

October 1993

## DESCRIPTION

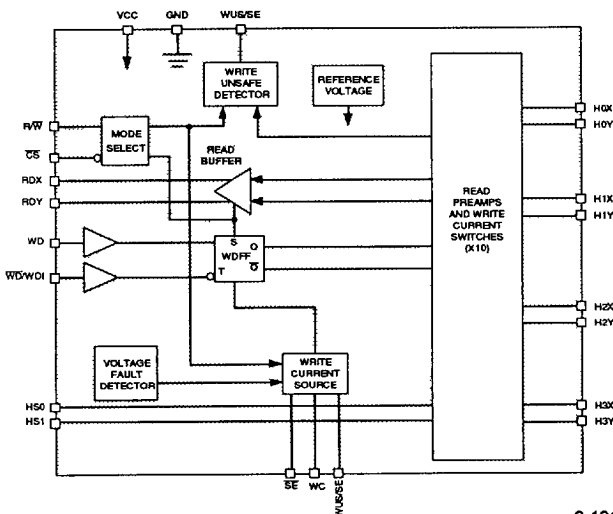
The SSI 32R2063R/64R/65R are Bipolar monolithic integrated circuits designed for use with two-terminal recording heads. They provide a low noise read amplifier, write current control, and data protection circuitry for up to four channels. The SSI 32R2063R option provides internal 350Ω damping resistors. Damping resistors are switched in during Write mode and switched out during Read mode. The SSI 32R2063/64/65 option does not provide a damping resistor. Power supply fault protection is provided by disabling the write current generator during power sequencing. System write to read recovery time is significantly improved by making the read channel outputs high impedance. The device also offers multiple channel "servo bank write" capability to assist in servo writing operations. Servo write is selected either with a TTL input (32R2063R/32R2064R) or with the WUS/SE pin (32R2065R).

The SSI 32R2063R/64R/65R require only a +5.0V power supply and are available in a variety of packages and gain options.

## FEATURES

- **+5V ±10% supply**
- **Low power**
  - PD = 120 mW Read mode (Nom)
  - PD = 7 mW Idle (Max)
- **High Performance:**
  - Read mode gain = (U) 150, (W) 250 V/V
  - Input noise = 0.56 nV/√Hz (Nom)
  - Input capacitance = 16 pF (Nom)
  - Write current range = 1-35 mA
  - Max write current rise/fall time = 15 nsec (typical head)
  - Head voltage swing = 3.4 Vpp min
- **Servo bank-write capability**
- **Self switching damping resistance**
- **Write unsafe detection**
- **Power supply fault protection**
- **Head short to ground protection**
- **Differential ECL-like (32R2063R) or TTL (32R2064R, 32R2065R) write data inputs**

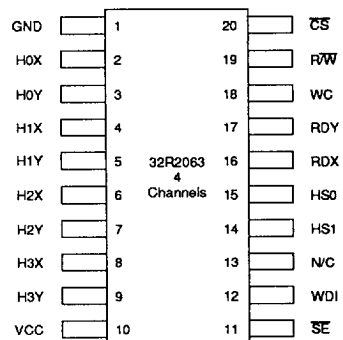
## BLOCK DIAGRAM



1093 - rev.

3-101

## PIN DIAGRAM



**20-Lead SOL, VSOP**

**CAUTION:** Use handling procedures necessary for a static sensitive component.

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# SSI 32R2063R/64R/65R

## 5V, 4-Channel Thin Film

### Read/Write Device

#### CIRCUIT OPERATION

The SSI 32R2063R/64R/65R has the ability to address up to 4 two-terminal heads and provide write drive or read amplification. Mode control and head selection are described in Tables 1 and 2. The TTL inputs R/W,  $\overline{CS}$  and  $\overline{SE}$  have internal pull-up resistors to prevent an accidental write condition. HS0 and HS1 have internal pulldown(W)/Internal pull up (U) resistors. Internal clamp circuitry will protect the IC from a head short to ground condition in any mode.

