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Renesas Technology Corp.  
Customer Support Dept.  
April 1, 2003

# M16C

## Pulse Period/Width Measurement on the M16C/62

### 1. Abstract

Measuring the frequency ( $1/\text{period}$ ) or the pulse width of an input signal is useful in applications such as tachometers, DC motor control, power usage calculations, and so on. The following article describes how to use timer B to measure the period and pulse width of an input waveform, referred to as 'Pulse Period/Pulse Width Measurement Mode'.

### 2. Introduction

The Mitsubishi M16C/62 is a 16-bit MCU, based on the M16C CPU core, with an impressive list of features including 10-bit A/D, D/A, UARTS, timers, DMA, etc., and up to 256k bytes of user flash. The MCU has 6 B timers and all 6 timers can operate in Pulse Period/Pulse Width Measurement Mode.

Timer B has the following additional modes of operation:

- Timer Mode
- Event Counter Mode

Figure 1 illustrates the operation of timer B. The remainder of this article focuses on setting up timer B0 to measure pulse width, and timer B1 to measure pulse period.

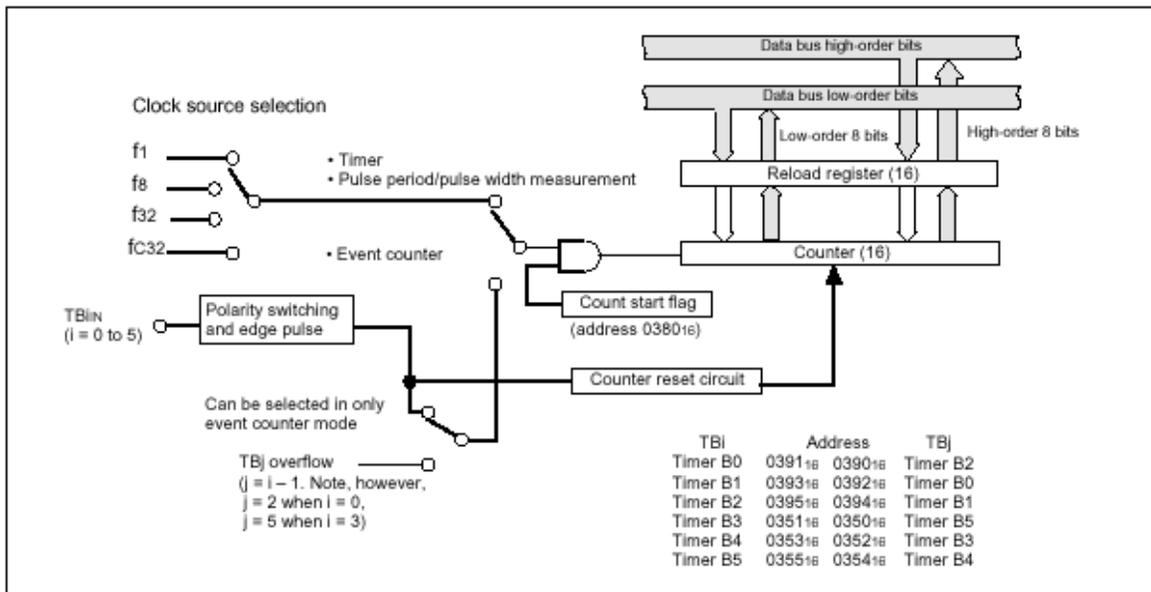


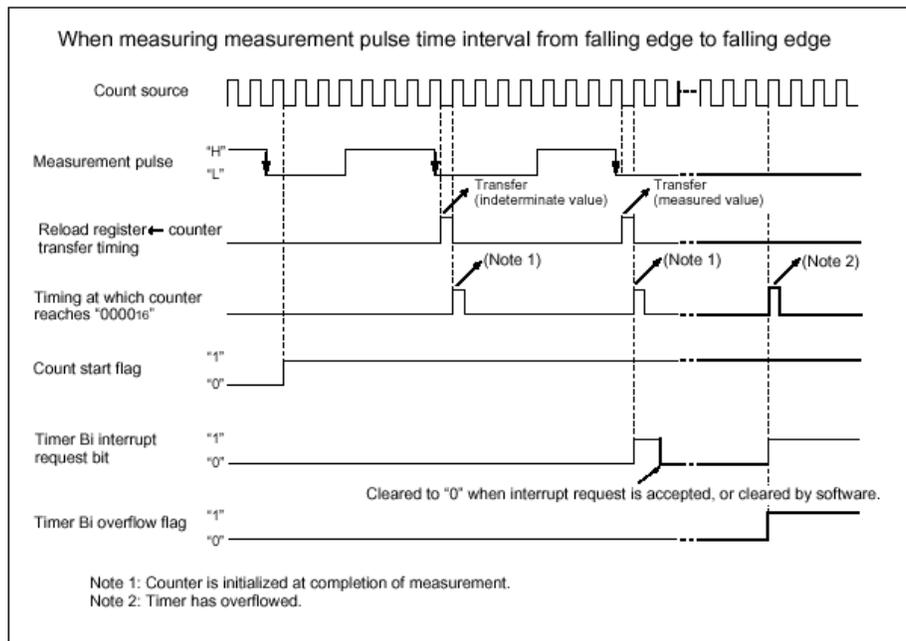
Figure 1. Block Diagram of Timer B

### 3. Pulse Period/Pulse Width Measurement Mode Description

As illustrated in Figure 1, the timer TBi register consists of two parts, a counter and a reload register. In Measurement Mode, when an effective edge appears on the TBiIN pin, the count value is transferred to the reload register and the CPU can read this value by performing a read on the TBi register. The