3.3V ECL Programmable Delay Chip with FTUNE

The MC100EP196 is a programmable delay chip (PDC) designed primarily for clock deskewing and timing adjustment. It provides programmably variable delay of a differential ECL input signal. It has similar architecture to the EP195 with the added feature of further tuneability in delay using the FTUNE pin. The FTUNE input takes an analog voltage from V_{CC} to V_{EE} to fine tune the output delay from 0 to 60 ps.

The delay section consists of a programmable matrix of gates and multiplexers as shown in the logic diagram, Figure 2. The delay increment of the EP196 has a digitally selectable resolution of about 10 ps and a range of up to 10 ns. The required delay is selected by the 10 programmable data select inputs D[0:9] which are latched on chip by a high signal on the latch enable (LEN) control. Delays are set by programming values of 00000000000 to 11111111111 on the D0 (LSB) through D9 (MSB) as shown in Table 1.

Because the EP196 is designed using a chain of multiplexers, it has a fixed minimum delay of 2.4 ns. An additional pin, D10, is provided for cascading multiple PDCs for increased programmable range. The cascade logic allows full control of multiple PDCs.

Select input pins, D0–D10, may be threshold controlled by combinations of interconnects between V_{EF} (pin 7) and V_{CF} (pin 8) for CMOS, ECL, or TTL level signals. TTL and CMOS operation is available in PECL mode only. For CMOS input levels, leave V_{CF} and V_{EF} open. For ECL operation, short V_{CF} and V_{EF} (pins 7 and 8). For TTL level operation, connect a 1.5 V supply reference to V_{CF} and leave open V_{EF} pin. The 1.5 V reference voltage to V_{CF} pin can be accomplished by placing a 2.2 k Ω resistor between V_{CF} and V_{EE} for 3.3 V power supply.

The V_{BB} pin, an internally generated voltage supply, is available to this device only. For single–ended input conditions, the unused differential input is connected to V_{BB} as a switching reference voltage. V_{BB} may also rebias AC coupled inputs. When used, decouple V_{BB} and V_{CC} via a 0.01 μ F capacitor and limit current sourcing or sinking to 0.5 mA. When not used, V_{BB} should be left open.

The 100 Series contains temperature compensation.

- Maximum Frequency > 1.2 GHz Typical
- PECL Mode Operating Range: V_{CC} = 3.0 V to 3.6 V with V_{EE} = 0 V
- NECL Mode Operating Range: V_{CC} = 0 V with V_{EE} = -3.0 V to -3.6 V
- Open Input Default State
- Safety Clamp on Inputs
- A Logic High on the EN Pin Will Force Q to Logic Low
- D[0:10] Can Accept Either ECL, CMOS, or TTL Inputs
- V_{BB} Output Reference Voltage

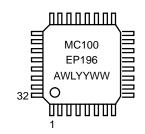


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MARKING DIAGRAM*





A = Assembly Location

WL = Wafer Lot

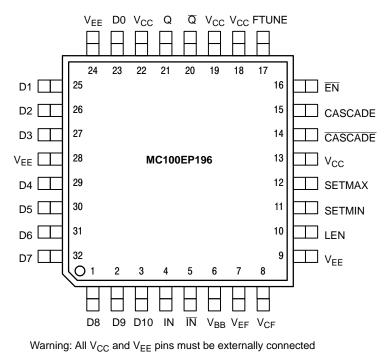
YY = Year

WW = Work Week

*For additional information, refer to Application Note AND8002/D

ORDERING INFORMATION

Device	Package	Shipping
MC100EP196FA	LQFP-32	250 Units/Tray
MC100EP196FAR2	LQFP-32	2000/Tape & Reel



to Power Supply to guarantee proper operation.

