt Return	PC ← STACK	1	4
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC ← PC + 2 or 3	None	1/2/3
CP	Rd,Rr	Compare	Rd – Rr	Z, N,V,C,H	1
CPC	Rd,Rr	Compare with Carry	Rd – Rr – C	Z, N,V,C,H	1
CPI	Rd,K	Compare Register with Immediate	Rd – K	Z, N,V,C,H	1
SBRC	Rr, b	Skip if Bit in Register Cleared	if (Rr(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBRS	Rr, b	Skip if Bit in Register is Set	if $(Rr(b)=1) PC \leftarrow PC + 2 \text{ or } 3$	None	1/2/3
SBIC	P, b	Skip if Bit in I/O Register Cleared	if (P(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBIS	P, b	Skip if Bit in I/O Register is Set	if (P(b)=1) PC ← PC + 2 or 3	None	1/2/3
BRBS	s, k	Branch if Status Flag Set	if (SREG(s) = 1) then PC←PC+k + 1	None	1/2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 0) then PC←PC+k + 1	None	1/2
BREQ	k	Branch if Equal	if (Z = 1) then PC ← PC + k + 1	None	1/2
BRNE	k	Branch if Not Equal	if (Z = 0) then PC ← PC + k + 1	None	1/2
BRCS	k	Branch if Carry Set	if (C = 1) then PC ← PC + k + 1	None	1/2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC ← PC + k + 1	None	1/2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC ← PC + k + 1	None	1/2
BRLO	k	Branch if Lower	if (C = 1) then PC ← PC + k + 1	None	1/2
BRMI	k	Branch if Minus	if (N = 1) then PC \leftarrow PC + k + 1	None	1/2
BRPL	k	Branch if Plus	if (N = 0) then PC \leftarrow PC + k + 1	None	1/2
BRGE	k	Branch if Greater or Equal, Signed	if $(N \oplus V = 0)$ then $PC \leftarrow PC + k + 1$	None	1/2
BRLT	k	Branch if Less Than Zero, Signed	if (N ⊕ V= 1) then PC ← PC + k + 1	None	1/2
BRHS	k	Branch if Half Carry Flag Set	if (H = 1) then PC ← PC + k + 1	None	1/2
BRHC	k	Branch if Half Carry Flag Cleared	if (H = 0) then PC \leftarrow PC + k + 1	None	1/2
BRTS	k	Branch if T Flag Set	if (T = 1) then PC ← PC + k + 1	None	1/2
BRTC	k	Branch if T Flag Cleared	if (T = 0) then PC ← PC + k + 1	None	1/2
BRVS	k	Branch if Overflow Flag is Set	if (V = 1) then PC ← PC + k + 1	None	1/2
BRVC	k	Branch if Overflow Flag is Cleared	if $(V = 0)$ then $PC \leftarrow PC + k + 1$	None	1/2
BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC ← PC + k + 1	None	1/2
BRID BIT AND BIT TEST I	k	Branch if Interrupt Disabled	if (I = 0) then PC ← PC + k + 1	None	1/2
BIT AND BIT-TEST I		Out Divin I/O Descietos	LIO(DE)	Lare	
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	$I/O(P,b) \leftarrow 0$	None	2
LSL	Rd	Logical Shift Left	$Rd(n+1) \leftarrow Rd(n), Rd(0) \leftarrow 0$	Z,C,N,V	1
LSR	Rd	Logical Shift Right	$Rd(n) \leftarrow Rd(n+1), Rd(7) \leftarrow 0$	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	$Rd(0)\leftarrow C,Rd(n+1)\leftarrow Rd(n),C\leftarrow Rd(7)$	Z,C,N,V	1



