

# DRAM MODULE

**KMM366F400CK1**  
**KMM366F410CK1**

## KMM366F400CK1 & KMM366F410CK1 EDO Mode without buffer

4M x 64 DRAM DIMM using 4Mx4, 4K & 2K Refresh, 3.3V

### GENERAL DESCRIPTION

The Samsung KMM366F40(1)0CK1 is a 4Mx64bits Dynamic RAM high density memory module. The Samsung KMM366F40(1)0CK1 consists of sixteen CMOS 4Mx4bits DRAMs in SOJ 300mil package and one 1K/2K EEPROM for SPD in 8-pin TSSOP package mounted on a 168-pin glass-epoxy substrate. A 0.1 or 0.22uF decoupling capacitor is mounted on the printed circuit board for each DRAM. The KMM366F40(1)0CK1 is a Dual In-line Memory Module and is intended for mounting into 168 pin edge connector sockets.

### PERFORMANCE RANGE

Speed	tRAC	tCAC	tRC	tHPC
-5	50ns	13ns	90ns	25ns
-6	60ns	15ns	110ns	30ns

### FEATURES

- Part Identification
  - KMM366F400CK1 (4096 cycles/64ms Ref. SOJ)
  - KMM366F410CK1 (2048 cycles/32ms Ref. SOJ)
- New JEDEC standard proposal without buffer
- Serial Presence Detect with EEPROM
- Extended Data Out Mode Operation
- $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  Refresh capability
- $\overline{\text{RAS}}$ -only and Hidden refresh capability
- LVTTTL compatible inputs and outputs
- Single +3.3V±0.3V power supply
- PCB : Height(1000mil), double sided component

### PIN CONFIGURATIONS

Pin	Front	Pin	Front	Pin	Front	Pin	Back	Pin	Back	Pin	Back
1	Vss	29	$\overline{\text{CAS1}}$	57	DQ18	85	Vss	113	$\overline{\text{CAS5}}$	141	DQ50
2	DQ0	30	$\overline{\text{RAS0}}$	58	DQ19	86	DQ32	114	* $\overline{\text{RAS1}}$	142	DQ51
3	DQ1	31	$\overline{\text{OE0}}$	59	Vcc	87	DQ33	115	DU	143	Vcc
4	DQ2	32	Vss	60	DQ20	88	DQ34	116	Vss	144	DQ52
5	DQ3	33	A0	61	NC	89	DQ35	117	A1	145	NC
6	Vcc	34	A2	62	DU	90	Vcc	118	A3	146	DU
7	DQ4	35	A4	63	NC	91	DQ36	119	A5	147	NC
8	DQ5	36	A6	64	Vss	92	DQ37	120	A7	148	Vss
9	DQ6	37	A8	65	DQ21	93	DQ38	121	A9	149	DQ53
10	DQ7	38	A10	66	DQ22	94	DQ39	122	A11	150	DQ54
11	DQ8	39	*A12	67	DQ23	95	DQ40	123	*A13	151	DQ55
12	Vss	40	Vcc	68	Vss	96	Vss	124	Vcc	152	Vss
13	DQ9	41	Vcc	69	DQ24	97	DQ41	125	DU	153	DQ56
14	DQ10	42	DU	70	DQ25	98	DQ42	126	DU	154	DQ57
15	DQ11	43	Vss	71	DQ26	99	DQ43	127	Vss	155	DQ58
16	DQ12	44	$\overline{\text{OE2}}$	72	DQ27	100	DQ44	128	DU	156	DQ59
17	DQ13	45	$\overline{\text{RAS2}}$	73	Vcc	101	DQ45	129	* $\overline{\text{RAS3}}$	157	Vcc
18	Vcc	46	$\overline{\text{CAS2}}$	74	DQ28	102	Vcc	130	$\overline{\text{CAS6}}$	158	DQ60
19	DQ14	47	$\overline{\text{CAS3}}$	75	DQ29	103	DQ46	131	$\overline{\text{CAS7}}$	159	DQ61
20	DQ15	48	$\overline{\text{W2}}$	76	DQ30	104	DQ47	132	DU	160	DQ62
21	*CB0	49	Vcc	77	DQ31	105	*CB4	133	Vcc	161	DQ63
22	*CB1	50	NC	78	Vss	106	*CB5	134	NC	162	Vss
23	Vss	51	NC	79	NC	107	Vss	135	NC	163	NC
24	NC	52	*CB2	80	NC	108	NC	136	*CB6	164	NC
25	NC	53	*CB3	81	NC	109	NC	137	*CB7	165	**SA0
26	Vcc	54	Vss	82	**SDA	110	Vcc	138	Vss	166	**SA1
27	$\overline{\text{W0}}$	55	DQ16	83	**SCL	111	DU	139	DQ48	167	**SA2
28	$\overline{\text{CAS0}}$	56	DQ17	84	Vcc	112	$\overline{\text{CAS4}}$	140	DQ49	168	Vcc

NOTE : A12 is used for only KMM366F400CK1 (4K ref.)

### PIN NAMES

Pin Name	Function
A0 - A11	Address Input(4K ref.)
A0 - A10	Address Input(2K ref.)
DQ0 - DQ63	Data In/Out
$\overline{\text{W0}}, \overline{\text{W2}}$	Read/Write Enable
$\overline{\text{OE0}}, \overline{\text{OE2}}$	Output Enable
$\overline{\text{RAS0}}, \overline{\text{RAS2}}$	Row Address Strobe
$\overline{\text{CAS0}} - \overline{\text{CAS7}}$	Column Address Strobe
Vcc	Power(+3.3V)
Vss	Ground
NC	No Connection
DU	Don't use
**SDA	Serial Address /Data I/O
**SCL	Serial Clock
**SA0 - **SA2	Address in EEPROM
*CB0 - *CB7	Check Bit

\* These pins are not used in this modeule.

\*\* These pins should be NC in the system which does not support SPD.