Figure 1. 32-Lead LQFP Pinout (Top View)

PIN DESCRIPTION

PIN	FUNCTION
IN*, ĪN*	ECL Signal Input
<u>EN</u> *	ECL Input Enable
D[0:10]*	CMOS, ECL, or TTL Select Inputs
Q, \overline{Q}	ECL Signal Output
LEN*	ECL Latch Enable Input
SETMIN*†	ECL Minimum Delay Set Input
SETMAX*	ECL Maximum Delay Set Input
CASCADE,	ECL Cascade Signal Output
V _{BB}	Output Reference Voltage
V _{CC}	Positive Supply
V _{EE}	Negative Supply
V _{CF}	CMOS, ECL, or TTL Input Select Input
V _{EF}	ECL Reference Mode Connection
FTUNE*	Fine Tuning Input

^{*} Pins will default LOW (V_{EE}) when left open. †SETMIN will override SETMAX if both pins are high.

TRUTH TABLE

EN	L*	Q = IN
EN	Н	Q Logic Low
LEN	L*	Pass Through D[0:10]
LEN	Н	Latch D[0:10]
SETMIN	L*	Normal Mode
SETMIN	Н	Min Delay Path
SETMAX	L*	Normal Mode
SETMAX	Н	Max Delay Path
V _{CF}	V _{EF} Pin**	ECL Mode
V _{CF}	No Connect	CMOS Mode
V _{CF}	1.5 V ±100 mV	TTL Mode***

- * Internal pulldown will provide logic low if pin left unconnected.
- ** Short V_{CF} (pin 8) and V_{EF} (pin 7).
- *** For TTL Mode, if no external voltage can be provided, the reference voltage can be provided by connecting the appropriate resistor between V_{CF} and V_{EE} pins.

Power Supply	Resistor Value 5% (Tolerance)
3.3 V	2.2 kΩ

DATA INPUT OPERATING VOLTAGE TABLE								
POWER SUPPLY	DATA SELECT INPUTS (D [0:10])							
(V _{CC} , V _{EE})	CMOS	TTL	PECL	NECL				
PECL	1	~	~	N/A				
NECL	N/A	N/A	N/A	~				

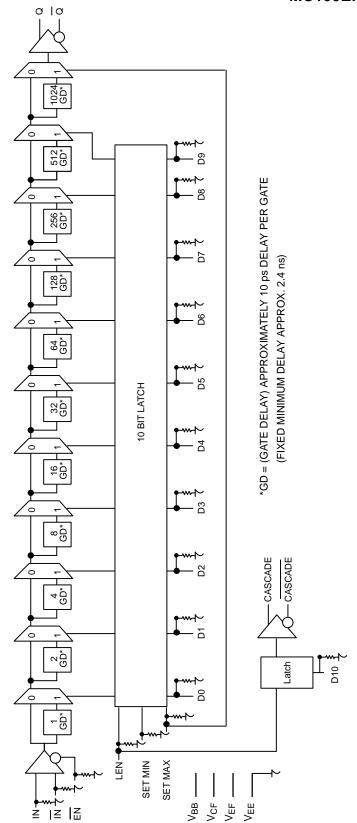


Figure 2. Logic Diagram

Table 1. Theoretical Delta Delay Values

(does not include fixed minimum delay)

D10	D(9:0) Value	Delay Value	Comment
	000000000	0 ps	(SET MIN)
	000000001	10 ps	
	000000010	20 ps	
	000000011	30 ps	
	000000100	40 ps	
	000000101	50 ps	
	000000110	60 ps	
	0000000111	70 ps	
	000001000	80 ps	
	0000010000	160 ps	
	0000100000	320 ps	
	0001000000	640 ps	
	0010000000	1280 ps	
	0100000000	2560 ps	
	100000000	5120 ps	
	1111111111	10230 ps	
1	XXXXXXXXX	10240 ps	(SET MAX)

Table 2. Typical FTUNE Delay Pin

Input Range	Output Range
V _{CC} -V _{EE} (V)	0 - 60 (ps)

ATTRIBUTES

Characteris	Value			
Internal Input Pulldown Resistor	75 kΩ			
Internal Input Pullup Resistor		N/A		
ESD Protection	Human Body Model Machine Model Charged Device Model	> 2 kV > 100 V > 2 kV		
Moisture Sensitivity (Note 1)		Level 2		
Flammability Rating	Oxygen Index: 28 to 34	UL 94 V-0 @ 0.125 in"		
Transistor Count		1279 Devices		
Meets or exceeds JEDEC Spec EIA/	JESD78 IC Latchup Test			

^{1.} For additional information, see Application Note AND8003/D.