Mnemonics	Operands	Description	Operation	Flags	#Clocks
ROR	Rd	Rotate Right Through Carry	$Rd(7)\leftarrow C,Rd(n)\leftarrow Rd(n+1),C\leftarrow Rd(0)$	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	$Rd(n) \leftarrow Rd(n+1), n=06$	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(30)←Rd(74),Rd(74)←Rd(30)	None	1
BSET	S	Flag Set	SREG(s) ← 1	SREG(s)	1
BCLR	S	Flag Clear	$SREG(s) \leftarrow 0$	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	Т	1
BLD	Rd, b	Bit load from T to Register	$Rd(b) \leftarrow T$	None	1
SEC		Set Carry	C ← 1	С	1
CLC		Clear Carry	C ← 0	С	1
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag	N ← 0	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 0	Z	1
SEI		Global Interrupt Enable	I ← 1	1	1
CLI		Global Interrupt Disable	1 ← 0	1	1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET		Set T in SREG	T ← 1	T	1
CLT		Clear T in SREG	T ← 0	Ť	1
SEH		Set Half Carry Flag in SREG	H←1	Н	1
CLH		Clear Half Carry Flag in SREG	H ← 0	H	1
DATA TRANSFER	INSTRUCTIONS		4 · · · · · · · ·		<u> </u>
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	Rd+1:Rd ← Rr+1:Rr	None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	$Rd \leftarrow (X)$	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	$Rd \leftarrow (X)$ $Rd \leftarrow (X), X \leftarrow X + 1$	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	$X \leftarrow X - 1$, $Rd \leftarrow (X)$	None	2
LD	Rd, Y	Load Indirect Load Indirect	$Rd \leftarrow (Y)$	None	2
LD	Rd, Y+	Load Indirect Load Indirect and Post-Inc.	$Rd \leftarrow (1)$ $Rd \leftarrow (Y), Y \leftarrow Y + 1$	None	2
LD			$Y \leftarrow Y - 1, Rd \leftarrow (Y)$		2
LDD	Rd, - Y	Load Indirect and Pre-Dec.		None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1$, $Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z+q)$	None	2
LDS	Rd, k	Load Direct from SRAM	Rd ← (k)	None	2
ST	X, Rr	Store Indirect	(X) ← Rr	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	$(X) \leftarrow Rr, X \leftarrow X + 1$	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	$X \leftarrow X - 1, (X) \leftarrow Rr$	None	2
ST	Y, Rr	Store Indirect	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1$, $(Y) \leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	(Y + q) ← Rr	None	2
ST	Z, Rr	Store Indirect	$(Z) \leftarrow Rr$	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	$(Z) \leftarrow Rr, Z \leftarrow Z + 1$	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	$Z \leftarrow Z - 1$, $(Z) \leftarrow Rr$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	$(Z + q) \leftarrow Rr$	None	2
STS	k, Rr	Store Direct to SRAM	(k) ← Rr	None	2
LPM		Load Program Memory	R0 ← (Z)	None	3
LPM	Rd, Z	Load Program Memory	$Rd \leftarrow (Z)$	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	3
SPM		Store Program Memory	(z) ← R1:R0	None	
IN	Rd, P	In Port	$Rd \leftarrow P$	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	$Rd \leftarrow STACK$	None	2
MCU CONTROL IN	STRUCTIONS				
NOP		No Operation		None	1
	1	Sleep	(see specific descr. for Sleep function)	None	1
SLEEP		C.00p	(cor operation accounts the corp.		
SLEEP WDR		Watchdog Reset	(see specific descr. for WDR/Timer)	None	1



Ordering Information 7.

7.1 ATtiny1634

Speed (MHz) (1)	Supply Voltage (V)	Temperature Range	Package ⁽²⁾	Accuracy (3)	Ordering Code ⁽⁴⁾
12	1.8 – 5.5	Industrial (-40°C to +85°C) ⁽⁵⁾	20M1	±10%	ATtiny1634-MU
				±2%	ATtiny1634R-MU
				±10%	ATtiny1634-MUR
				±2%	ATtiny1634R-MUR
			20\$2	±10%	ATtiny1634-SU
				±2%	ATtiny1634R-SU
				±10%	ATtiny1634-SUR
				±2%	ATtiny1634R-SUR
			20U-1	±10%	ATtiny1634-UUR