measured time is the counter value (TBi) divided by the frequency of the clock source (Fi). Two period measurement options are available that measure from falling edge to falling edge or rising edge to rising edge. For width measurement, the measurement is taken at both edges and software determines if the measured value is for the high width or low.

#### 3.1 Pulse Period Measurement

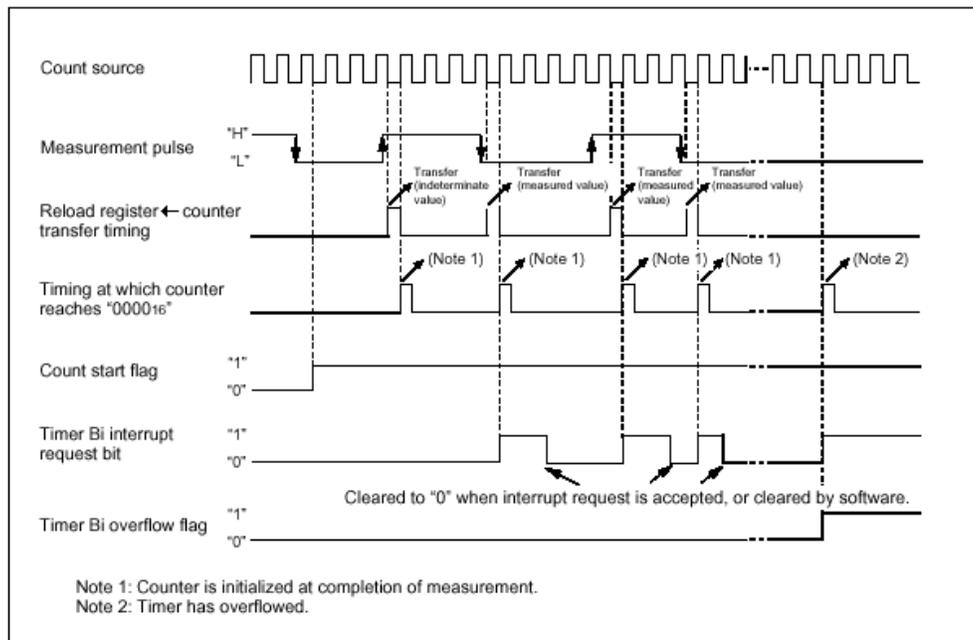
In Period Measurement Mode (e.g. falling edge to falling edge), after the 'start count flag' is set, the counter counts up using the selected clock source and every time a falling edge is detected on the TBiIN pin, the value in the counter is transferred to the reload register, the counter is reset to zero, and then continues counting. At the same time, the timer interrupt request bit is set and an interrupt is generated if the timer interrupt priority level is set above the current CPU priority level (if the I flag in the CPU flag register is cleared, the interrupt will not be serviced until the flag is set). If the timer's counter overflows within a period, it will also generate the interrupt and the MR3 bit in the TBIMR is set to distinguish between the interrupt causes. Note that the measurement is free running and the reload register contains the most recent measurement. The user has the option of polling the TBi register or reading it in an interrupt service routine. Also note that the value of the counter immediately after the 'start count flag' is set is indeterminate and an overflow could occur before the first falling edge. Figure 2 illustrates this.