MAXIMUM RATINGS (Note 2)

Symbol	Parameter	Condition 1	Condition 2	Rating	Units
V _{CC}	PECL Mode Power Supply	V _{EE} = 0 V		6	V
V _{EE}	NECL Mode Power Supply	V _{CC} = 0 V		-6	V
VI	PECL Mode Input Voltage NECL Mode Input Voltage	V _{EE} = 0 V V _{CC} = 0 V	$\begin{aligned} &V_I \leq V_{CC} \\ &V_I \geq V_{EE} \end{aligned}$	6 -6	V V
l _{out}	Output Current	Continuous Surge		50 100	mA mA
I _{BB}	V _{BB} Sink/Source			± 0.5	mA
TA	Operating Temperature Range			-40 to +85	°C
T _{stg}	Storage Temperature Range			-65 to +150	°C
$\theta_{\sf JA}$	Thermal Resistance (Junction–to–Ambient)	0 LFPM 500 LFPM	32 LQFP 32 LQFP	80 55	°C/W
$\theta_{\sf JC}$	Thermal Resistance (Junction-to-Case)	std bd	32 LQFP	12 to 17	°C/W
T _{sol}	Wave Solder	< 2 to 3 sec @ 248°C		265	°C

^{2.} Maximum Ratings are those values beyond which device damage may occur.

DC CHARACTERISTICS, PECL $V_{CC} = 3.3 \text{ V}$, $V_{EE} = 0 \text{ V}$ (Note 3)

		−40°C			25°C						
Symbol	Characteristic	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
I _{EE}	Power Supply Current	100	125	160	110	130	170	110	135	175	mA
V _{OH}	Output HIGH Voltage (Note 4)	2155	2300	2405	2155	2300	2405	2155	2300	2405	mV
V _{OL}	Output LOW Voltage (Note 4)	1355	1520	1605	1355	1500	1605	1355	1485	1605	mV
V _{IH}	Input HIGH Voltage (Single–Ended) PECL CMOS TTL	2075 2000 2000		3300 3300 3300	2075 2000 2000		3300 3300 3300	2075 2000 2000		3300 3300 3300	mV
V _{IL}	Input LOW Voltage (Single-Ended) PECL CMOS TTL	1355 0 0		1675 800 800	1355 0 0		1675 800 800	1355 0 0		1675 800 800	mV
V_{BB}	Output Voltage Reference	1775	1875	1975	1775	1875	1975	1775	1875	1975	mV
V _{CF}	TTL Mode Input Detect Voltage @ IV _{CF} = 700 μA	1.4	1.5	1.6	1.4	1.5	1.6	1.4	1.5	1.6	V
V _{EF}	Reference Voltage for ECL Mode Connection	1850	1979	2100	1800	1975	2125	1800	1966	2125	mV
V _{IHCMR}	Input HIGH Voltage Common Mode Range (Differential) (Note 5)	2.0		3.3	2.0		3.3	2.0		3.3	V
I _{IH}	Input HIGH Current IN, ĪN, D0-D10, ĒN Setmin, Setmax, LEN			400 400			400 400			400 400	μΑ
I _{IHH}	FTUNE Input Current @ V _{CC}			400			400			400	μΑ
I _{IL}	Input LOW Current IN IN	-150 -150			-150 -150			-150 -150			μΑ
I _{ILL}	FTUNE Input LOW Current @V _{EE}	-200			-200			-200			μΑ

NOTE: EP circuits are designed to meet the DC specifications shown in the above table after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse airflow greater than 500 lfpm is maintained.

3. Input and output parameters vary 1:1 with V_{CC}. V_{EE} can vary +0.3 V to -0.3 V.

 ^{4.} All loading with 50 Ω to V_{CC}-2.0 volts.
 5. V_{IHCMR} min varies 1:1 with V_{EE}, V_{IHCMR} max varies 1:1 with V_{CC}. The V_{IHCMR} range is referenced to the most positive side of the differential input signal.