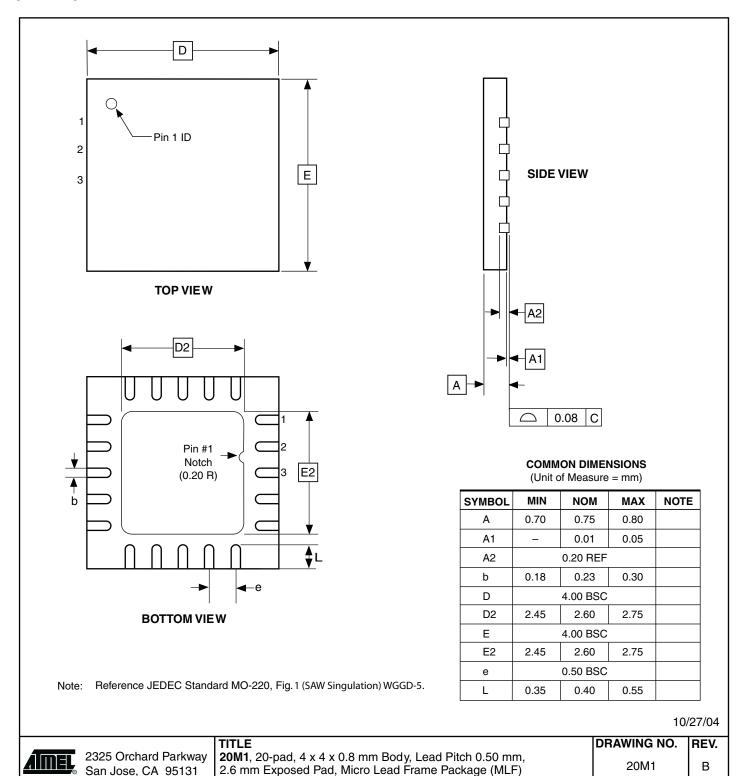
- Notes: 1. For speed vs. supply voltage, see section 24.3 "Speed" on page 229.
 - 2. All packages are Pb-free, halide-free and fully green, and they comply with the European directive for Restriction of Hazardous Substances (RoHS).
 - 3. Denotes accuracy of the internal oscillator. See Table 24-2 on page 230.
 - 4. Code indicators:
 - U: matte tin
 - R: tape & reel
 - 5. Can also be supplied in wafer form. Contact your local Atmel sales office for ordering information and minimum quantities.

Package Type						
20M1	20-pad, 4 x 4 x 0.8 mm Body, Quad Flat No-Lead / Micro Lead Frame Package (QFN/MLF)					
20\$2	20-lead, 0.300" Wide Body, Plastic Gull Wing Small Outline Package (SOIC)					
20U-1	20-ball 2.38 x 2.02 x 0.409mm Body, 5x4 Array, 0.40 mm Pitch, Wafer Level Chip Scale Package (WLCSP)					



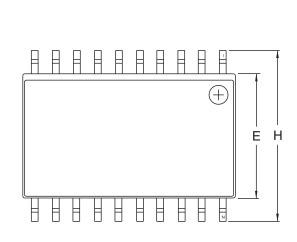
8. Packaging Information

8.1 20M1

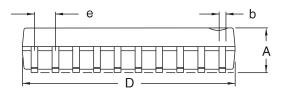




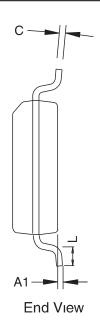
20S2 8.2



Top View



Side View



COMMON DIMENSIONS

(Unit of Measure - mm)

SYMBOL	MIN	NOM	MAX	NOTE
Α	2.35		2.65	
A1	0.10		0.30	
b	0.33		0.51	4
С	0.23		0.32	
D	12.60		13.00	1
Е	7.40		7.60	2
Н	10.00		10.65	
L	0.40		1.27	3
е		1.27 BS	С	

- Notes. 1. This drawing is for general information only; refer to JEDEC Drawing MS-013, Variation AC for additional information.
 2. Dimension 'D' does not include mold Flash, protrusions or gate burrs. Mold Flash, protrusions and gate burrs shall not exceed 0.15 mm (0.006') per side.
 - 3. Dimension 'E' does not include inter-lead Flash or protrusion. Inter-lead Flash and protrusions shall not exceed 0.25 mm (0.010') per side.

