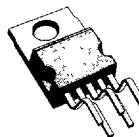


3A POWER OPERATIONAL AMPLIFIER

- OUTPUT CURRENT UP TO 3A
- LARGE COMMON-MODE AND DIFFERENTIAL MODE RANGES
- SOA PROTECTION
- THERMAL PROTECTION
- ± 18 V SUPPLY

The L165 is a monolithic integrated circuit in Pentawatt® package, intended for use as power operational amplifier in a wide range of applications, including servo amplifiers and power supplies. The high gain and high output power capability provide

superior performance wherever an operational amplifier/power booster combination is required.



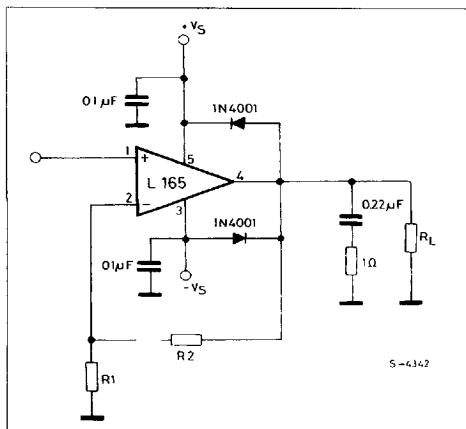
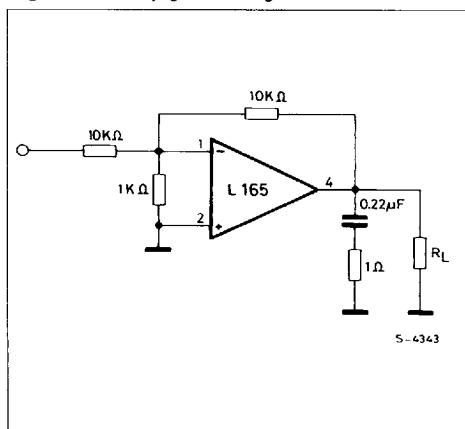
Pentawatt®

ORDER CODE : L165V

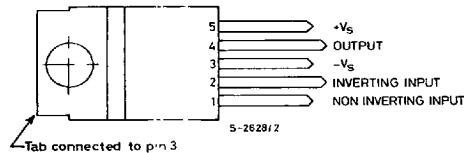
ABSOLUTE MAXIMUM RATINGS

V_s	Supply voltage	± 18	V
$V_5 - V_4$	Upper power transistor V_{CE}	36	V
$V_4 - V_3$	Lower power transistor V_{CE}	36	V
V_i	Input voltage	V_s	
V_i	Differential input voltage	± 15	V
I_o	Peak output current (internally limited)	3.5	A
P_{tot}	Power dissipation at $T_{case} = 90^\circ\text{C}$	20	W
T_{stg}, T_j	Storage and junction temperature	- 40 to 150	$^\circ\text{C}$

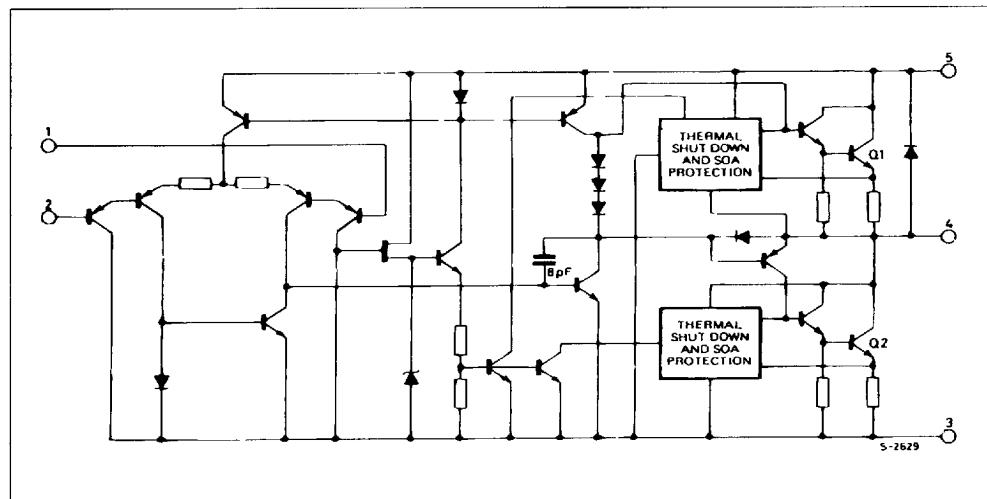
APPLICATION CIRCUITS

Figure 1 : Gain > 10.