DC CHARACTERISTICS, NECL V_{CC} = 0 V, V_{EE} = -3.0 V to -3.6 V (Note 6)

		−40°C				25°C					
Symbol	Characteristic	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
I _{EE}	Power Supply Current	100	125	160	110	130	170	110	135	175	mA
V _{OH}	Output HIGH Voltage (Note 7)	-1145	-1000	-895	-1145	-1000	-895	-1145	-1000	-895	mV
V _{OL}	Output LOW Voltage (Note 7)	-1945	-1780	-1695	-1945	-1800	-1695	-1945	-1815	-1695	mV
V _{IH}	Input HIGH Voltage (Single–Ended) NECL	-1225	-1394	-880	-1225	-1412	-880	-1225	-1429	-880	mV
V _{IL}	Input LOW Voltage (Single–Ended) NECL	-1945	-1417	-1625	-1945	-1435	-1625	-1945	-1453	-1625	mV
V _{BB}	Output Voltage Reference	-1525	-1425	-1325	-1525	-1425	-1325	-1525	-1425	-1325	mV
V _{EF}	Mode Connection	-1450	-1321	-1200	-1500	-1325	-1175	-1500	-1334	-1175	mV
V _{IHCMR}	Input HIGH Voltage Common Mode Range (Differential) (Note 8)	V _{EE}	+2.0	0	V _{EE}	+2.0	0	V _{EE}	+2.0	0	V
I _{IH}	Input HIGH Current IN, IN, D0-D10, EN Setmin, Setmax, LEN			400 400			400 400			400 400	μΑ
I _{IHH}	FTUNE Input Current @ V _{CC}			400			400			400	μΑ
I _{IL}	Input LOW Current IN IN	-150 -150			-150 -150			-150 -150			μΑ
I _{ILL}	FTUNE Input LOW Current @ VEE	-200			-200			-200			μΑ

NOTE: EP circuits are designed to meet the DC specifications shown in the above table after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse airflow greater than 500 lfpm is maintained.
6. Input and output parameters vary 1:1 with V_{CC}.
7. All loading with 50 Ω to V_{CC}-2.0 volts.
8. V_{IHCMR} min varies 1:1 with V_{EE}, V_{IHCMR} max varies 1:1 with V_{CC}. The V_{IHCMR} range is referenced to the most positive side of the differential input signal.

AC CHARACTERISTICS $V_{CC} = 0 \text{ V}$; $V_{EE} = -3.0 \text{ V}$ to -3.6 V or $V_{CC} = 3.0 \text{ V}$ to 3.6 V; $V_{EE} = 0 \text{ V}$ (Note 9)

			-40°C 25°C		85°C						
Symbol	Characteristic	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
f _{max}	Maximum Frequency		1.2			1.2			1.2		GHz
t _{PLH} t _{PHL}	Propagation Delay IN to Q; D(0–9) = 0 IN to Q; D(0–9) = 1023 EN to Q; D(0–9) = 0 D10 to CASCADE	1810 9500 1780 350	2210 11496 2277 450	2610 13500 2780 550	1960 10000 1930 380	2360 12258 2430 477	2760 14000 2930 580	2180 10955 2150 420	2580 13454 2650 520	2980 15955 3150 620	ps
t _{RANGE}	Programmable Range $ \{D(0-9) = HI\} - \{D(0-9) = LO\} $	8600	9285	10000	9200	9897	10700	9900	10875	12000	ps
Δt	Step Delay (Note 10) D0 High D1 High D2 High D3 High D4 High D5 High D6 High D7 High D8 High D9 High	90 245 530 1060 2160 4335	12 28 46 64 137 293 590 1158 2317 4647	185 335 650 1265 2490 5010	100 260 560 1130 2290 4590	16 32 50 69 149 313 629 1237 2472 4955	200 370 710 1355 2680 5385	90 270 600 1200 2450 4935	11 39 63 154 337 681 1353 2712 5440	225 410 770 1520 3015 6015	ps
Mono	Monotonicity (Note 11)		9			10			11		ps
t _{SKEW}	Duty Cycle Skew (Note 12) t _{PHL} -t _{PLH}		20			22			27		ps
t _S	Setup Time D to LEN D to IN (Note 13) EN to IN (Note 14)	150 100 150	-10 -130 -105		150 100 150	-70 -150 -120		150 100 150	-70 -165 -140		ps
t _h	Hold Time LEN to D IN to EN (Note 15)	TBD 450	TBD 275		200 450	70 305		200 450	60 325		ps
t _R	Release Time EN to IN (Note 16) SET MAX to LEN SET MIN to LEN	150 400 300	-105 70 165		150 400 350	-120 110 180		150 400 350	-140 160 205		ps
t _{jit}	Random Clock Jitter @ 1.2 GHz, SETMAX Delay		3			3			3		ps
V _{PP}	Input Voltage Swing (Differential)	150	800	1200	150	800	1200	150	800	1200	mV
t _r t _f	Output Rise/Fall Time 20–80% (Q) 20–80% (CASCADE)	85 100	110 150	130 200	95 110	120 160	145 210	110 125	135 175	160 225	ps