**TABLE 1a: Mode Select (32R2063R, 32R2064R)**

$\overline{CS}$	R/W	$\overline{SE}$	Mode
0	0	1	Single Channel Write. See Table 2.
0	0	0	Servo Write Channels 0, 1, 2, 3
0	1	X	Single Channel Read. See Table 2.
1	X	X	Idle.

**TABLE 1b: Mode Select (32R2065R)**

$\overline{CS}$	R/W	WUS/SE	Mode
0	0	*	Single Channel Write. See Table 2.
0	0	Vcc+1.5*	Servo Write Channels 0, 1, 2, 3
0	1	X	Single Channel Read. See Table 2.
1	X	X	Idle.

\*WUS/SE functions as WUS in Write Mode unless it is pulled above Vcc.

**TABLE 2: Head Select**

HS1	HS0	Head
0	0	0
0	1	1
1	0	2
1	1	3

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#### WRITE MODE

Taking both  $\overline{CS}$  and  $R/\overline{W}$  low selects Write mode which configures the SSI 32R2063R/64R/65R as a current switch and activates the Write Unsafe (WUS) detector circuitry. On the 32R2063R, head current is toggled between the X and Y side of the selected head on each low to high transition of  $WD/\overline{WD}$ . On the 32R2064R/65R, head current is toggled between the X and Y side of the selected head on each high to low transition of the Write Data Input (WDI). Note that a preceding Read to Write transition or Idle to Write transition initializes the Write Data Flip-Flop to pass write current into the "X" side of the device. In this case, the Y side is higher potential than the X side. The magnitude of the write current (0-pk) is given by:

$$I_w = A_w \cdot \frac{V_{wc}}{R_{wc}} = K/R_{wc}$$

where  $A_w$  is the write current gain.

$R_{wc}$  is connected from pin WC to GND. Note the actual head current  $I_x, y$  is given by:

$$I_x, y = \frac{I_w}{1 + R_h/R_d}$$

Where:

$R_h$  = Head resistance plus external wire resistance

$R_d$  = Damping resistance

In Write mode a  $350\Omega$  damping resistor is switched in across the Hx, Hy ports (32R2063R/64R/65R). The unselected head potential is kept at ground.

#### SERVO WRITE MODE

Taking  $\overline{SE}$  low and  $R/\overline{W}$  low (32R2063R/64R) or taking  $WUS/SE$  to  $V_{cc}+1.5$  (32R2065R) activates Servo Write mode. This mode allows for writing to multiple channels at once, which is useful during servo formatting. In this mode, the write driver will drive channels 0, 1, 2, and 3 simultaneously.

#### POWER SUPPLY FAULT PROTECTION

A voltage fault detection circuit improves data security by disabling the write current generator during a voltage fault or power startup regardless of mode. Note that WUS does not necessarily turn on to flag a power supply fault condition.

#### HEAD SHORT TO GROUND PROTECTION

The SSI 32R2063R/64R/65R provides a head short to ground protection circuit in any mode. In Idle or Read Mode, current out of the head port will not exceed 20 mA if any head is shorted to ground. In Write mode, if any head is shorted to ground (regardless if it is selected or not) the write current generator will turn off, the WUS flag will go high, and current will be limited to less than 1 mA out of the head port.

#### WRITE UNSAFE

Any of the following conditions will be indicated as a high level on the Write Unsafe, WUS, open collector output.

- WDI frequency too low
- Device in Read mode
- Device not selected
- Device in Servo Write mode
- No head current
- Open head
- Head short to ground

**WDI frequency too low** is detected if the WDI frequency falls below 1.67 MHz (typ). Consult the WUS Safe to Unsafe timing for range of frequency detection.

**Device in Read mode, Device in servo Write mode and Chip disabled** will flag WUS if  $R/\overline{W}$  is high, if  $SE$  is high, or  $\overline{CS}$  is high.

**No head current** will flag WUS if  $R_{wc} = \infty$  and the selected head is present.

**Head opened** will flag WUS if  $R_h = \infty$

# SSI 32R2063R/64R/65R

## 5V, 4-Channel Thin Film

### Read/Write Device

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**Head short to ground** is described in the preceding paragraph.