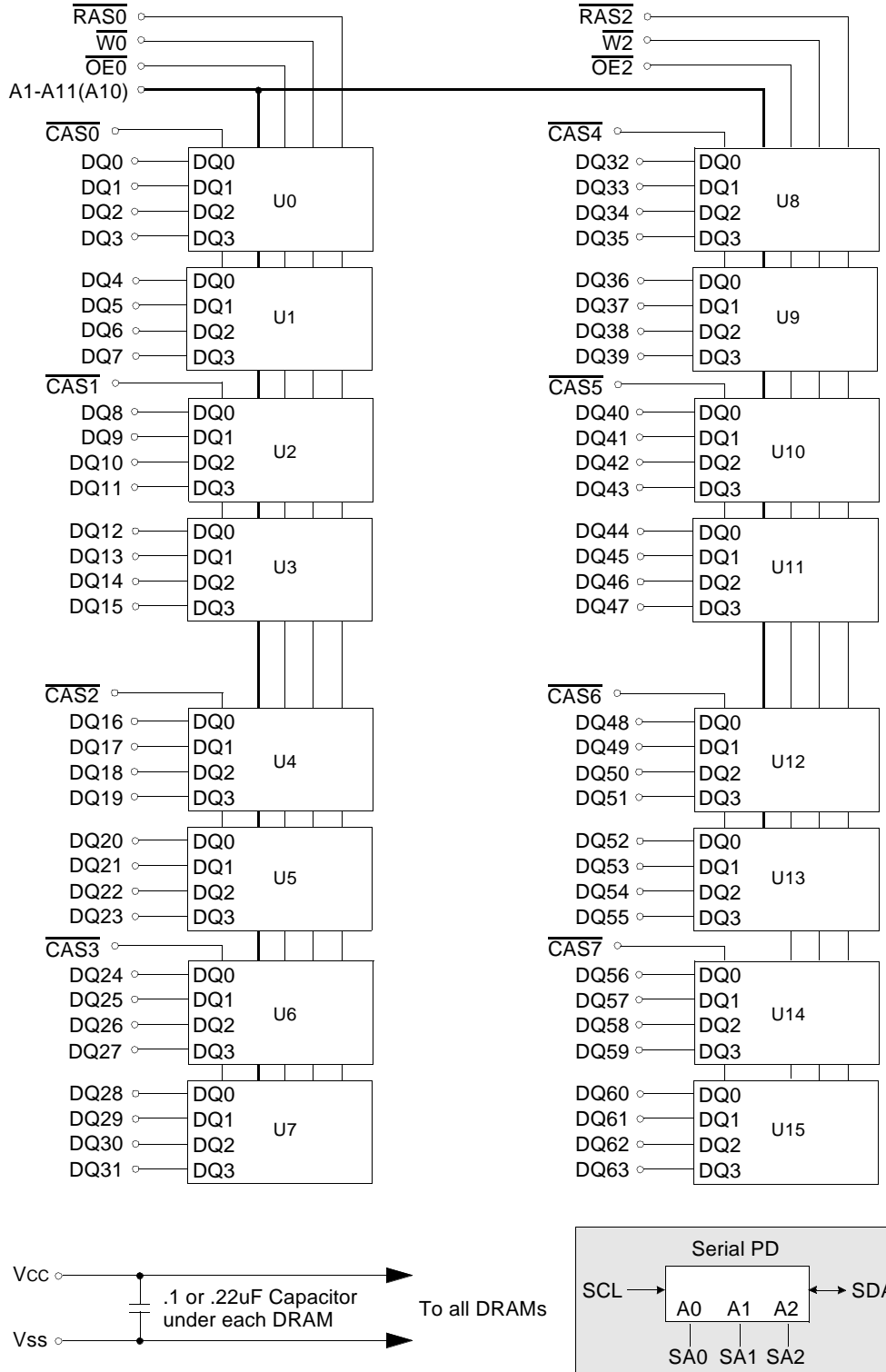


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## FUNCTIONAL BLOCK DIAGRAM



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## ABSOLUTE MAXIMUM RATINGS \*

Item	Symbol	Rating	Unit
Voltage on any pin relative Vss	V <sub>IN</sub> , V <sub>OUT</sub>	-0.5 to +4.6	V
Voltage on Vcc supply relative to Vss	V <sub>CC</sub>	-0.5 to +4.6	V
Storage Temperature	T <sub>stg</sub>	-55 to +150	°C
Power Dissipation	P <sub>D</sub>	16	W
Short Circuit Output Current	I <sub>OS</sub>	50	mA

\* Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for intended periods may affect device reliability.

## RECOMMENDED OPERATING CONDITIONS (Voltage referenced to Vss, TA = 0 to 70°C)

Item	Symbol	Min	Typ	Max	Unit
Supply Voltage	V <sub>CC</sub>	3.0	3.3	3.6	V
Ground	V <sub>SS</sub>	0	0	0	V
Input High Voltage	V <sub>IH</sub>	2.0	-	V <sub>CC</sub> +0.3 <sup>*1</sup>	V
Input Low Voltage	V <sub>IL</sub>	-0.3 <sup>*2</sup>	-	0.8	V

\*1 : V<sub>CC</sub>+1.3V at pulse width ≤ 15ns which is measured at V<sub>CC</sub>.

\*2 : -1.3V at pulse width ≤ 15ns which is measured at V<sub>SS</sub>.

## DC AND OPERATING CHARACTERISTICS (Recommended operating conditions unless otherwise noted)

Symbol	Speed	KMM366F400CK1		KMM366F410CK1		Unit
		Min	Max	Min	Max	
I <sub>CC1</sub>	-5	-	1440	-	1760	mA
	-6	-	1280	-	1600	mA
I <sub>CC2</sub>	Don't care	-	16	-	16	mA
I <sub>CC3</sub>	-5	-	1440	-	1760	mA
	-6	-	1280	-	1600	mA
I <sub>CC4</sub>	-5	-	1280	-	1440	mA
	-6	-	1120	-	1280	mA
I <sub>CC5</sub>	Don't care	-	8	-	8	mA
I <sub>CC6</sub>	-5	-	1440	-	1760	mA
	-6	-	1280	-	1600	mA
I <sub>I(L)</sub>	Don't care	-80	80	-80	80	uA
I <sub>O(L)</sub>		-5	5	-5	5	uA
V <sub>OH</sub>	Don't care	2.4	-	2.4	-	V
V <sub>OL</sub>		-	0.4	-	0.4	V

I<sub>CC1</sub> : Operating Current \* ( $\overline{RAS}$ ,  $\overline{CAS}$ , Address cycling @trc=min)

I<sub>CC2</sub> : Standby Current ( $\overline{RAS}=\overline{CAS}=\overline{W}=V_{IH}$ )

I<sub>CC3</sub> :  $\overline{RAS}$  Only Refresh Current \* ( $\overline{CAS}=V_{IH}$ ,  $\overline{RAS}$  cycling @trc=min)

I<sub>CC4</sub> : Extended Data Out Mode Current \* ( $\overline{RAS}=V_{IL}$ ,  $\overline{CAS}$  cycling : t<sub>HPC</sub>=min)

I<sub>CC5</sub> : Standby Current ( $\overline{RAS}=\overline{CAS}=\overline{W}=V_{CC}-0.2V$ )

I<sub>CC6</sub> :  $\overline{CAS}$ -Before- $\overline{RAS}$  Refresh Current \* ( $\overline{RAS}$  and  $\overline{CAS}$  cycling @trc=min)

I<sub>I(L)</sub> : Input Leakage Current (Any input 0 ≤ V<sub>IN</sub> ≤ V<sub>CC</sub>+0.3V, all other pins not under test=0 V)

I<sub>O(L)</sub> : Output Leakage Current(Data Out is disabled, 0V ≤ V<sub>OUT</sub> ≤ V<sub>CC</sub>)

V<sub>OH</sub> : Output High Voltage Level (I<sub>OH</sub> = -2mA)

V<sub>OL</sub> : Output Low Voltage Level (I<sub>OL</sub> = 2mA)

\* NOTE : I<sub>CC1</sub>, I<sub>CC3</sub>, I<sub>CC4</sub> and I<sub>CC6</sub> are dependent on output loading and cycle rates. Specified values are obtained with the output open. I<sub>CC</sub> is specified as an average current. In I<sub>CC1</sub> and I<sub>CC3</sub>, address can be changed maximum once while  $\overline{RAS}=V_{IL}$ . In I<sub>CC4</sub>, address can be changed maximum once within one EDO mode cycle, t<sub>HPC</sub>.



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## CAPACITANCE (TA = 25°C, VCC=3.3V, f = 1MHz)

Item	Symbol	Min	Max	Unit
Input capacitance[A0-A11(A10)]	CIN1	-	90	pF
Input capacitance[W0, W2, OE0, OE2]	CIN2	-	66	pF
Input capacitance[RAS0, RAS2]	CIN3	-	66	pF
Input capacitance[CAS0 - CAS7]	CIN4	-	24	pF
Input/Output capacitance[DQ0-DQ63]	CDQ1	-	17	pF

## AC CHARACTERISTICS (0°C≤TA≤70°C, VCC=3.3V±0.3V. See notes 1,2.)

Test condition : Vih/Vil=2.0/0.8V, Voh/Vol=2.0/0.8V, Output loading CL=100pF

Parameter	Symbol	-5		-6		Unit	Note
		Min	Max	Min	Max		
Random read or write cycle time	tRC	90		110		ns	
Read-modify-write cycle time	tRWC	131		155		ns	
Access time from $\overline{\text{RAS}}$	tRAC		50		60	ns	3,4,10
Access time from $\overline{\text{CAS}}$	tCAC		13		15	ns	3,4,5
Access time from column address	tAA		25		30	ns	3,10
$\overline{\text{CAS}}$ to output in Low-Z	tCLZ	3		3		ns	3
$\overline{\text{OE}}$ to output in Low-Z	tOLZ	3		3		ns	3
Output buffer turn-off delay from $\overline{\text{CAS}}$	tCEZ	3	13	3	15	ns	6,11,12
Transition time(rise and fall)	tT	2	50	2	50	ns	2
$\overline{\text{RAS}}$ precharge time	tRP	30		40		ns	
$\overline{\text{RAS}}$ pulse width	tRAS	50	10K	60	10K	ns	
$\overline{\text{RAS}}$ hold time	tRSH	13		15		ns	
$\overline{\text{CAS}}$ hold time	tCSH	38		45		ns	
$\overline{\text{CAS}}$ pulse width	tCAS	8	10K	10	10K	ns	13
$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ delay time	tRCD	20	37	20	45	ns	4
$\overline{\text{RAS}}$ to column address delay time	tRAD	15	25	15	30	ns	10
$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ precharge time	tCRP	5		5		ns	
Row address set-up time	tASR	0		0		ns	
Row address hold time	tRAH	10		10		ns	
Column address set-up time	tASC	0		0		ns	
Column address hold time	tCAH	8		10		ns	
Column address to $\overline{\text{RAS}}$ lead time	tRAL	25		30		ns	
Read command set-up time	tRCS	0		0		ns	
Read command hold referenced to $\overline{\text{CAS}}$	tRCH	0		0		ns	8
Read command hold referenced to $\overline{\text{RAS}}$	tRRH	0		0		ns	8
Write command hold time	tWCH	10		10		ns	
Write command pulse width	tWP	10		10		ns	
Write command to $\overline{\text{RAS}}$ lead time	tRWL	13		15		ns	
Write command to $\overline{\text{CAS}}$ lead time	tCWL	8		10		ns	
Data set-up time	tDS	0		0		ns	9
Data hold time	tDH	8		10		ns	9
Refresh period (8K Ref)	tREF		64		64	ms	
Refresh period (4K Ref)	tREF		32		32	ms	
Write command set-up time	tWCS	0		0		ns	7
$\overline{\text{CAS}}$ to $\overline{\text{W}}$ dealy time	tCWD	36		40		ns	7