**Figure 2. Operation Timing When Measuring a Pulse Period**

### 3.2 Pulse Width Measurement

Pulse Width Measurement Mode operates in much the same way except the count register is transferred to the reload register for every edge detected on the TBIIN pin, and the counter resets and resumes counting, as shown in Figure 3. Again, note that the value of the counter immediately after the 'start count flag' is set is indeterminate and an overflow could occur before the first falling edge. This measurement is also free running but now the user must determine by software whether the measurement is for the high or low width.



**Figure 3. Operation Timing When Measuring a Pulse Width**

## 4. Configuring Pulse Period/Pulse Width Measurement Mode

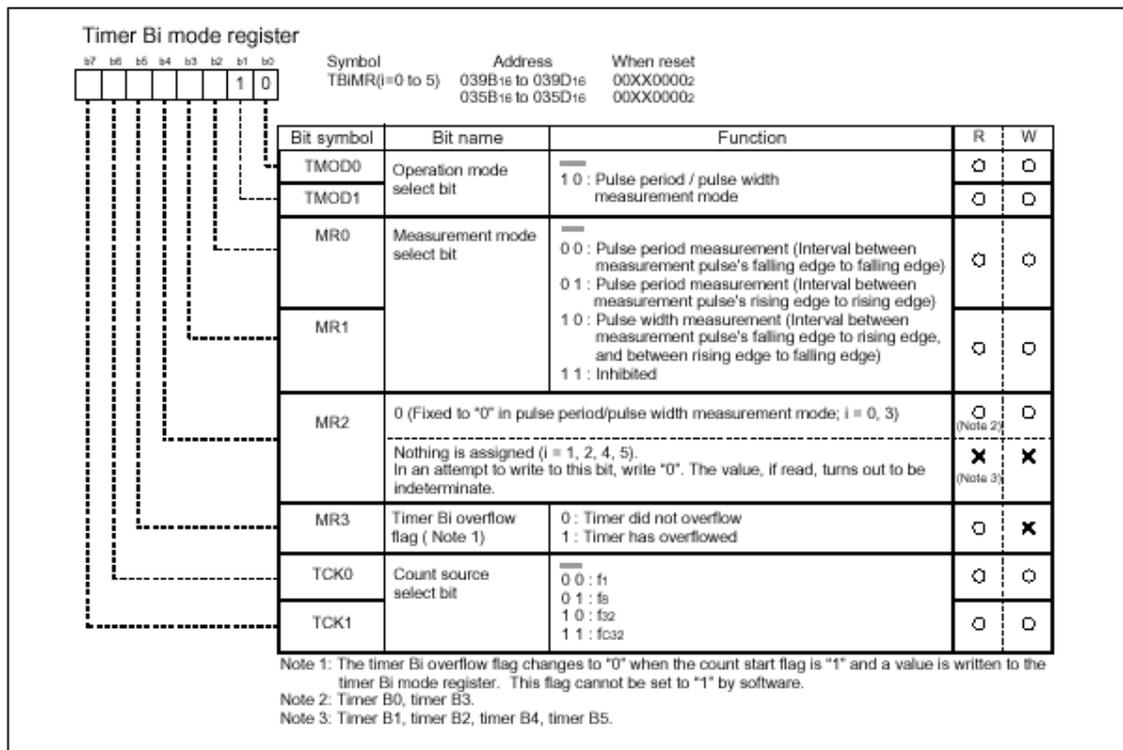
To configure a timer for Pulse Period/Pulse Width Measurement Mode:

1. Load the timer mode register, TAI<sub>MR</sub>.
  - Select Measurement Mode: bits TMOD0 = 0, TMOD1 = 1.
  - Set the MR0 and MR1 bits for period or width measurement.
  - Clear the MR2 bit for period or width measurement.
  - MR3 is the timer Bi overflow flag (can be cleared but not set).
  - Select the clock source (f<sub>1</sub>, f<sub>1</sub>/8, f<sub>1</sub>/32, or f<sub>c</sub>/32): bits TCK0, TCK1 register.
2. Set the timer 'interrupt priority level', TBI<sub>IC</sub>, to at least 1 if required.