 4. 'L' is the length of the terminal for soldering to a substrate.

 - 4. 'L' is the length of the terminal for soldering to a substrate.
 5. The lead width 'b', as measured 0.36 mm (0.014') or greater above the seating plane, shall not exceed a maximum value of 0.61 mm 11/6/06 (0.024') per side.



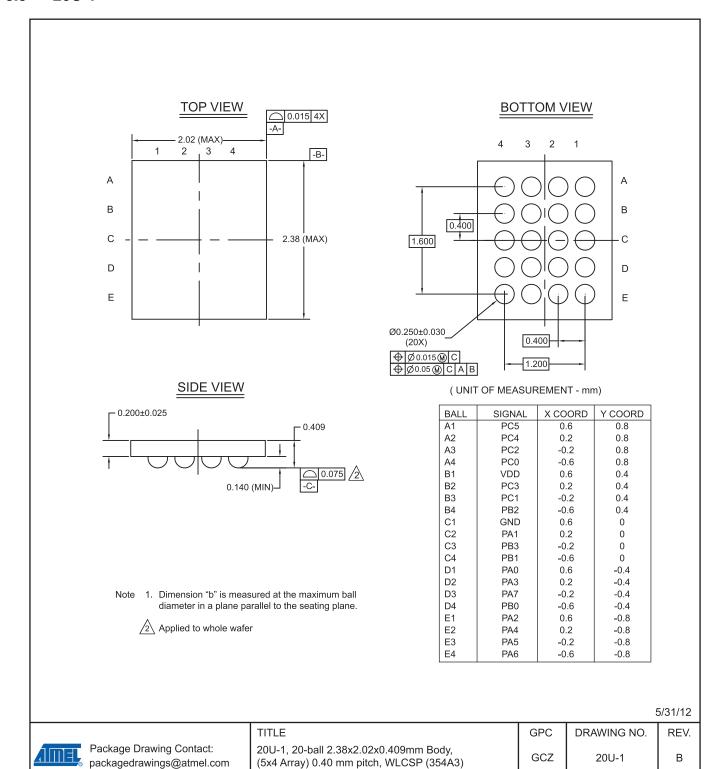
2325 Orchard Parkway San Jose, CA 95131

20S2, 20-lead, 0.300' Wide Body, Plastic Gull Wing Small Outline Package (SOIC)

DRAWING NO. REV. В 20S2



8.3 20U-1





9. Errata

The revision letters in this section refer to the revision of the corresponding ATtiny1634 device.

9.1 ATtiny1634

9.1.1 Rev. B

• Port Pin Should Not Be Used As Input When ULP Oscillator Is Disabled

1. Port Pin Should Not Be Used As Input When ULP Oscillator Is Disabled

Port pin PB3 is not guaranteed to perform as a reliable input when the Ultra Low Power (ULP) oscillator is not running. In addition, the pin is pulled down internally when ULP oscillator is disabled.

Problem Fix / Workaround

The ULP oscillator is automatically activated when required. To use PB3 as an input, activate the watchdog timer. The watchdog timer automatically enables the ULP oscillator.

9.1.2 Rev. A

- Flash / EEPROM Can Not Be Written When Supply Voltage Is Below 2.4V
- Port Pin Should Not Be Used As Input When ULP Oscillator Is Disabled

1. Flash / EEPROM Can Not Be Written When Supply Voltage Is Below 2.4V

When supply voltage is below 2.4V write operations to Flash and EEPROM may fail.

Problem Fix / Workaround

Do not write to Flash or EEPROM when supply voltage is below 2.4V.