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## AC CHARACTERISTICS (0°C ≤ T<sub>A</sub> ≤ 70°C, V<sub>CC</sub> = 3.3V ± 0.3V. See notes 1,2.)

Test condition : V<sub>ih</sub>/V<sub>il</sub> = 2.0/0.8V, V<sub>oh</sub>/V<sub>ol</sub> = 2.0/0.8V, Output loading C<sub>L</sub> = 100pF

Parameter	Symbol	-5		-6		Unit	Note
		Min	Max	Min	Max		
$\overline{\text{RAS}}$ to $\overline{\text{W}}$ dealy time	t <sub>RWD</sub>	73		85		ns	7
Column address to $\overline{\text{W}}$ delay time	t <sub>AWD</sub>	48		55		ns	7
$\overline{\text{CAS}}$ precharge to $\overline{\text{W}}$ delay time	t <sub>CPWD</sub>	53		60		ns	
$\overline{\text{CAS}}$ setup time ( $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh)	t <sub>CSR</sub>	5		5		ns	
$\overline{\text{CAS}}$ hold time ( $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh)	t <sub>CHR</sub>	10		10		ns	
$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ precharge time	t <sub>RPC</sub>	5		5		ns	
Access time from $\overline{\text{CAS}}$ precharge	t <sub>CPA</sub>		28		35	ns	3
Hyper page mode cycle time	t <sub>HPC</sub>	25		30		ns	13
Hyper page mode read-modify write cycle	t <sub>HPRWC</sub>	68		77		ns	13
$\overline{\text{CAS}}$ precharge time (Hyper page cycle)	t <sub>CP</sub>	8		10		ns	
$\overline{\text{RAS}}$ pulse width (Hyper page cycle)	t <sub>RASP</sub>	50	200K	60	200K	ns	
$\overline{\text{RAS}}$ hold time from $\overline{\text{CAS}}$ precharge	t <sub>RHCP</sub>	30		35		ns	
$\overline{\text{OE}}$ access time	t <sub>OE A</sub>		13		15	ns	
$\overline{\text{OE}}$ to data delay	t <sub>OE D</sub>	13		15		ns	
Output buffer turn off delay time from $\overline{\text{OE}}$	t <sub>OE Z</sub>	3	13	3	15	ns	7,11
$\overline{\text{OE}}$ command hold time	t <sub>OE H</sub>	13		15		ns	
$\overline{\text{W}}$ to $\overline{\text{RAS}}$ precharge time ( $\overline{\text{C}}$ -B- $\overline{\text{R}}$ refresh)	t <sub>WRP</sub>		10		10	ns	
$\overline{\text{W}}$ to $\overline{\text{RAS}}$ hold time ( $\overline{\text{C}}$ -B- $\overline{\text{R}}$ refresh)	t <sub>WRH</sub>		10		10	ns	
Output data hold time	t <sub>DOH</sub>	5		5		ns	
Output buffer turn off delay from $\overline{\text{RAS}}$	t <sub>REZ</sub>	3	13	3	15	ns	6,11,12
Output buffer turn off delay from $\overline{\text{W}}$	t <sub>WEZ</sub>	3	13	3	15	ns	6,11
$\overline{\text{W}}$ to data delay	t <sub>WED</sub>	15		15		ns	
$\overline{\text{OE}}$ to $\overline{\text{CAS}}$ hold time	t <sub>OE H</sub>	5		5		ns	
$\overline{\text{CAS}}$ hold time to $\overline{\text{OE}}$	t <sub>CHO</sub>	5		5		ns	
$\overline{\text{OE}}$ precharge time	t <sub>OE P</sub>	5		5		ns	
$\overline{\text{W}}$ pulse width	t <sub>WPE</sub>	5		5		ns	