Figure 2 : Unity gain configuration.


CONNECTION DIAGRAM
(top view)



SCHEMATIC DIAGRAM



THERMAL DATA

R _{th(j-case)}	Thermal resistance junction-case	max	3	°C/W
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ELECTRICAL CHARACTERISTICS ($V_S = \pm 15$ V, $T_J = 25$ °C unless otherwise specified)

Symbol	Parameter	Test Conditions		Min.	Typ.	Max.	Unit
V_S	Supply Voltage			± 6		± 18	V
I_d	Quiescent Drain Current				40	60	mA
I_b	Input Bias Current	$V_S = \pm 18$ V			0.2	1	µA
V_{os}	Input Offset Voltage				± 2	± 10	mV
I_{os}	Input Offset Current				± 20	± 200	nA
SR	Slew-rate	$G_V = 10$			8		V/µs
		$G_V = 1$ (°)			6		
V_o	Output Voltage Swing	$f = 1$ kHz	$I_p = 0.3$ A $I_p = 3$ A		27		V _{PP}
		$f = 10$ kHz	$I_p = 0.3$ A $I_p = 3$ A		27	23	
R	Input Resistance (pin 1)	$f = 1$ KHz		100	500		KΩ
G_V	Voltage Gain (open loop)				80		dB
e_N	Input Noise Voltage	$B = 10$ to $10\,000$ Hz			2		µV
i_N	Input Noise Current				100		pA
CMR	Common-mode Rejection	$R_g \leq 10$ KΩ	$G_V = 30$ dB		70		dB
SVR	Supply Voltage Rejection	$R_Q = 22$ KΩ	$G_V = 10$		60	dB	dB
		$V_{ripple} = 0.5$ V _{rms} $f_{ripple} = 100$ Hz	$dBG_V = 100$		40		dB
T_{sd}	Efficiency	$f = 1$ kHz	$I_p = 1.6$ A ; $P_o = 5$ W		70		%
		$R_L = 4$ Ω	$I_p = 3$ A ; $P_o = 18$ W		60		%
T_{sd}	Thermal Shut-down Case Temperature	$P_{tot} = 12$ W			110		°C
		$P_{tot} = 6$ W			130		