^{9.} Measured using a 750 mV source, 50% duty cycle clock source. All loading with 50 Ω to V_{CC}-2.0 V. 10. Specification limits represent the amount of delay added with the assertion of each individual delay control pin. The various combinations of asserted delay control inputs will typically realize D0 resolution steps across the specified programmable range.

^{11.} The monotonicity indicates the increased delay value for each binary count increment on the control inputs D(0-9).

^{12.} Duty cycle skew guaranteed only for differential operation measured from the cross point of the input to the cross point of the output.

^{13.} This setup time defines the amount of time prior to the input signal the delay tap of the device must be set.

^{13.} This setup time defines the amount of time prior to the input signal the delay tap of the device must be set.
14. This setup time is the minimum time that EN must be asserted prior to the next transition of IN/IN to prevent an output response greater than V_{CC} – 1425 mV to that IN/IN transition.
15. This hold time is the minimum time that EN must remain asserted after a negative going IN or positive going IN to prevent an output response greater than V_{CC} – 1425 mV to that IN/IN transition.
16. This release time is the minimum time that EN must be deasserted prior to the next IN/IN transition to ensure an output response that meets

the specified IN to Q propagation delay and transition times.

Using the FTUNE Analog Input

The analog FTUNE pin on the EP196 device is intended to add more delay in a tunable gate to enhance the 10 ps resolution capabilities of the fully digital EP196. The level of resolution obtained is dependent on the voltage applied to the FTUNE pin.

To provide this further level of resolution, the FTUNE pin must be capable of adjusting the additional delay finer than the 10 ps digital resolution (See Logic Diagram). This requirement is easily achieved because a 60 ps additional delay can be obtained over the entire FTUNE voltage range (See Figure 3). This extra analog range ensures that the FTUNE pin will be

capable even under worst case conditions of covering a digital resolution. Typically, the analog input will be driven by an external DAC to provide a digital control with very fine analog output steps. The final resolution of the device will be dependent on the width of the DAC chosen.

To determine the voltage range necessary for the FTUNE input, Figure 3 should be used. There are numerous voltage ranges which can be used to cover a given delay range; users are given the flexibility to determine which one best fits their designs.

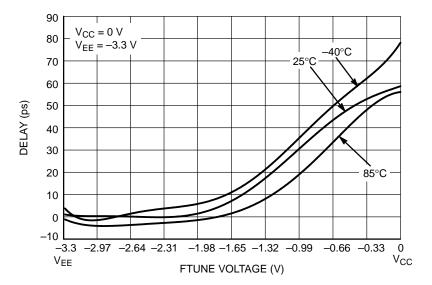


Figure 3. Typical EP196 Delay versus FTUNE Voltage

Cascading Multiple EP196s

To increase the programmable range of the EP196, internal cascade circuitry has been included. This circuitry allows for the cascading of multiple EP196s without the need for any external gating. Furthermore, this capability requires only one more address line per added E196. Obviously, cascading multiple programmable delay chips will result in a larger programmable range; however, this increase is at the expense of a longer minimum delay.