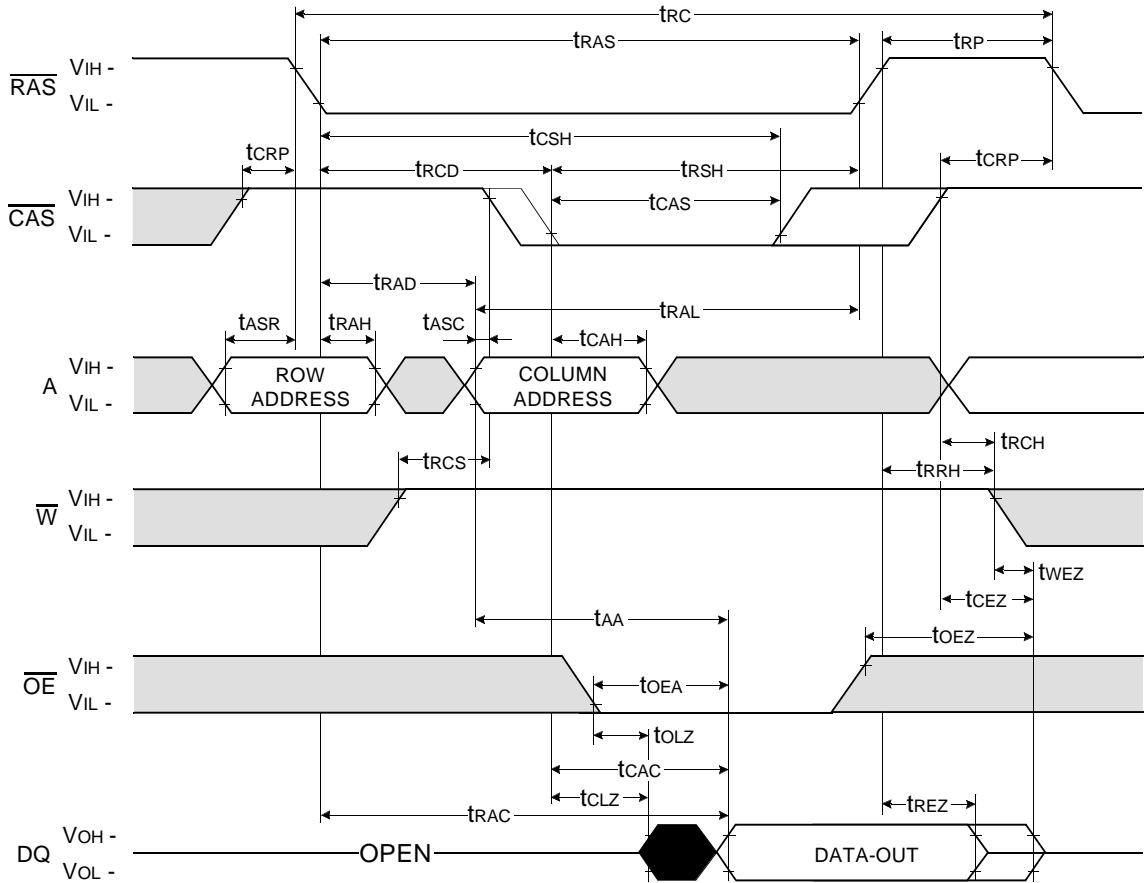


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## NOTES

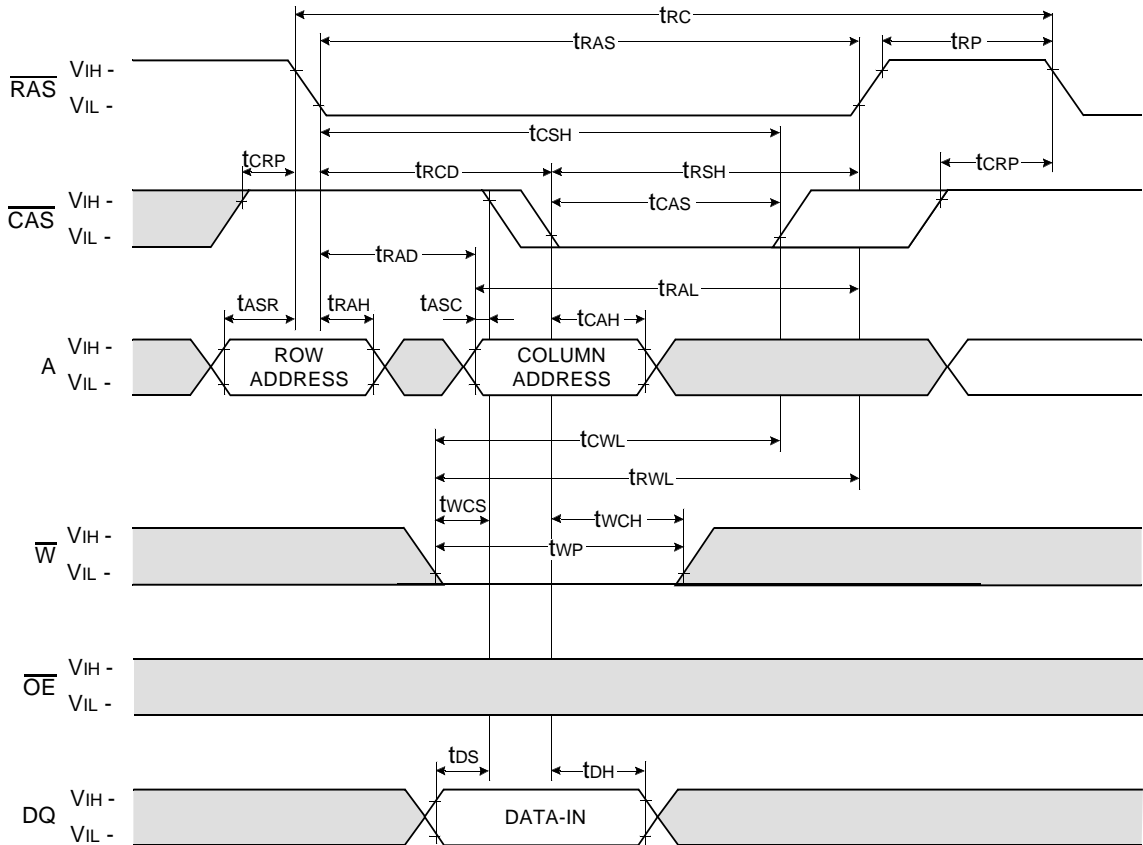
1. An initial pause of 200us is required after power-up followed by any 8 RAS-only or CAS-before-RAS refresh cycles before proper device operation is achieved.
2. Input voltage levels are  $V_{ih}/V_{il}$ .  $V_{IH}(\min)$  and  $V_{IL}(\max)$  are reference levels for measuring timing of input signals. Transition times are measured between  $V_{IH}(\min)$  and  $V_{IL}(\max)$  and are assumed to be 5ns for all inputs.
3. Measured with a load equivalent to 1 TTL loads and 100pF,  $V_{oh}=2.0V$  and  $V_{ol}=0.8V$ .
4. Operation within the  $t_{RCD}(\max)$  limit insures that  $t_{RAC}(\max)$  can be met.  $t_{RCD}(\max)$  is specified as a reference point only. If  $t_{RCD}$  is greater than the specified  $t_{RCD}(\max)$  limit, then access time is controlled exclusively by  $t_{CAC}$ .
5. Assumes that  $t_{RCD} \geq t_{RCD}(\max)$ .
6. This parameter defines the time at which the output achieves the open circuit condition and is not referenced to  $V_{OH}$  or  $V_{OL}$ .
7.  $t_{WCS}$ ,  $t_{RWD}$ ,  $t_{CWD}$  and  $t_{AWD}$  are non-restrictive operating parameter. They are included in the data sheet as electrical characteristics only. If  $t_{WCS} \geq t_{WCS}(\min)$ , the cycle is an early write cycle and the data out pin will remain high impedance for the duration of the cycle.
8. Either  $t_{RCH}$  or  $t_{RRH}$  must be satisfied for a read cycle.
9. These parameters are referenced to the  $\overline{CAS}$  leading edge in early write cycles and to the  $\overline{W}$  leading edge in read-wirte cycles.
10. Operation within the  $t_{RAD}(\max)$  limit insures that  $t_{RAC}(\max)$  can be met.  $t_{RAD}(\max)$  is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}(\max)$  limit, then access time is controlled by  $t_{AA}$ .
11.  $t_{CEZ}(\max)$ ,  $t_{REZ}(\max)$ ,  $t_{WEZ}(\max)$  and  $t_{OEZ}(\max)$  define the time at which the output achieves the open circuit condition and are not referenced to output voltage level.
12. If  $\overline{RAS}$  goes to high before  $\overline{CAS}$  high going, the open circuit condition of the output is achieved by  $\overline{CAS}$  high going. If  $\overline{CAS}$  goes to high before  $\overline{RAS}$  high going, the open circuit condition of the output is achieved by  $\overline{RAS}$  high going.
13.  $t_{ASC} \geq 6ns$

READ CYCLE



WRITE CYCLE ( EARLY WRITE )