2. Port Pin Should Not Be Used As Input When ULP Oscillator Is Disabled

Port pin PB3 is not guaranteed to perform as a reliable input when the Ultra Low Power (ULP) oscillator is not running. In addition, the pin is pulled down internally when ULP oscillator is disabled.

Problem Fix / Workaround

The ULP oscillator is automatically activated when required. To use PB3 as an input, activate the watchdog timer. The watchdog timer automatically enables the ULP oscillator.



10. Datasheet Revision History

10.1 Rev. 8303F - 08/2013

1. Updated Bit 2 from the UCSR1C register from "USBSZ11" to "UCSZ11" in "Register Summary" on page 7.

10.2 Rev. 8303E - 01/2013

- 1. Updated:
 - Applied the Atmel new brand template that includes new log and new addresses.

10.3 Rev. 8303D - 06/12

- 1. Updated:
 - "Ordering Information" on page 11
- 2. Added:
 - Wafer Level Chip Scale Package "20U-1" on page 14

10.4 Rev. 8303C - 03/12

- 1. Updated:
 - "Register Description" on page 167
 - "Self-Programming" on page 203

10.5 Rev. 8303B - 03/12

- 1. Removed Preliminary status.
- 2. Added:
 - "Typical Characteristics" on page 239
 - "Temperature Sensor" on page 235
 - "Rev. B" on page 15
- 3. Updated:
 - "Pin Descriptions" on page 3
 - "Calibrated Internal 8MHz Oscillator" on page 27
 - "OSCTCALOA Oscillator Temperature Calibration Register A" on page 33
 - "OSCTCAL0B Oscillator Temperature Calibration Register B" on page 33
 - "TWSCRA TWI Slave Control Register A" on page 127
 - "USART (USART0 & USART1)" on page 145
 - "Temperature vs. Sensor Output Voltage (Typical)" on page 195
 - "DC Characteristics" on page 228
 - "Calibration Accuracy of Internal 32kHz Oscillator" on page 231
 - "External Clock Drive Characteristics" on page 231
 - "Reset, Brown-out, and Internal Voltage Characteristics" on page 231
 - "Analog Comparator Characteristics, TA = -40°C to +85°C" on page 235
 - "Parallel Programming Characteristics, $T_A = 25$ °C, $V_{CC} = 5V$ " on page 237
 - "Serial Programming Characteristics, $T_A = -40$ °C to +85°C" on page 238
 - "Ordering Information" on page 11



10.6 Rev. 8303A - 11/11

Initial revision.





Atmel Corporation

1600 Technology Drive San Jose, CA 95110 USA

Tel: (+1) (408) 441-0311 **Fax:** (+1) (408) 487-2600

www.atmel.com

Atmel Asia Limited

Unit 01-5 & 16, 19F BEA Tower, Millennium City 5 418 Kwun Tong Roa Kwun Tong, Kowloon

HONG KONG **Tel:** (+852) 2245-6100

Fax: (+852) 2722-1369

Atmel Munich GmbH

Business Campus
Parkring 4
D-85748 Garching b. Munich
GERMANY

Tel: (+49) 89-31970-0 **Fax:** (+49) 89-3194621

Atmel Japan G.K.

16F Shin-Osaki Kangyo Bldg 1-6-4 Osaki, Shinagawa-ku

Tokyo 141-0032

JAPAN

Tel: (+81) (3) 6417-0300 **Fax:** (+81) (3) 6417-0370

© 2013 Atmel Corporation. All rights reserved. / Rev.: 8303FS-AVR-08/2013

Atmel[®], Atmel logo and combinations thereof, Enabling Unlimited Possibilities[®], AVR[®], tinyAVR[®], QTouch[®] and others are registered trademarks or trademarks of Atmel Corporation or its subsidiaries. Other terms and product names may be trademarks of others.

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. EXCEPT AS SET FORTH IN THE ATMEL TERMS AND CONDITIONS OF SALES LOCATED ON THE ATMEL WEBSITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDENTAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS AND PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and products descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.