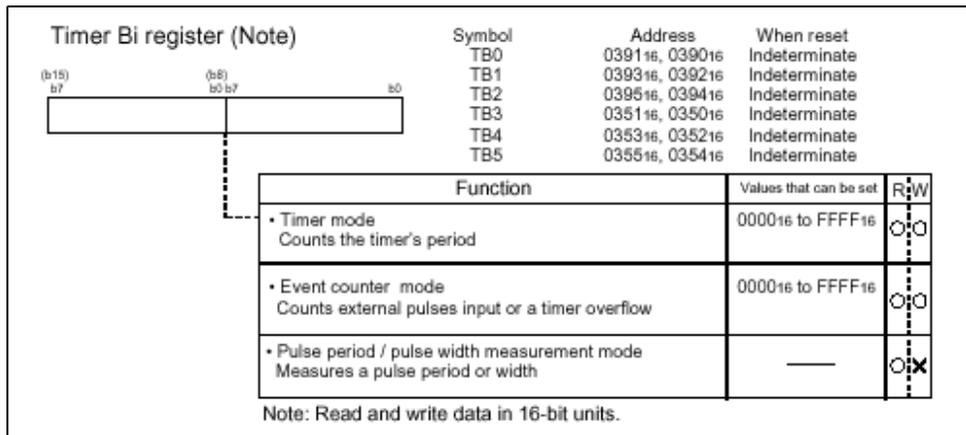
3. Enable interrupts (CPU I flag set).
4. Set the 'start count flag' bit, TBiS, in the 'count start flag' register, TABSR or TBSR.

It is not necessary to perform these steps in the order listed, but the mode register should be loaded before the 'start count' flag is set. Also, the priority level should not be modified when there is a possibility of an interrupt occurring.

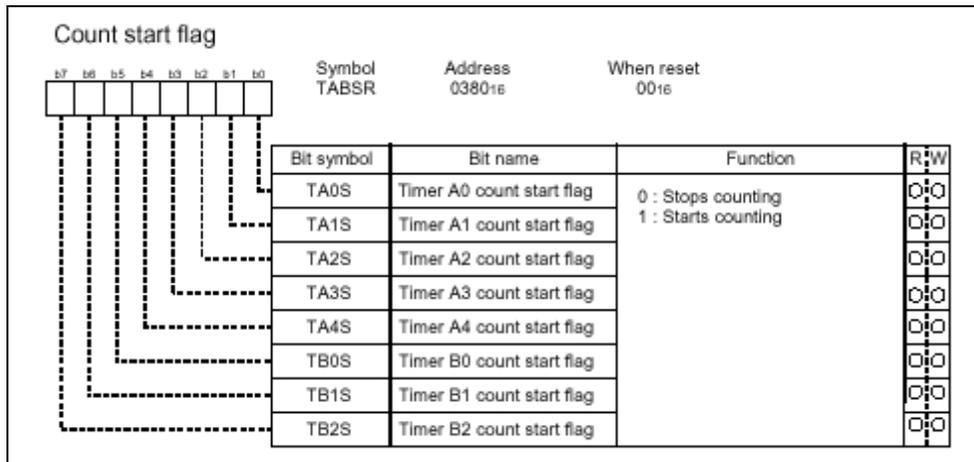
The required registers are shown in Figure 4.



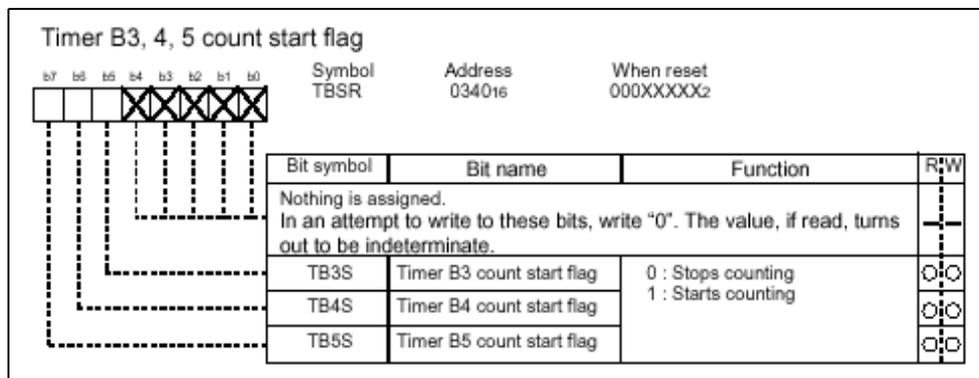
**Figure 4. Timer Bi Mode Register in Pulse Period/Pulse Width Measurement Mode**