NOTE : DOUT = OPEN

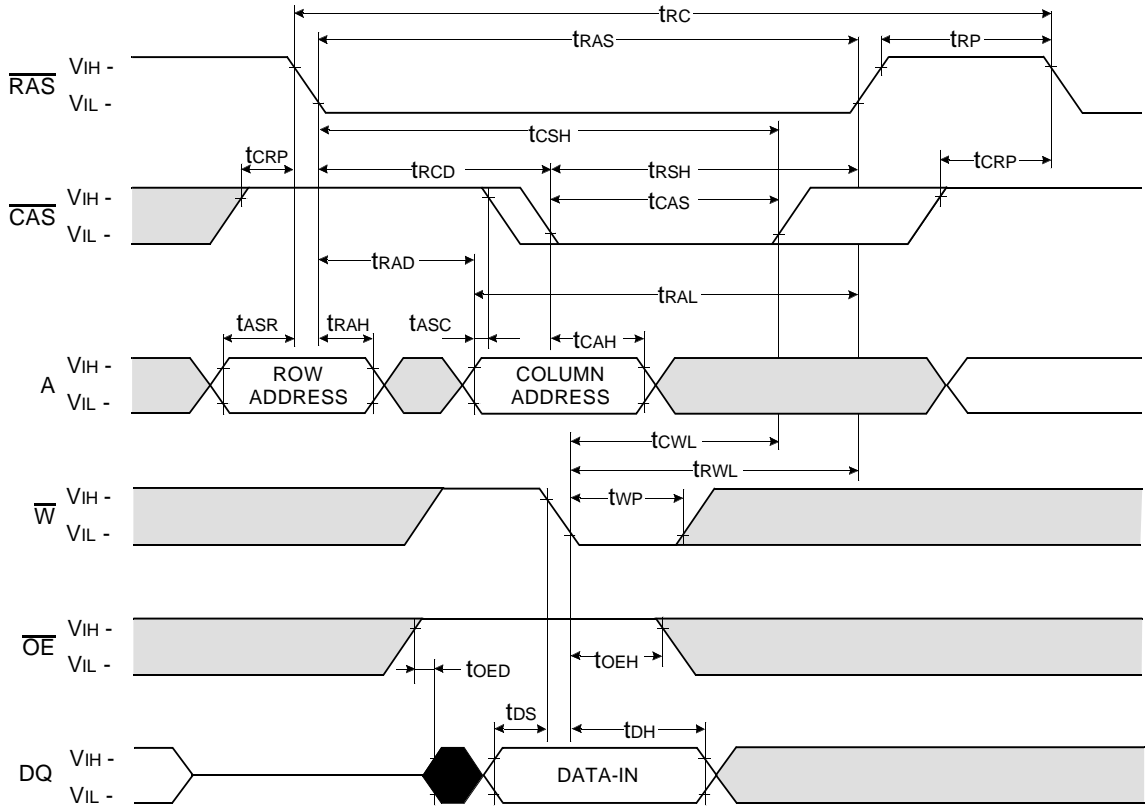


Don't care  
 Undefined



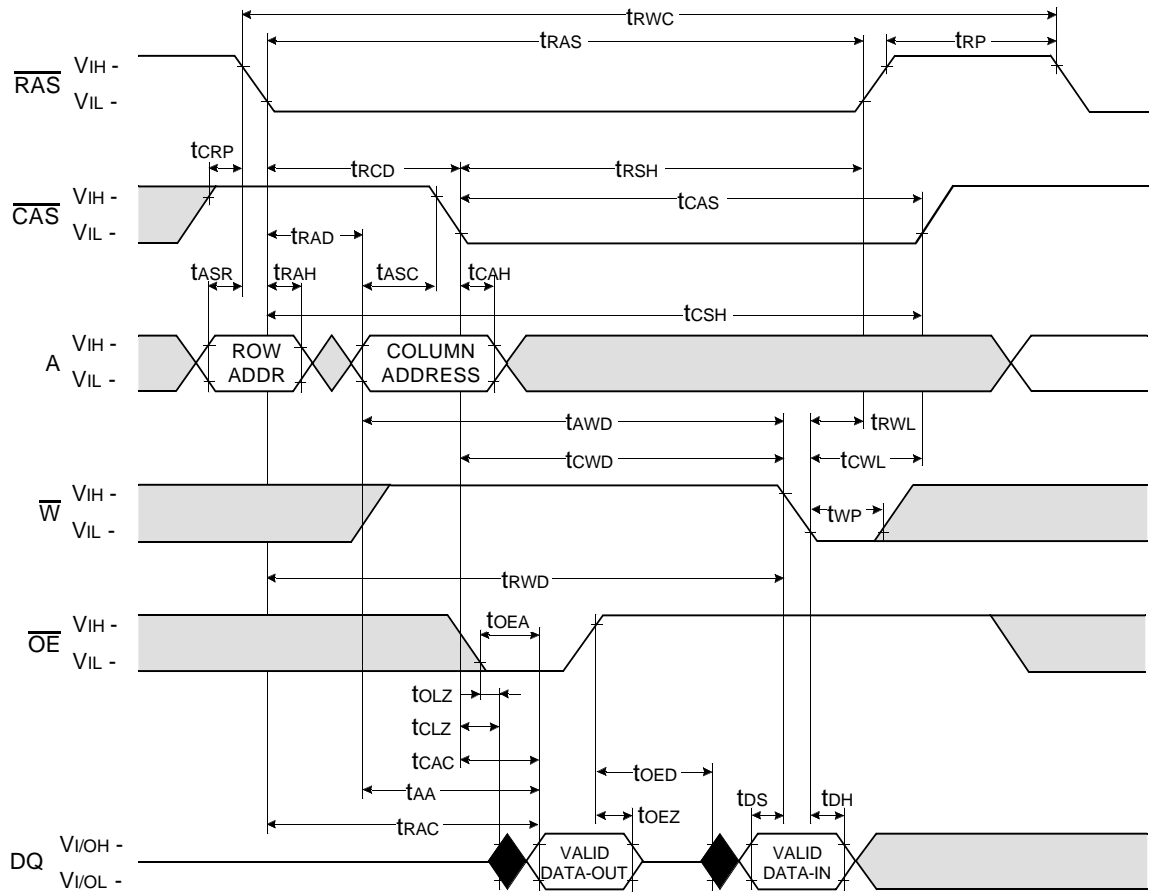
WRITE CYCLE (  $\overline{OE}$  CONTROLLED WRITE )