Upon entering Write mode, WUS is valid after two low to high transitions of  $\overline{WD}$  (32R2063R), or two high to low transitions of WDI (32R2064R/65R) following the required Read-Write transition time (0.6  $\mu$ s max).

After the fault condition is removed, two positive transitions of  $\overline{WD}$  (32R2063R), or two negative transitions of WDI (32R2064R/65R) are required to clear WUS.

#### READ MODE

The Read mode configures the devices as a low noise differential amplifier and deactivates the write current generator. The damping resistor is switched out of the circuit allowing a high impedance input to the read amplifier. The RDX and RDY output are driven by

emitter followers. They should be AC coupled to the load. The HnX, HnY inputs are non-inverting to the RDX, RDY outputs.

Note that in Idle or Write mode, the read amplifier is deactivated and RDX, RDY outputs become high impedance. This facilitates multiple R/W applications (wired-OR RDX, RDY) and minimizes voltage change when switching from Write to Read mode. Note also that the write current source is deactivated for both the Read and Idle mode. The unselected head potential is kept at ground.

#### IDLE MODE

Taking  $\overline{CS}$  high selects the Idle mode which switches the RDX and RDY outputs into a high impedance state and deactivates the device. Power consumption in this mode is held to a minimum. The head potential is kept at ground.

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## 5V, 4-Channel Thin Film

### Read/Write Device

#### PIN DESCRIPTION

##### CONTROL/STATUS

NAME	TYPE	DESCRIPTION
$\overline{CS}$	I	Chip Select Input. A logical low level enables the device.
$R/\overline{W}\dagger$	I	Read/Write. A logical high level enables Read mode. A logical low level enables Write mode.
$\overline{SE}$	I	Servo Enable. A low level enables servo bank Write mode. See Servo Enable section (32R2063R, 32R2064R).
HS0,HS1	I	Head Select. Decoded address selects one of 4 channels. See Table 2.
WUS $\dagger$	O	Write Unsafe. A high level indicates an unsafe writing condition. See WUS section (32R2064R).
WUS/ $\overline{SE}\dagger$	I/O	Write Unsafe/Servo Enable. When in Servo Bank Write mode, pulling this pin above Vcc enables servo bank write. See Servo Enable section. Otherwise, a high level indicates an unsafe writing condition. See WUS section (32R2065R).
WC	I	Write Current. Sets the write current through the recording head.

##### HEAD TERMINAL CONNECTIONS

H0X-H3X H0Y-H3Y	I	X,Y Head Connections
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##### DATA INPUT/OUTPUT

WDI $\dagger$	I	Write Data In. A negative transition of WDI changes the direction of current in the recording head (32R2064R, 32R2065R).
WD, $\overline{WD}\dagger$	I	Differential Write Data In. A positive transition of WD- $\overline{WD}$ changes the direction of current in the recording head (32R2063R).
RDX,RDY $\dagger$	O	Differential Read Data Out. Emitter follower output.

##### POWER

VCC	I	+5 V power supply
GND	I	Ground

$\dagger$  When more than one Read/Write device is used, signals can be wire OR'ed.

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### Read/Write Device

#### ELECTRICAL SPECIFICATIONS

Current maximums are currents with the highest absolute value

#### ABSOLUTE MAXIMUM RATINGS

Operation beyond the maximum ratings may damage the device.

PARAMETER		RATING
DC Supply Voltage	VCC	-0.3 to 7V
Write Current*	I <sub>w</sub>	60 mA
Digital Input Voltage	V <sub>in</sub>	-0.3 to VCC+0.3V
Head Port Voltage	V <sub>H</sub>	-0.3 to VCC+0.3V
WUS Pin Voltage	V <sub>wus</sub>	VCC+0.3V
Output Current	RDX,RDY	I <sub>o</sub>
	WUS	I <sub>wus</sub>
Junction Operating Temperature		+135°C
Storage Temperature		-65 to +150°C

#### RECOMMENDED OPERATING CONDITIONS

PARAMETER		CONDITIONS
DC Supply Voltage	VCC	5 ± 10%V
Ambient Operating Temperature		0° < T <sub>a</sub> < 75°C

#### TEST CONDITIONS

Recommended operating conditions apply.