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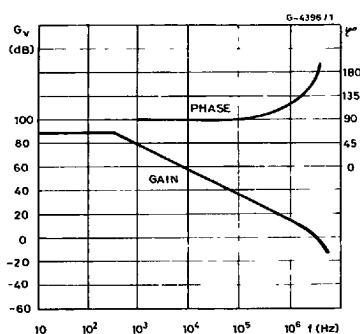
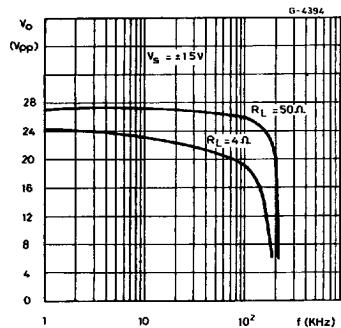
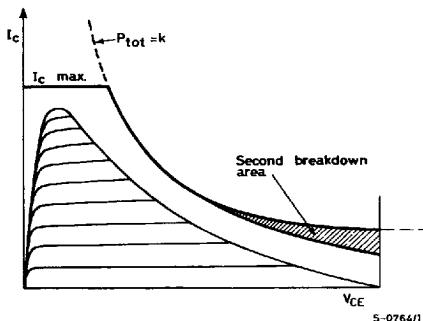
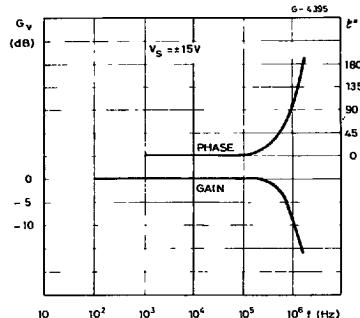
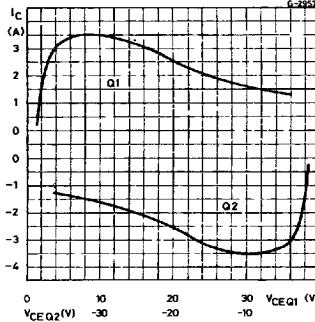
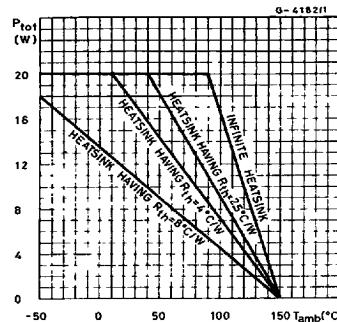
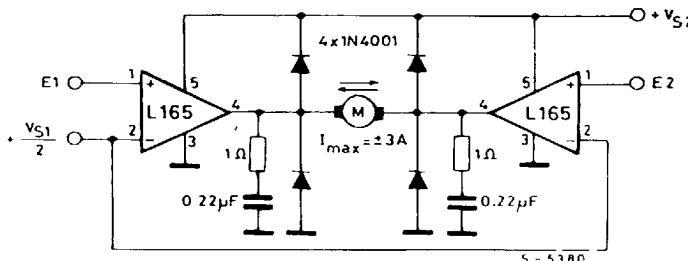
Figure 3 : Open loop frequency response.**Figure 5 : Large signal frequency response.****Figure 7 : Safe operating area and collector characteristics of the protected power transistor.****Figure 4 : Closed loop frequency response (circuit of figure 2).****Figure 6 : Maximum output current vs. voltage [VCE] across each output transistor.****Figure 8 : Maximum allowable power dissipation vs. ambient temperature.**

Figure 9 : Bidirectional DC motor control with TTL/CMOS/ μ P compatible inputs.



Must be $V_{S2} \geq V_{S1}$ E1, E2 = logic inputs
 V_{S1} = logic supply voltage

Figure 10 : Motor current control circuit with external power transistors ($I_{motor} > 3.5A$).