Figure 4 illustrates the interconnect scheme for cascading two EP196s. As can be seen, this scheme can easily be expanded for larger EP196 chains. The D10 input of the EP196 is the cascade control pin. With the interconnect scheme of Figure 4 when D10 is asserted, it signals the need for a larger programmable range than is achievable with a single device. The A11 address can be added to generate a cascade output for the next EP196. For a 2–device configuration, A11 is not required.

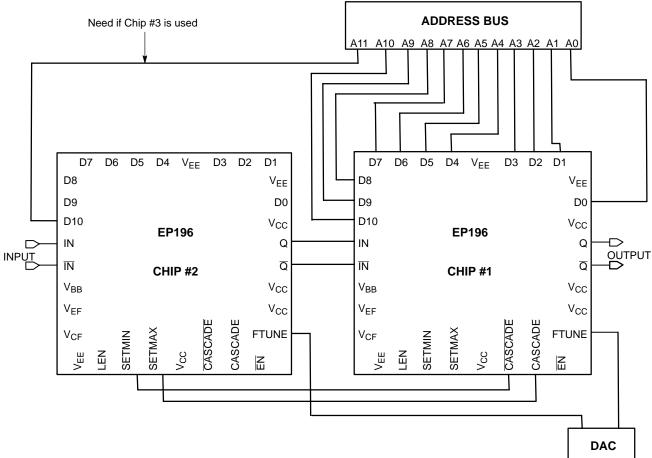


Figure 4. Cascading Interconnect Architecture

An expansion of the latch section of the block diagram is pictured in Figure 5. Use of this diagram will simplify the explanation of how the cascade circuitry works. When D10 of chip #1 in Figure 4 is low, the cascade output will also be low while the cascade bar output will be a logical high. In this condition, the SETMIN pin of chip #2 will be asserted and thus all of the latches of chip #2 will be reset and the device will be set at its minimum delay.

Chip #1, on the other hand, will have both SETMIN and SETMAX deasserted so that its delay will be controlled entirely by the address bus A0–A9. If the delay needed is greater than can be achieved with 1023 gate delays (11111111111 on the A0–A9 address bus), D10 will be asserted to signal the need to cascade the delay to the next EP196 device. When D10 is asserted, the SETMIN pin of

chip #2 will be deasserted and the SETMAX pin asserted, resulting in the device delay to be the maximum delay. Figure 6 shows the delay time of two EP196 chips in cascade.

To expand this cascading scheme to more devices, one simply needs to connect the D10 pin from the next chip to the address bus and CASCADE outputs to the next chip in the same manner as pictured in Figure 4. The only addition to the logic is the increase of one line to the address bus for cascade control of the second programmable delay chip.

Furthermore, to fully utilize EP196, the FTUNE pin can be used for additional delay and for finer resolution than 10 ps. As shown in Figure 3, an analog voltage input from DAC can adjust the FTUNE pin with an extra 60 ps of delay for each chip.