NOTE : DOUT = OPEN



□ Don't care  
■ Undefined

READ - MODIFY - WRITE CYCLE

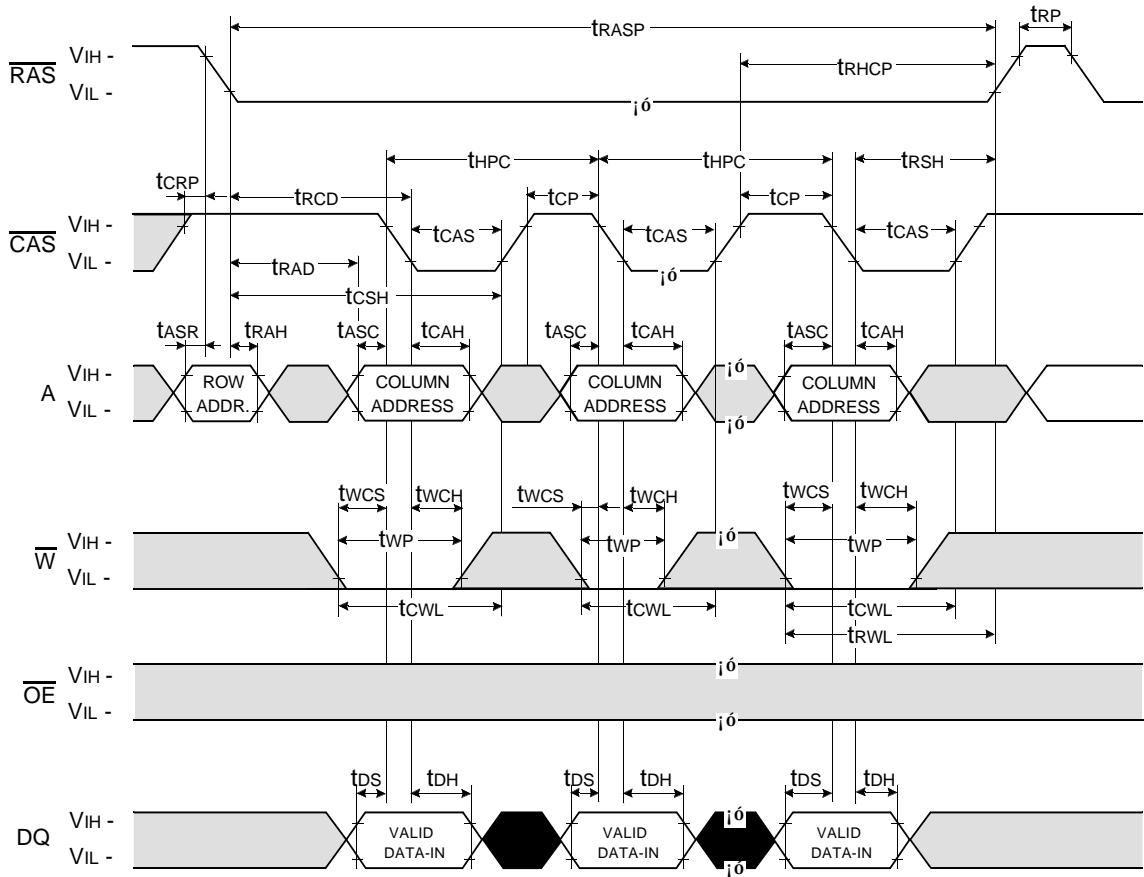


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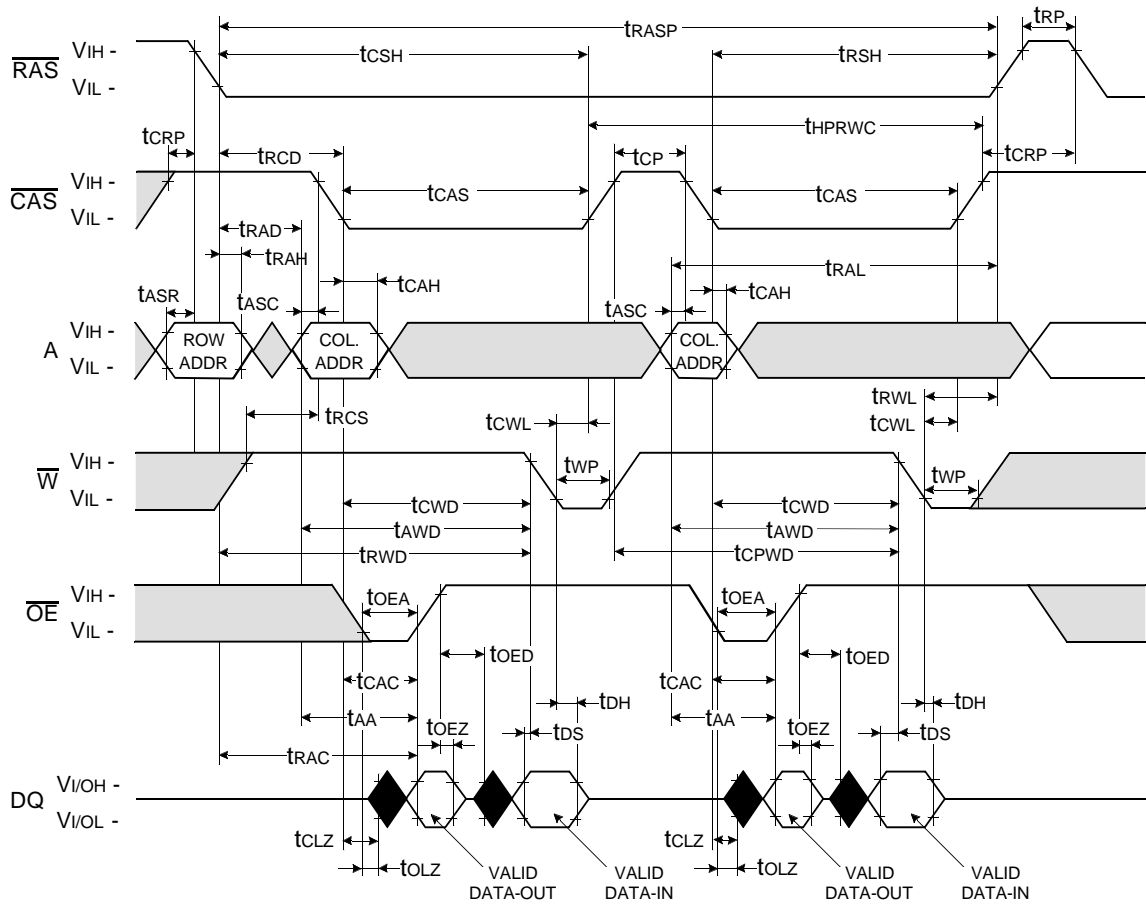
HYPER PAGE WRITE CYCLE ( EARLY WRITE )

NOTE : DOUT = OPEN



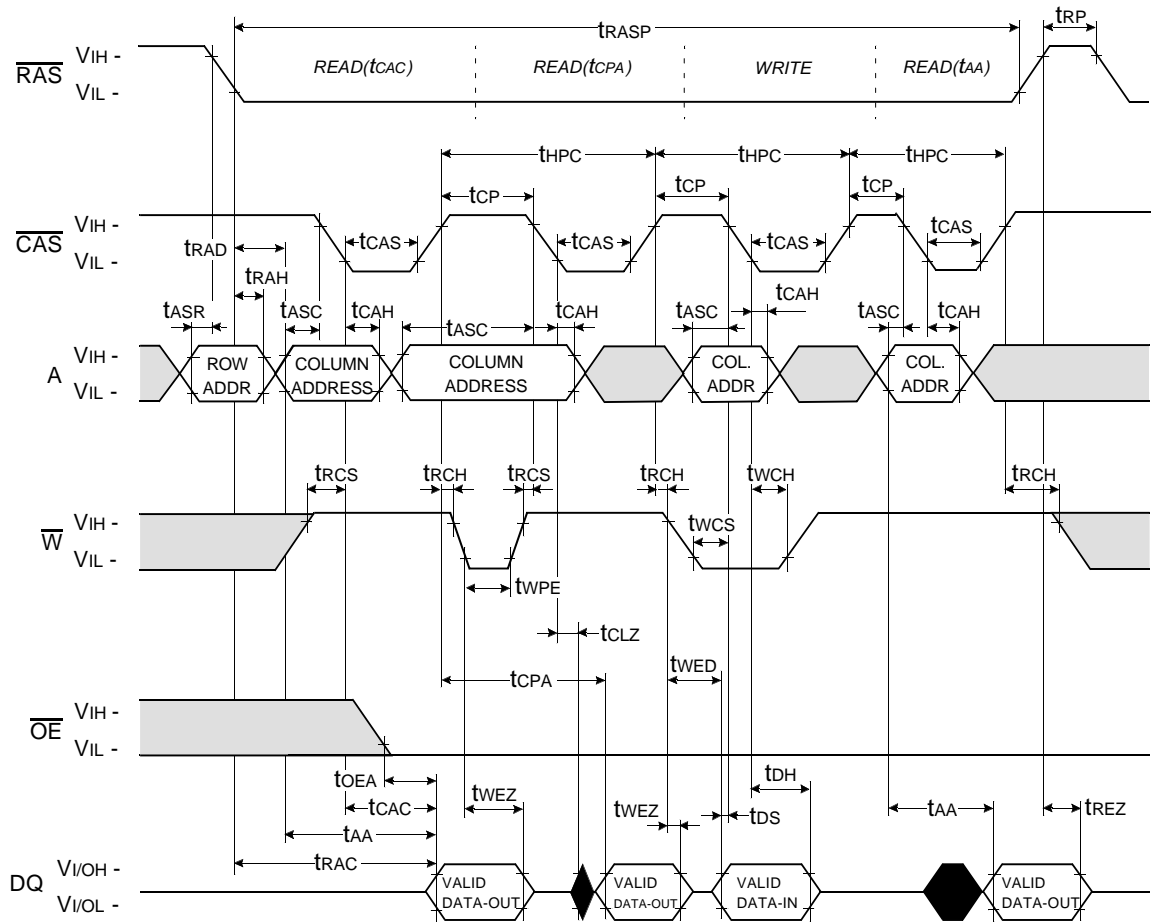
Don't care  
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HYPER PAGE READ-MODIFY-WRITE CYCLE



Don't care  
 Undefined

HYPER PAGE READ AND WRITE MIXED CYCLE

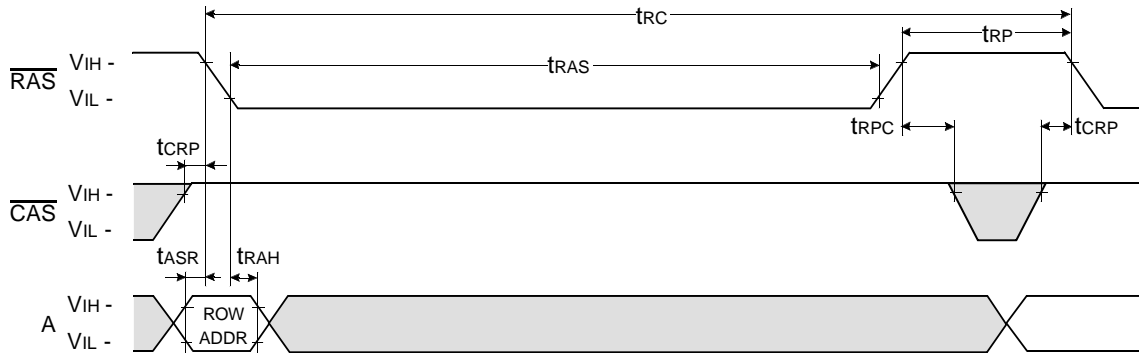


Don't care  
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**$\overline{\text{RAS}}$  - ONLY REFRESH CYCLE\***

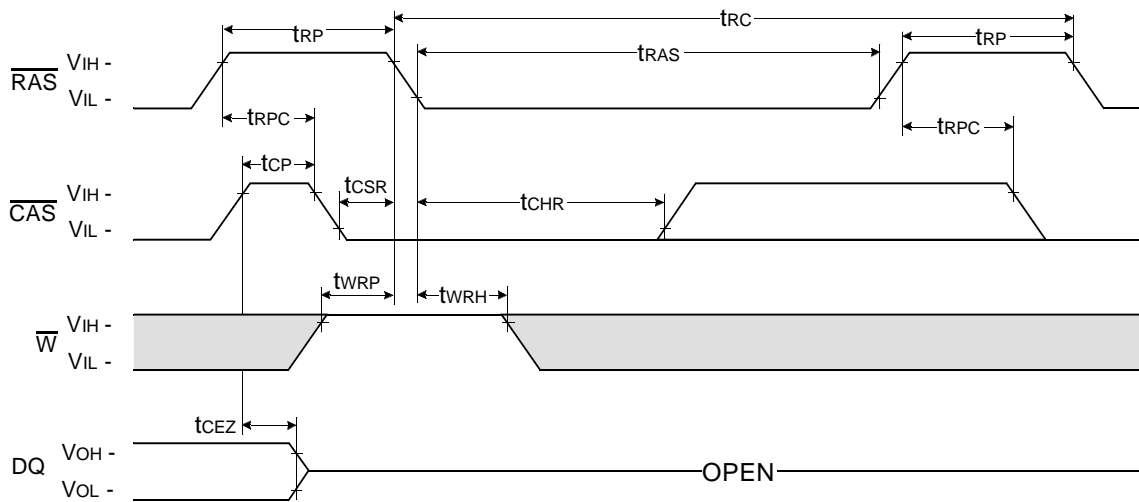
NOTE :  $\overline{\text{W}}$ ,  $\overline{\text{OE}}$ , DIN = Don't care