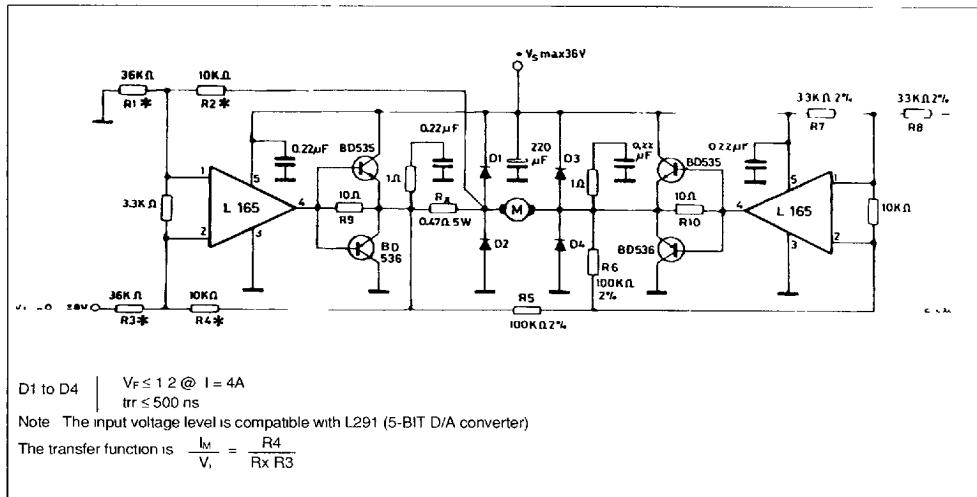


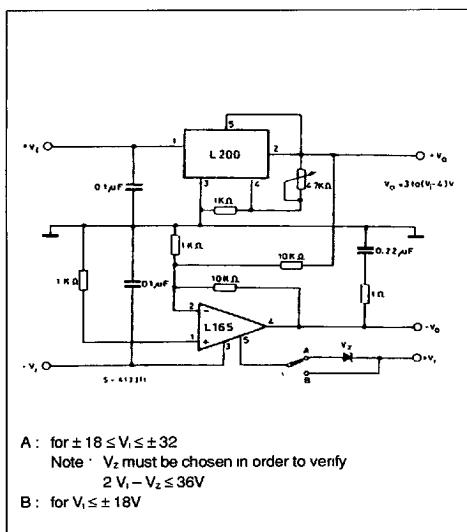
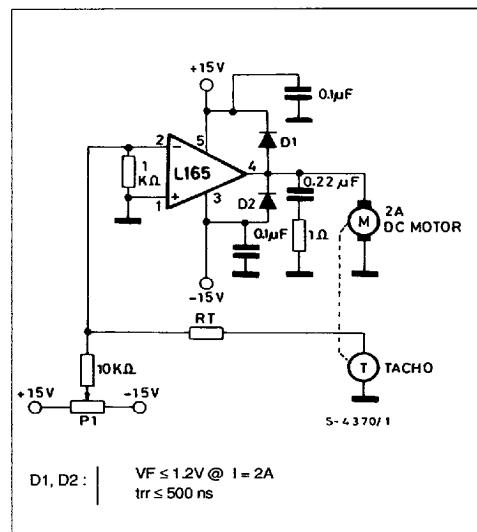
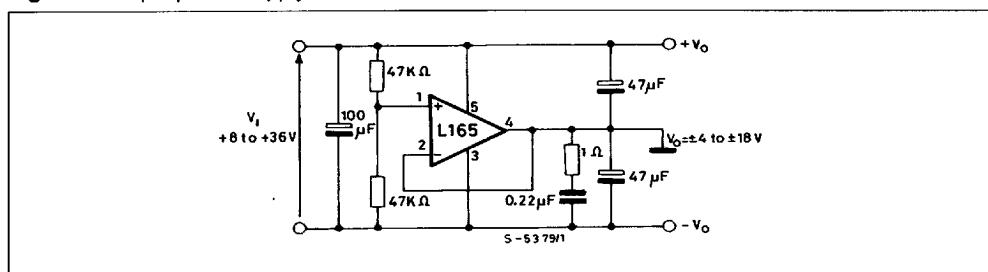
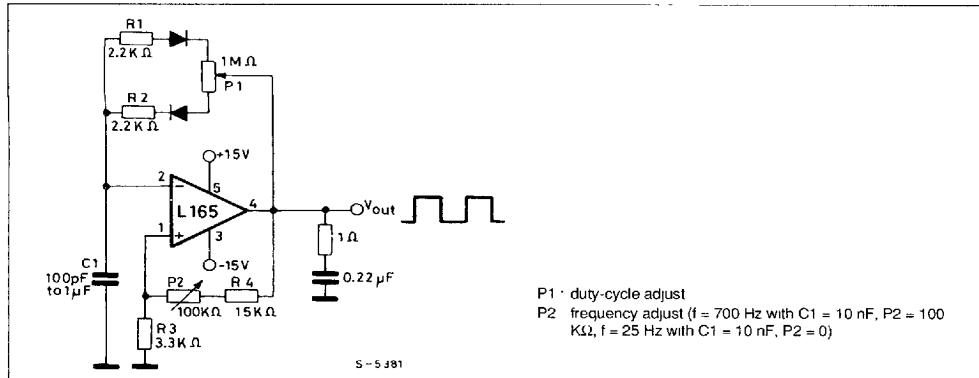
Figure 11 : High current tracking regulator.**Figure 12 : Bidirectional speed control of DC motor (Compensation networks not shown).****Figure 13 : Split power supply.**

Figure 14 : Power squarewave oscillator with independent adjustments for frequency and duty-cycle.



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