PARAMETER	CONDITIONS
Write Current, I <sub>w</sub>	1-35 mA
Head Inductance, L <sub>h</sub>	1 μH
Head Resistance, R <sub>h</sub>	30Ω
WD Frequency	5 MHz
WD, $\overline{\text{WD}}$ rise/fall time (32R2063R)	1ns
WDI rise/fall time (32R2064R/2065R)	1 ns

\*Maximum servo write current or ambient temperature needs to be regulated to prevent the junction temperature from exceeding 135°C.

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### Read/Write Device

#### POWER DISSIPATION

Recommended operating conditions apply.

PARAMETER	CONDITIONS	MIN	NOM	MAX	UNIT
VCC Supply Current	Read Mode (U)		24	32	mA
	(W)		28	38.2	mA
	Write Mode Single Channel		(28+lw)	(39+lw)	mA
	Servo Write		(61+4lw)	(83+4lw)	mA
	Idle Mode		0.7	1.1	mA
Power Dissipation	Read Mode		140	209	mW
	Write Mode Single Channel		(140+5.3 lw)	(210+6 lw)	mW
	Servo Write		(305+20 lw)	(450+22.5 lw)	mW
	Idle Mode		4	7	mW

#### DIGITAL INPUTS

Input High Voltage HSX, CS/, R/W, SE, WDI	Vih		2.0			VDC
Input Low Voltage HSX, CS/, R/W, SE, WDI	Vil				0.8	VDC
Input High Current HSX, CS/, R/W, SE, WDI	Iih	Vih = 2.0V			100	μA
Input Low Current HSX, CS/, R/W, SE, WDI	Iil	Vil = 0.8V	-0.4			mA
WD, WD/ Input High Voltage	Vih		Vcc-1.0		Vcc-0.5	VDC
WD, WD/ Input Low Voltage	Vil		Vih-2.5		Vih-1.0	VDC
WD-WD/ Input Voltage Difference		0.5	0.5	1.0	1.5	V
WD,WD/ Input High Current		Vih = Vcc-0.75V		85	120	μA
WD,WD/ Input Low Current		Vih = Vcc-1.75V		65	100	μA
WUS Output Low Voltage	Vol	Iol = 2 mA max		0.35	0.5	VDC

# SSI 32R2063R/64R/65R

## 5V, 4-Channel Thin Film

### Read/Write Device

#### ELECTRICAL SPECIFICATIONS (continued)

##### WRITE CHARACTERISTICS

Test conditions apply unless otherwise specified.

PARAMETER	CONDITIONS	MIN	NOM	MAX	UNIT
Write Current Voltage $V_{wc}$		2.4	2.5	2.6	V
Write Current Gain $A_w$	$I_w = A_w \cdot V_{wc} / R_{wc}$		20		V
Write Current Constant "K"	$I_w = K / R_{wc}$	48.5	50	51.5	V
Differential Head Voltage Swing	$I_w = 20 \text{ mA}$	4.2	3.6		V <sub>pp</sub>
	Open Head, $I_w = 20 \text{ mA}$	3.4	5.0		V <sub>pp</sub>
Head Differential Load Resistance $R_d$	32R2063R/64R/65R	310	350	390	$\Omega$
	32R2063	2400	3000	3600	$\Omega$
WD Pulse Width (Write mode)	PWH	5			ns
	PWL	10			ns
WD Pulse Width (Servo Write)	PWH	5			ns
	PWL	20			ns
WD, $\overline{WD}$ Pulse Width (Write, Servo Write) 32R2063R	PWH	5			ns
	PWL	5			ns
Head Current $H_{nX}, H_{nY}$		-200		200	$\mu\text{A}$
Unselected Head Voltage				0.3	VDC
Unselected Head Current	DC			100	$\mu\text{A}$
VCC Fault Voltage	$I_w \leq 0.2 \text{ mA}$	3.5	4.0	4.2	V

##### SERVO WRITE CHARACTERISTICS

Write Current Range		5		25	mA
Write Current Matching	Between channels		$\pm 10\%$		
WUS/SE Input Voltage	Servo bank write enabled (32R2065R)	$V_{cc} + 1.5$			V



# SSI 32R2063R/64R/65R

## 5V, 4-Channel Thin Film

### Read/Write Device

#### READ CHARACTERISTICS

Test conditions apply unless otherwise specified.  $CL (RDX, RDY) < 20 \text{ pF}$ ,  $RL (RDX, RDY) = 1 \text{ k}\Omega$ .