DOUT = OPEN



**$\overline{\text{CAS}}$  - BEFORE -  $\overline{\text{RAS}}$  REFRESH CYCLE**

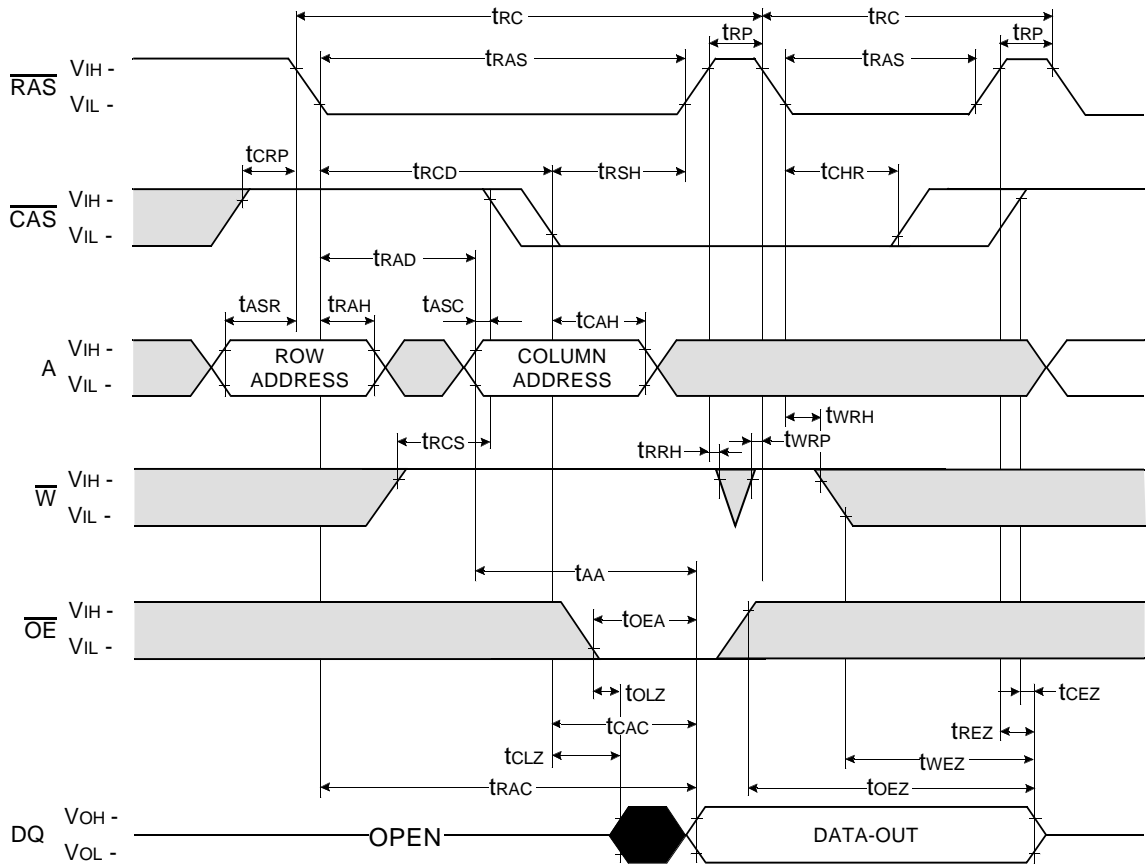
NOTE :  $\overline{\text{OE}}$ , A = Don't care



□ Don't care  
■ Undefined

\* In  $\overline{\text{RAS}}$ -only refresh cycle of 64Mb A-die & B-die, when  $\overline{\text{CAS}}$  signal transits from Low to High, the valid data may be cut off.

HIDDEN REFRESH CYCLE ( READ )

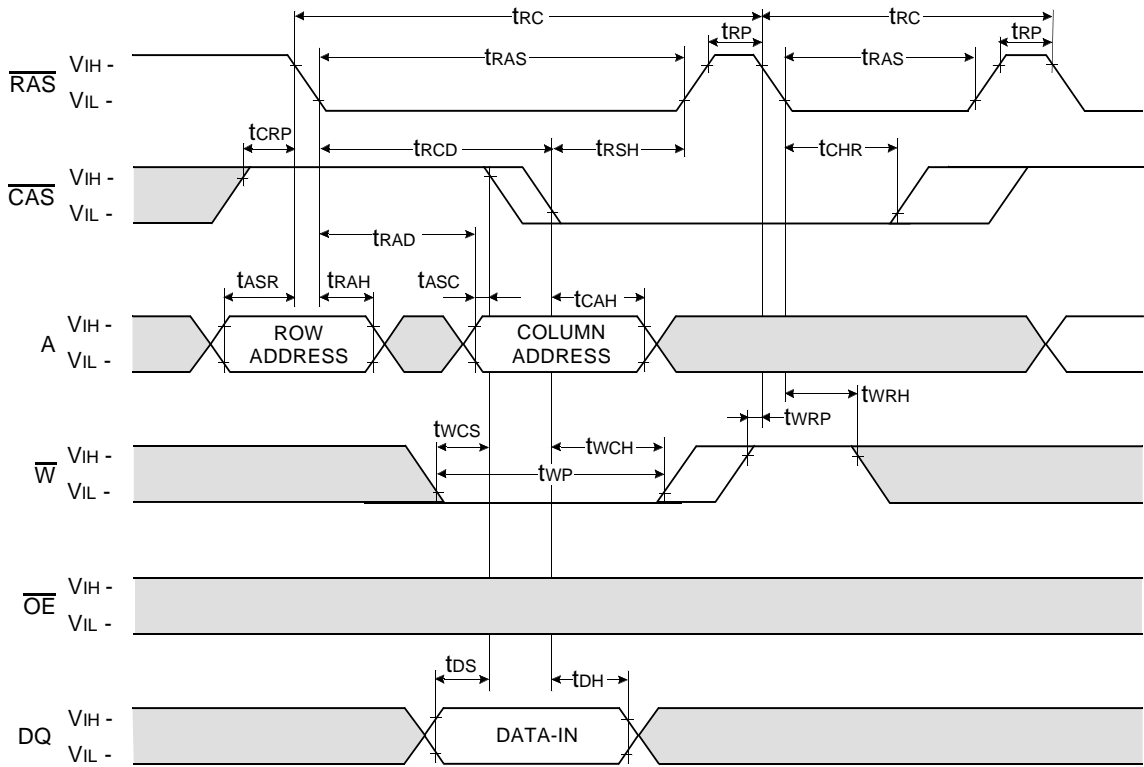


Don't care  
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## HIDDEN REFRESH CYCLE ( WRITE )