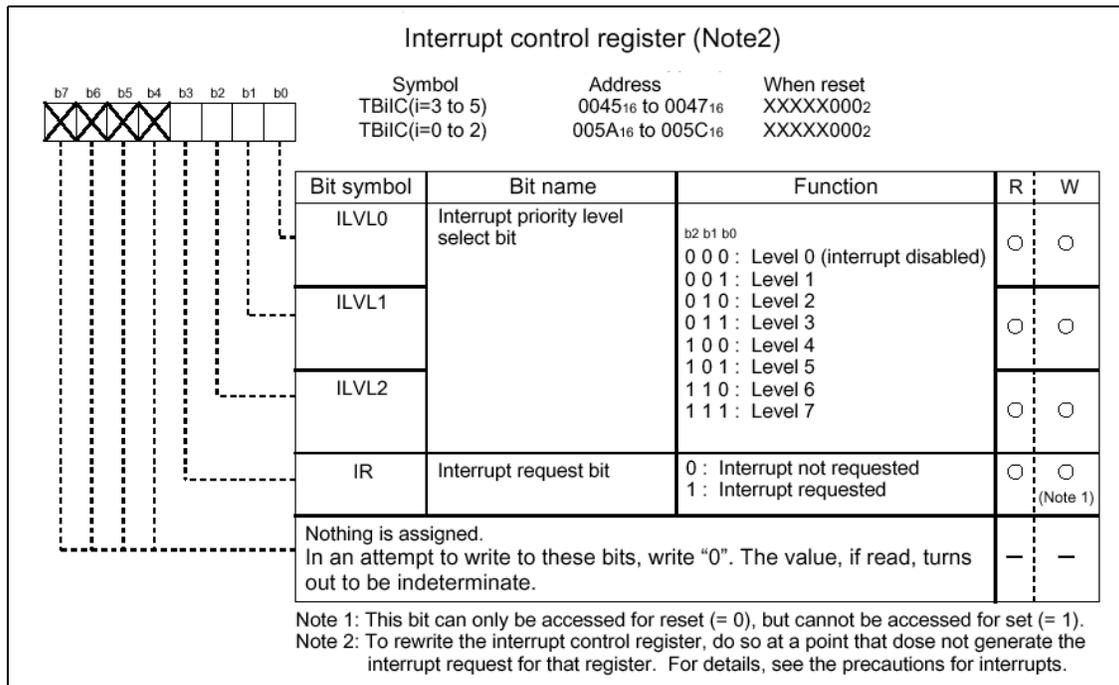
**Figure 5. Timer Bi Register**



**Figure 6. Count Start Flag**



**Figure 7. Timer B3, 4, 5 Count Start Flag**



**Figure 8. Interrupt Control Register**

## 5. References

- NC30 Ver. 4.0 User's Manual, NC30UE.pdf
- M16C/60 and M16C/20 C Language Programming Manual, 6020EC.pdf
- M16C/62 datasheets, 62aeds.pdf
- M16C/62 User's Manual, 62eum.pdf
- Application Note: Writing Interrupt Handlers in C for the M16C

## 6. Software Code

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Below is a program written for Mitsubishi's NC30 compiler to illustrate how to configure Pulse Period/Pulse Width Measurement Mode. The program can measure up to about a 16msec period and runs on the MSV1632 Starter Kit Board. Using the KD30 debugger, the program can be 'stopped' and the global variables 'widthlow', 'width\_hi', and 'period' viewed from the global watch window.

To become familiar with this mode, try changing the clock source or even switch to a different timer (e.g. TB2, TB3, etc.).

```

/*****
*
*   File Name: period_width.c
*
*   Content: Example program using Timer B in 'pulse width / period measurement
*           mode'. This program is written for the "Pulse Period/Width
*           Measurement" application note. Timer B0 is configured to measure
*           pulse width(TB0in pin),and timer B1,measures the period(TB1in pin).
*           Tested using a 250Hz square wave with a 0.5msec pulse width(high).
*           This program works with the MSV1632 starter kit board.
*
*   Compiled with NC30 ver. 3.20.00.
*
*   All timing based on 16 Mhz Xtal
*
*   Copyright,2001 MITSUBISHI ELECTRIC CORPORATION
*   AND MITSUBISHI SEMICONDUCTOR SYSTEM CORPORATION
*   and Mitsubishi Electric and Electronics USA
*=====
*   $Log:$
*=====*/