PARAMETER	CONDITIONS	MIN	NOM	MAX	UNIT
Differential Voltage Gain	$V_{in} = 1 \text{ mVpp}$ (U)	110	150	190	V/V
	@1 MHz (W)	200	250	300	V/V
Voltage BW	-1dB $ Z_s  < 5\Omega$ , $V_{in} = 1 \text{ mVpp}$	20	35		MHz
	-3dB	45	70		MHz
Input Noise Voltage	BW = 15 MHz, $L_h = 0$ , $R_h = 0$		0.56	0.75	nV/ $\sqrt{\text{Hz}}$
Input Noise Current			3		pA/ $\sqrt{\text{Hz}}$
Differential Input Capacitance	$V_{in} = 1 \text{ mVpp}$ , $f = 5 \text{ MHz}$		16	22	pF
Differential Input Resistance	$V_{in} = 1 \text{ mVpp}$ , $f = 5 \text{ MHz}$ 32R2063/64/65	720	1200		$\Omega$
Dynamic Range	AC input voltage where gain falls to 90% of its small signal gain value, $f = 5 \text{ MHz}$	2	5		mVpp
Common Mode Rejection Ratio	$V_{in} = 0 \text{ VDC} + 100 \text{ mVpp}$ @ 5 MHz	55			dB
Power Supply Rejection Ratio	100 mVpp @ 5 MHz on VCC	50			dB
Channel Separation	Unselected channels driven with $V_{in} = 0 \text{ VDC} + 100 \text{ mVpp}$	50			dB
Output Offset Voltage	Shorted head (U) 150 Av	-200		+200	mV
	(W) 250 Av	-300		+300	mV
Single Ended Output Resistance	$f = 5 \text{ MHz}$		25	50	$\Omega$
Output Current	AC coupled load, RDX to RDY	0.9	1.4		mA
RDX, RDY Common Mode Output Voltage		$0.4 \cdot V_{CC}$	$0.5 \cdot V_{CC}$	$0.6 \cdot V_{CC}$	VDC

# SSI 32R2063R/64R/65R

## 5V, 4-Channel Thin Film

### Read/Write Device

#### ELECTRICAL SPECIFICATIONS (continued)

##### SWITCHING CHARACTERISTICS

Test conditions apply unless otherwise specified.

PARAMETER		CONDITIONS	MIN	NOM	MAX	UNIT
R/W	Read to Write	R/W to 90% of write current U		0.1	0.3	$\mu$ s
		W		0.2	0.6	$\mu$ s
	Read to Write	Rh = 10 $\Omega$ , Lh = 1.5 $\mu$ H Iw = 10 mA		0.07	0.15	$\mu$ s
	Write to Read	R/W to 90% of 100 mV Read signal envelope		0.1	0.6	$\mu$ s
CS	Unselect to Select	CS to 90% of 100 mV 10 MHz Read signal envelope		0.4	1	$\mu$ s
	Select to Unselect	CS to 10% of write current		0.4	1	$\mu$ s
HS0,1 to any Head		To 90% of 100 mV 10 MHz Read signal envelope		0.2	0.6	$\mu$ s
WUS	Safe to Unsafe (TD1)	Write mode, loss of WD transitions; Defines max WD period for WUS operation	0.6	2.0	3.6	$\mu$ s
	Unsafe to Safe (TD2)	Fault cleared: from second WD transition		0.2	1.0	$\mu$ s
WDI	Frequency Range	Valid WUS	1.67		25	MHz
Head Current		Lh = 0, Rh = 0				
	WDI to Ix - Iy (TD3)	from 50% points		3	10	ns
	Asymmetry	WDI has 1 ns rise/fall time			1.0	ns
	Rise/fall Time	10% to 90% points Iw = 15 mA, Rh = 0, Lh = 0		4	6	ns
		Iw = 15 mA, Rh = 30 $\Omega$ , Lh = 1 $\mu$ H			15	ns