NOTE : DOUT = OPEN

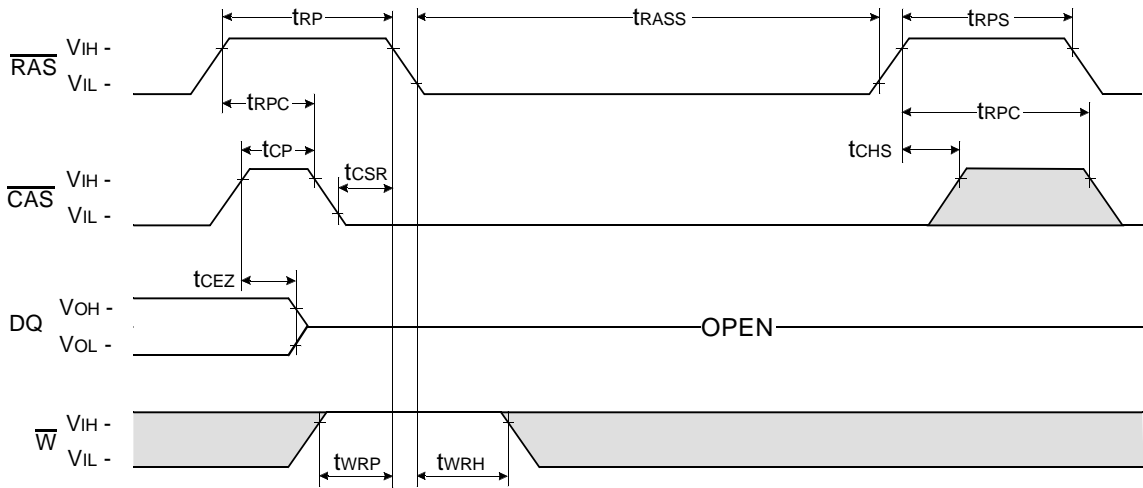


Don't care  
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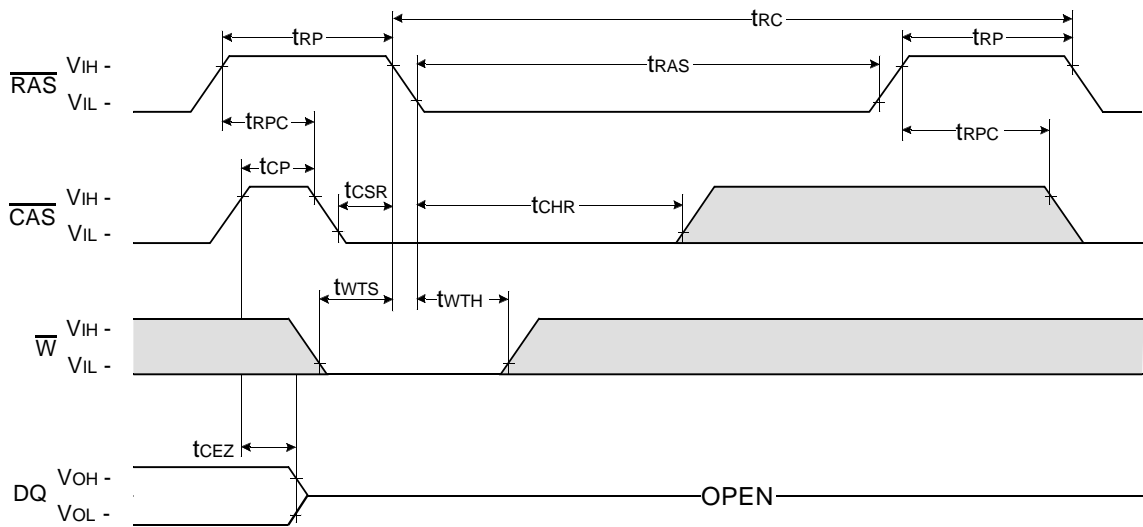
**CAS - BEFORE - RAS SELF REFRESH CYCLE**

NOTE :  $\overline{OE}$ , A = Don't care



**TEST MODE IN CYCLE**

NOTE :  $\overline{OE}$ , A = Don't care



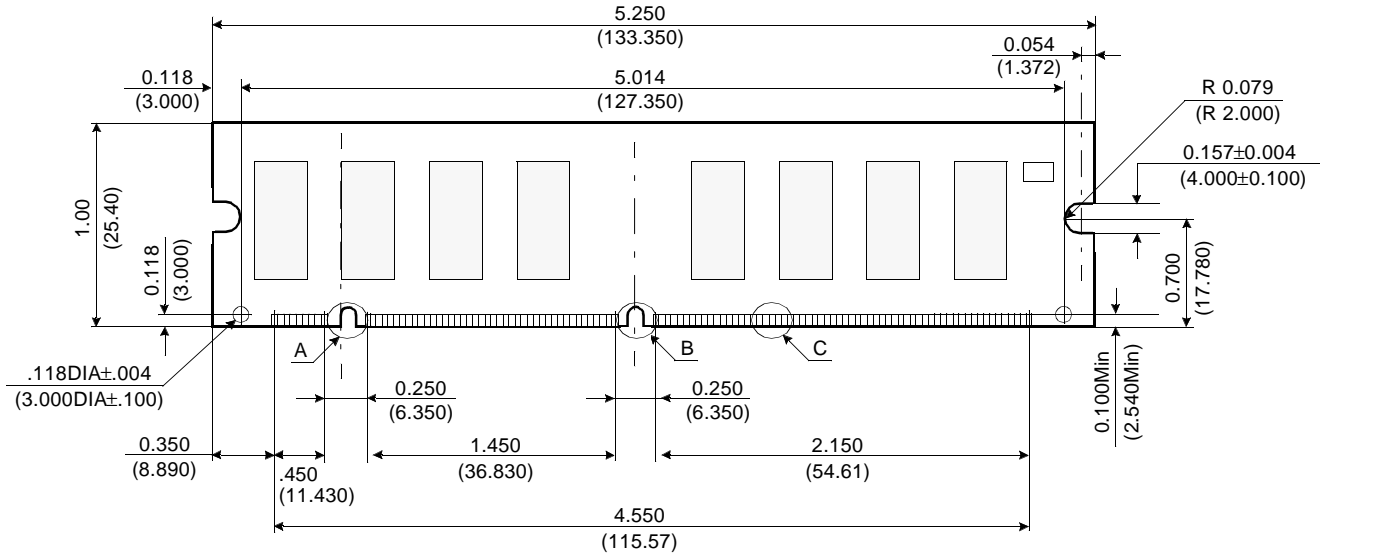
□ Don't care  
■ Undefined

# DRAM MODULE

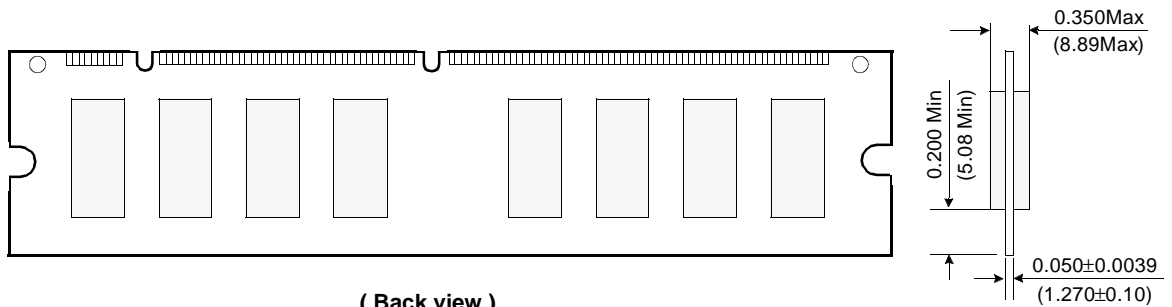
**KMM366F400CK1**  
**KMM366F410CK1**

## PACKAGE DIMENSIONS

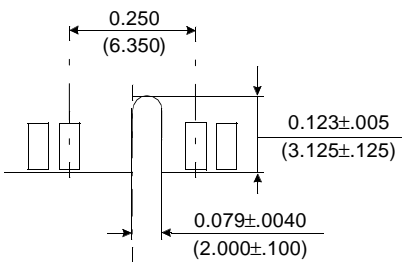
Units : Inches (millimeters)



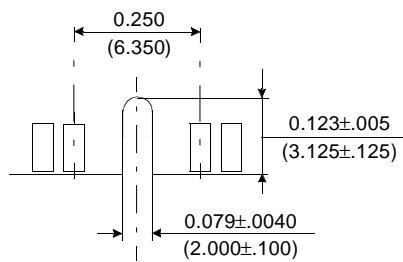
( Front view )



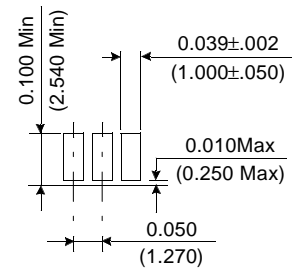
( Back view )



Detail A



Detail B



Detail C

Tolerances : ±.005(.13) unless otherwise specified

The used device is 4Mx4 DRAM with EDO mode, SOJ  
DRAM Part No. : KMM366F400CK1 - KM44V4004CK  
KMM366F410CK1 - KM44V4104CK

Revision History

Rev 0.0 : Aug. 1997