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SERIES: AMT10X DESCRIPTION: INCREMENTAL ENCODER

FEATURES

- patented capacitive technology
- ·16 dip switch programmable resolutions
- ·straight (radial) and right-angle (axial) versions
- 9 different mounting hole options for AMT102
- •6 different mounting hole options for AMT103
- ·low power consumption
- ·line driver output available (CUI-10XE-10)
- •-40°C to 100°C operating temperature
- TTL voltage output
- · modular package



ELECTRICAL SPECIFICATIONS

ELLCTRICATE ST ECHTICATIONS	
output phase difference	90° (A ch leads B ch in CW direction viewed from front)
output current	5 mA max.
output waveform	TTL voltage square wave
output signals	A, B, Z^1 phase (\overline{A} , \overline{B} , \overline{C} line driver available with CUI-10XE-10)
current consumption	6 mA typ., 10 mA max.
supply voltage	3.6 ~ 5.5 V dc
output resolution (ppr) ²	48, 96, 100, 125, 192, 200, 250, 256, 384, 400, 500, 512, 800, 1000, 1024, 2048
frequency response	250 kHz max.
accuracy ³	±15 arcmin (at 192, 384, 400, 500, 800, 1000, 1024, 2048 ppr) ±30 arcmin (at 96, 200, 250, 512 ppr) ±60 arcmin (at 48, 100, 125, 256 ppr)
max. rotational speed	7500 rpm (at 2048, 1000, 800, 384 ppr) 15000 rpm (at 1024, 500, 400, 192 ppr) 30000 rpm (at 48, 96, 100, 125, 200, 250, 256, 512 ppr)

- 1. Some stepper motors may leak a magnetic field causing the AMT index pulse to not function properly.
- 2. All resolutions stated are before quadrature decoding. (example: 1000 ppr \times 4 = 4000 counts)
- 3. Based on full production testing standards and includes all electronic and mechanical based errors, not a computed estimate.

MECHANICAL SPECIFICATIONS

mounting hole options		A) 2 each M1.6 holes on 16 mm (0.63") bolt circle B) 2 each #4 holes on 19.05 mm (0.75") bolt circle C) 2 each M1.6 or M2 holes on 20 mm (0.787") bolt circle D) 3 each M1.6 or M2 holes on 20.9 mm (0.823") bolt circle E) 3 each M1.6 or M2 holes on 22 mm (0.866") bolt circle F) 4 each M1.6 or M2 holes on 25.4 mm (1") bolt circle G) 2 each #4 holes on 15.75 mm (0.62") x 20.96 (0.825") hole layout* H) 2 each #4 holes on 32.43 mm (1.277") bolt circle* I) 2 each #4 holes on 46.03 mm (1.812") bolt circle*
weight	AMT102 AMT103	20.5 g 14.0 g
vibration proof		50 m/s², 10 ~ 200 Hz, 2 hours each on XYZ
shock resistance		147 m/s², 11 ms, 2 hours each on XYZ



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2mm

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ENVIRONMENTAL SPECIFICATIONS

operating temperature	-40° ~ +100° C
storage temperature	-40° ~ +100°C
humidity	30 ~ 95% (no condensation)

AMT10X-V KIT

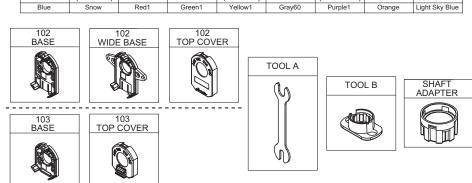
In order to provide maximum flexibility for our customers, the AMT10X series is provided in kit form standard. This allows the user to implement the encoder into a range of applications using one sku#, reducing engineering and inventory costs.



AMT10X - V

Mounting Version: 2 = Straight (radial connector)

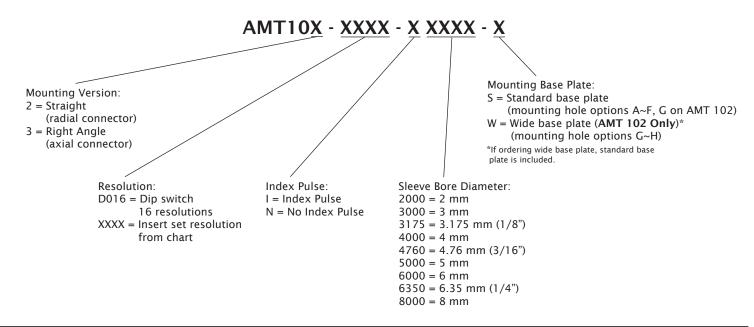
3 = Right Angle (axial connector)



SLEEVES

CUSTOM CONFIG KEY

For customers that prefer a specific AMT10X configuration, please reference the custom configuration key below.