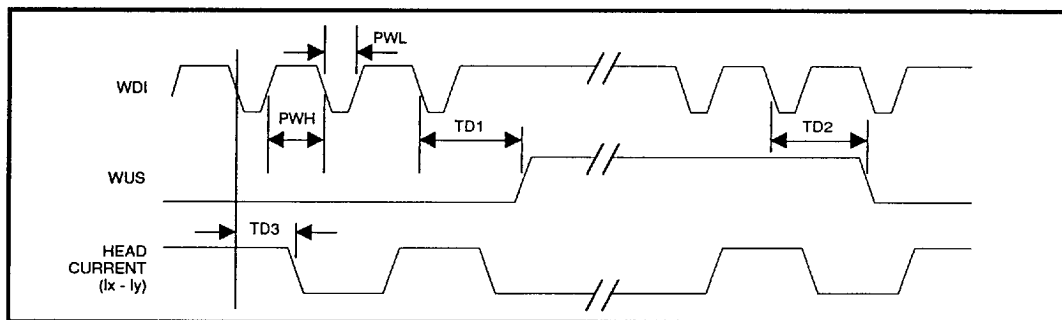


FIGURE 1a: Write Mode Timing Diagram 32R2064R, 32R2065R

# SSI 32R2063R/64R/65R

## 5V, 4-Channel Thin Film

### Read/Write Device

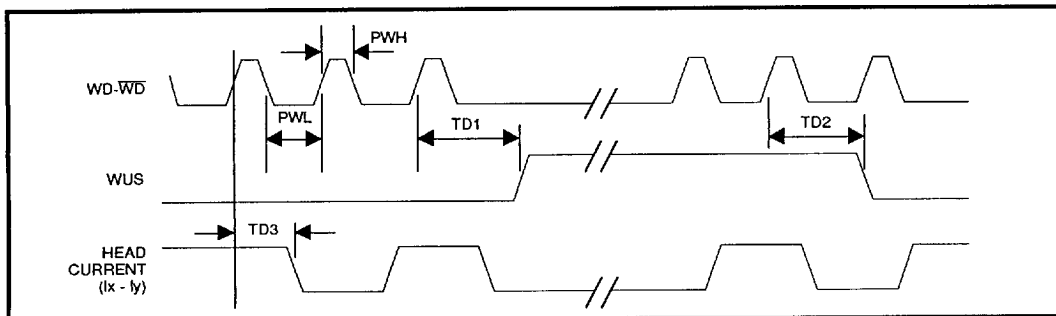


FIGURE 1b: Write Mode Timing Diagram 32R2063R

### PACKAGE LEAD DESIGNATION

(Top View)

CAUTION: Use handling procedures necessary for a static sensitive component.

GND	1	20	CS	GND	1	20	SE	GND	1	20	SE
H0X	2	19	R/W	H0X	2	19	R/W	H0X	2	19	R/W
H0Y	3	18	WC	H0Y	3	18	WC	H0Y	3	18	WC
H1X	4	17	RDY	H1X	4	17	RDY	H1X	4	17	RDY
H1Y	5	16	RDX	H1Y	5	16	RDX	H1Y	5	16	RDX
H2X	6	15	HS0	H2X	6	15	HS0	H2X	6	15	HS0
H2Y	7	14	HS1	H2Y	7	14	HS1	H2Y	7	14	HS1
H3X	8	13	N/C	H3X	8	13	VCC	H3X	8	13	VCC
H3Y	9	12	WDI	H3Y	9	12	WDI	H3Y	9	12	WDI
VCC	10	11	SE	VCC	10	11	WUS	VCC	10	11	WUS/SE

20-Lead SOL, VSOP

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