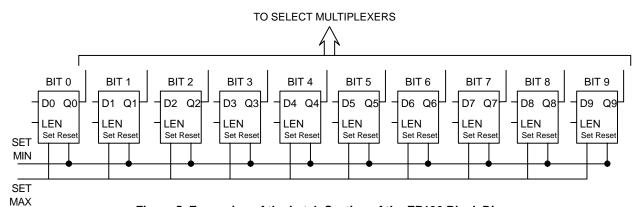


Figure 5. Expansion of the Latch Section of the EP196 Block Diagram

VARIABLE INPUT TO CHIP #1 AND SETMIN FOR CHIP #2												
INPUT FOR CHIP #1											Total	
D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	Delay Value	Delay Value
0	0	0	0	0	0	0	0	0	0	0	0 ps	4400 ps
0	0	0	0	0	0	0	0	0	0	1	10 ps	4410 ps
0	0	0	0	0	0	0	0	0	1	0	20 ps	4420 ps
0	0	0	0	0	0	0	0	0	1	1	30 ps	4430 ps
0	0	0	0	0	0	0	0	1	0	0	40 ps	4440 ps
0	0	0	0	0	0	0	0	1	0	1	50 ps	4450 ps
0	0	0	0	0	0	0	0	1	1	0	60 ps	4460 ps
0	0	0	0	0	0	0	0	1	1	1	70 ps	4470 ps
0	0	0	0	0	0	0	1	0	0	0	80 ps	4480 ps
0	0	0	0	0	0	1	0	0	0	0	160 ps	4560 ps
0	0	0	0	0	1	0	0	0	0	0	320 ps	4720 ps
0	0	0	0	1	0	0	0	0	0	0	640 ps	5040 ps
0	0	0	1	0	0	0	0	0	0	0	1280 ps	5680 ps
0	0	1	0	0	0	0	0	0	0	0	2560 ps	6960 ps
0	1	0	0	0	0	0	0	0	0	0	5120 ps	9520 ps
0	1	1	1	1	1	1	1	1	1	1	10230 ps	14630 ps

VARIABLE INPUT TO CHIP #1 AND SETMAX FOR CHIP #2												
INPUT FOR CHIP #1											Total	
D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	Delay Value	Delay Value
1	0	0	0	0	0	0	0	0	0	0	10240 ps	14640 ps
1	0	0	0	0	0	0	0	0	0	1	10250 ps	14650 ps
1	0	0	0	0	0	0	0	0	1	0	10260 ps	14660 ps
1	0	0	0	0	0	0	0	0	1	1	10270 ps	14670 ps
1	0	0	0	0	0	0	0	1	0	0	10280 ps	14680 ps
1	0	0	0	0	0	0	0	1	0	1	10290 ps	14690 ps
1	0	0	0	0	0	0	0	1	1	0	10300 ps	14700 ps
1	0	0	0	0	0	0	0	1	1	1	10310 ps	14710 ps
1	0	0	0	0	0	0	1	0	0	0	10320 ps	14720 ps
1	0	0	0	0	0	1	0	0	0	0	10400 ps	14800 ps
1	0	0	0	0	1	0	0	0	0	0	10560 ps	14960 ps
1	0	0	0	1	0	0	0	0	0	0	10880 ps	15280 ps
1	0	0	1	0	0	0	0	0	0	0	11520 ps	15920 ps
1	0	1	0	0	0	0	0	0	0	0	12800 ps	17200 ps
1	1	0	0	0	0	0	0	0	0	0	15360 ps	19760 ps
1	1	1	1	1	1	1	1	1	1	1	20470 ps	24870 ps

Figure 6. Cascaded Delay Value of Two EP196s

Multi-Channel Deskewing

The most practical application for EP196 is in multiple channel delay matching. Slight differences in impedance and cable length can create large timing skews within a high–speed system. To deskew multiple signal channels, each channel can be sent through each EP196 as shown in

Figure 7. One signal channel can be used as reference and the other EP196s can be used to adjust the delay to eliminate the timing skews. Nearly any high–speed system can be fine tuned (as small as 10 ps) to reduce the skew to extremely tight tolerances using the available FTUNE pin.

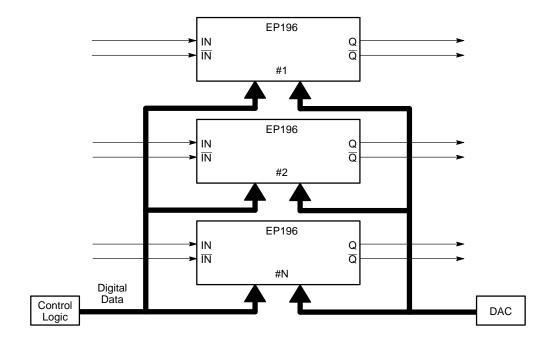


Figure 7. Multiple Channel Deskewing Diagram

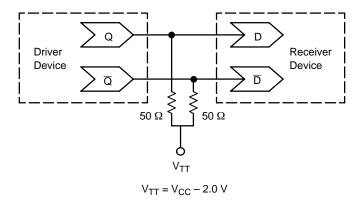


Figure 8. Typical Termination for Output Driver and Device Evaluation (See Application Note AND8020 – Termination of ECL Logic Devices.)