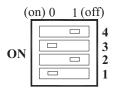
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SERIES: AMT10X **DESCRIPTION: INCREMENTAL ENCODER**

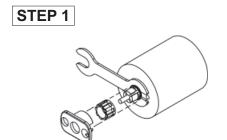
RESOLUTION SETTINGS

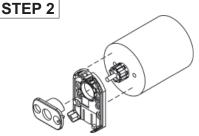
0 = On, 1 = OffResolution (PPR) Maximum RPM

DIP switch: Example setting: 500



ASSEMBLY PROCEDURE





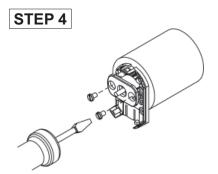
6a. Align Tool B with flange on Base.

STEP 3

6b. Slide Base and Tool B onto motor, centering onto the Shaft Adapter.

Align Tool B with flange on Base

- Insert Tool A as a spacer that defines the distance to the mounting surface.
 Slide appropriate sized Sleeve over shaft all the way down to Tool A.
- Slide Shaft Adaptor over Sleeve.
 Use Tool B to press Shaft Adaptor over Sleeve until flush with Tool A.
- 5. Remove Tools A and B.6. Place Base on motor, with Tool B used as a centering tool.

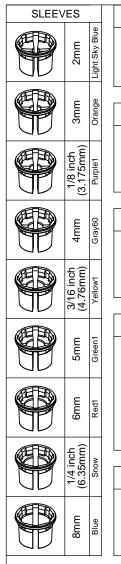


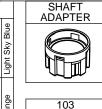
- 7. Fasten the Base on the motor.
- 8. Remove Tool B.

- STEP 5
- 9. Slide the Top Cover onto the Base, carefully observing that the teeth of the Shaft Adaptor align with the grooves in the hub.



- 10. Make sure the snaps are fully engaged and the Top Cover is flush
- 11. When assembly is finished, the Shaft Adaptor should be about flush with the front of the Encoder and the Motor Shaft should rotate freely.





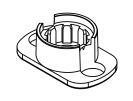


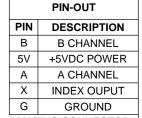






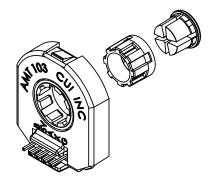






MATING CONNECTOR AMP 3-640440-5

CABLES AVAILABLE (SOLD SEPERATELY)





MM [INCHES]

SCALE:

N/A



20050 SW 112th Ave. Tualatin, OR 97062 Phone: 503-612-2300 800-275-4899 Fax: 503-612-2383 Website: www.cui.com

TITLE: REV: AMT103-V PART NO. UNITS:

AMT103-V

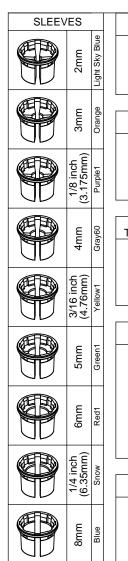
APPROVED BY: DRAWN BY: ZRJ

AMT103-V comes with all items shown: all Sleeve sizes, Shaft Adapter, Base, Top Cover, Tool A, Tool B, Index Pulse, and 16 Resolution Dip Switch.

AMT103-V-REV-E

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PC FILE NAME:



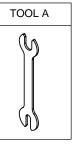




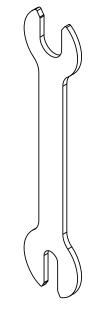


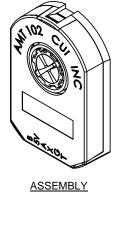




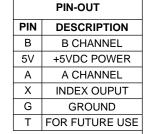






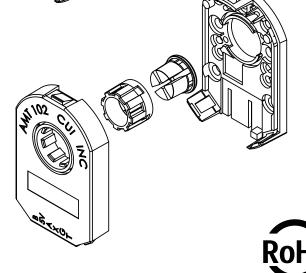






MATING CONNECTOR MOLEX 50-57-9405 HOUSING MOLEX 16-02-0086 TERMINALS

> CABLES AVAILABLE (SOLD SEPERATELY)





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TITLE: REV: AMT102-V PART NO. UNITS: AMT102-V

DRAWN BY: ZRJ

MM [INCHES] APPROVED BY: SCALE: N/A

AMT102-V comes with all items shown: all Sleeve sizes, Shaft Adapter, Base, Wide Base, Top Cover, Tool A, Tool B, Index Pulse, and 16 Resolution Dip Switch.