```

```
#include "sfr62.h"

#define B1TIME_CONFIG 0x42 /* 01000010 value to load into timer B1 mode register
    |||||_ TMOD0,TMOD1: PULSE MEASUREMENT MODE
    |||||_ MR0,MR1: PULSE PERIOD MODE
    |||_ MR2: = 0 FOR PULSE MEASUREMENT
    ||_ MR3: OVERFLOW FLAG
    ||_ TCK0,TCK1: F DIVIDED BY 8 SELECTED */

#define B0TIME_CONFIG 0x4a /* 01001010 value to load into timer B0 mode register
    |||||_ TMOD0,TMOD1: PULSE MEASUREMENT MODE
    |||||_ MR0,MR1: PULSE WIDTH MODE
    |||_ MR2: = 0 FOR PULSE MEASUREMENT
    ||_ MR3: OVERFLOW FLAG
    ||_ TCK0,TCK1: F DIVIDED BY 8 SELECTED */

#define CNTR_IPL 0x03 // TB0 priority interrupt level

int period,widthlow,width_hi;

//prototypes
void init(void);

#pragma INTERRUPT /B TimerB0Int
void TimerB0Int(void);

/*****
Name: TimerB0Int()
Parameters: none
Returns: nothing
Description: Timer B0 Interrupt Service Routine. The overflow flag is check
to determine if the TB0 register contains valid data. If so, the
input is tested to determine if the value in the TB0 register
is the high pulse width or low width and stored in the appropriate
variable.
*****/

void TimerB0Int(void)
{
    if (mr3_tb0mr ==1) // check for timer overflow
    {
        tb0mr = B0TIME_CONFIG; // if so clear flag and
        return; // data invalld, so leave
    }
    if (p9_0== 1)
        widthlow = tb0 ; // if input now hi, just measured a low width
    else
        width_hi = tb0;
}

```

```

/*****
Name:    main()
Parameters: none
Returns: nothing
Description: initializes variables. Then the variable 'period' is constantly
              updated with the period count in timer TB1. This is to illustrate
              that the period measurement is free running. Note that the first
              few times TB1 is read, the data may not be valid.
*****/

void main (void)
{

    init();
    while (1)
    {
        period = tbl ;           // period measured in polled mode
    }
}

/*****
Name:    initial()
Parameters: none
Returns: nothing
Description: Timer TB0 setup for pulse width interrupts and TB1 configured for
              pulse period measurement (no interrupts).
*****/
void init()
{

/* the following procedure for writing an Interrupt Priority Level follows that as
described in the M16C
data sheets under 'Interrupts' */

    _asm (" fclr i" ) ;           // turn off interrupts before modifying IPL
    tb0ic |= CNTR_IPL;           // use read-modify-write instruction to write IPL
    tb0mr = B0TIME_CONFIG;
    _asm (" fset i" );

    tb0s = 1; //start counting

    tb1mr = B1TIME_CONFIG;
    tb1s = 1; //start counting

}

```

In order for this program to run properly, timer B0's interrupt vector needs to point to the function. The interrupt vector table is near the end of the startup file "sect30.inc". Insert the function label "TimerB0Int" into the interrupt vector table at vector 26 as shown below.

```

;*****
;
;   C Compiler for M16C/62
;
;   Copyright,2000 MITSUBISHI ELECTRIC CORPORATION
;   AND MITSUBISHI SEMICONDUCTOR SYSTEM CORPORATION
;   and Mitsubishi Electric and Electronics USA
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;
;   Written by T.Aoyama
;   Modified for use on MSV1632 Starter Kit.
;   sect30.inc      : section definition
;   This program is applicable when using KD30 and the ROM Monitor.
;
;   $Id:
;*****

:
:
:
:
:
:

.lword    dummy_int      ; timer A0(for user)(vector 21)
.lword    dummy_int      ; timer A1(for user)(vector 22)
.lword    dummy_int      ; timer A2(for user)(vector 23)
.lword    dummy_int      ; timer A3(for user)(vector 24)
.lword    dummy_int      ; timer A4(for user)(vector 25)
.glb     _TimerB0Int
.lword    _TimerB0Int    ; timer B0(for user)(vector 26)
.lword    dummy_int      ; timer B1(for user)(vector 27)
.lword    dummy_int      ; timer B2(for user)(vector 28)
.lword    dummy_int      ; int0 (for user)(vector 29)
.lword    dummy_int      ; int1 (for user)(vector 30)
.lword    dummy_int      ; int2 (for user)(vector 31)

.lword    dummy_int      ; vector 32 (for user or MR30)
.lword    dummy_int      ; vector 33 (for user or MR30)
.lword    dummy_int      ; vector 34 (for user or MR30)
.lword    dummy_int      ; vector 35 (for user or MR30)
.lword    dummy_int      ; vector 36 (for user or MR30)
.lword    dummy_int      ; vector 37 (for user or MR30)
:
:
:

```

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