Resource Reference of Application Notes

AN1404 - ECLinPS Circuit Performance at Non–Standard V_{IH} Levels

AN1405 - ECL Clock Distribution Techniques

AN1406 - Designing with PECL (ECL at +5.0 V)

AN1504 - Metastability and the ECLinPS Family

AN1568 - Interfacing Between LVDS and ECL

AND8002 - Marking and Date Codes

AND8009 – ECLinPS Plus Spice I/O Model Kit
AND8020 – Termination of ECL Logic Devices

AND8066 - Interfacing with ECLinPS

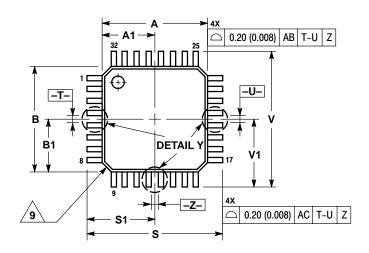
AND8072 - Thermal Analysis and Reliability of WIRE BONDED ECL

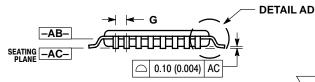
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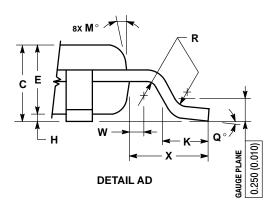
PACKAGE DIMENSIONS

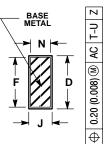
LQFP FA SUFFIX

32-LEAD PLASTIC PACKAGE CASE 873A-02 **ISSUE A**

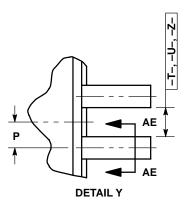








SECTION AE-AE



NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- 2. CONTROLLING DIMENSION: MILLIMETER.
 3. DATUM PLANE -AB- IS LOCATED AT BOTTOM OF LEAD AND IS COINCIDENT WITH THE LEAD. WHERE THE LEAD EXTIS THE PLASTIC BODY AT THE BOTTOM OF THE PARTING LINE.

 4. DATUMS -T-, -U-, AND -Z- TO BE DETERMINED AT DATUM PLANE -AB-.

- AT DATUM PLANE -AB-.

 5. DIMENSIONS S AND V TO BE DETERMINED AT SEATING PLANE -AC-.

 6. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION. A LLOWABLE PROTRUSION IS 0.250 (0.010) PER SIDE. DIMENSIONS A AND B DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE -AB-.

 7. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. DAMBAR PROTRUSION SHALL NOT CAUSE THE D DIMENSION TO EXCEED 0.520 (0.020).

 8. MINIMUM SOLDER PLATE THICKNESS SHALL BE 0.0076 (0.0003).

- MINIMOW SOLDER PLATE THICKNESS SHALL
 0.0076 (0.0003).

 EXACT SHAPE OF EACH CORNER MAY VARY
 FROM DEPICTION.

	MILLIN	IETERS	INCHES			
DIM	MIN	MAX	MIN	MAX		
Α	7.000	BSC	0.276 BSC			
A1	3.500	BSC	0.138 BSC			
В	7.000	BSC	0.276 BSC			
B1	3.500	BSC	0.138 BSC			
С	1.400	1.600	0.055	0.063		
D	0.300	0.450	0.012	0.018		
E	1.350	1.450	0.053	0.057		
F	0.300	0.400	0.012	0.016		
G	0.800	BSC	0.031 BSC			
Н	0.050	0.150	0.002	0.006		
J	0.090	0.200	0.004	0.008		
K	0.500	0.700	0.020	0.028		
M	12°	REF	12° REF			
N	0.090	0.160	0.004	0.006		
P	0.400	BSC	0.016 BSC			
Q	1°	5°	1°	5°		
R	0.150	0.250	0.006	0.010		
S	9.000	BSC	0.354 BSC			
S1	4.500	BSC	0.177 BSC			
V	9.000	BSC	0.354 BSC			
V1	4.500	BSC	0.177 BSC			
W	0.200	REF	0.008 REF			
X	1.000	REF	0.039 REF			





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