

Description

The PUMA 2US2500 is a Mixed Technology Puma 2 Module comprising of 2 x 128K8 UVEPROM's and 2 x 32K8 SRAMs. The device is user configurable as 8 and 16 bit wide. The UVEPROM is available in speeds ranging from 100 to 250ns and has Fast Page Programming of 14 sec (typ). The SRAM has speeds ranging from 85 to 150ns and has a completely static operation. Both devices have inputs and outputs which are TTL compatible.

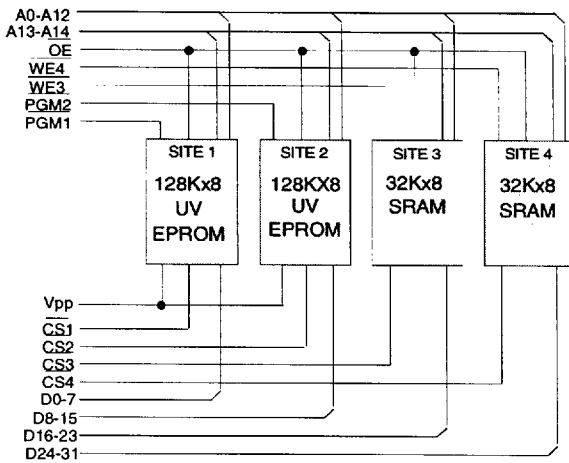
May be screened in accordance with MIL-STD-883.

2,097,152 bit UV-EPROM and 524,288 bit SRAM

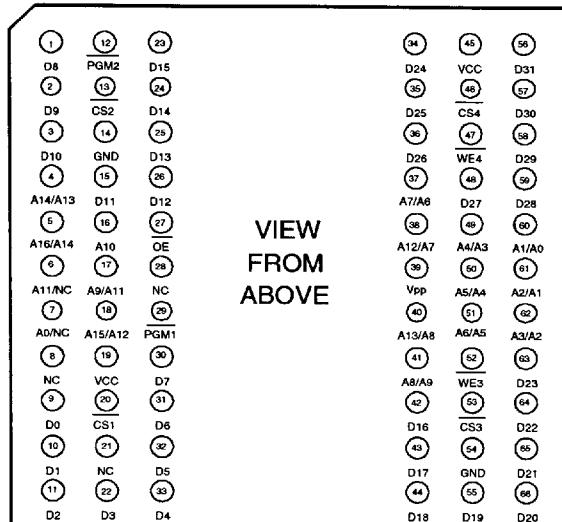
Features

- Output user configurable as 8 / 16 bit wide.
 - Average Power UVEPROM 315 / 585 mW(max).
SRAM 425 / 805 mW (max).
 - Standby Power 410 μ W(typical) - CMOS levels.
 - On-board decoupling capacitors.
 - All Inputs and Outputs TTL Compatible.
 - *EPROM Data* Access times of 100 to 250 ns.
Fast Page Programming of 14 sec (typ).
Programming Voltage of 12.5V \pm 0.3V
 - *SRAM Data* Access times of 85 to 150 ns.
Completely Static Operation

Block Diagram



Pin Definition



Note: Some pins in the above table have been allocated two functions. Where this is the case, the functions specified refer to the EPROM pinout and SRAM pinout respectively; for example, pin 41, allocated A8/A9, connects to A8 on the EPROMs, and to A9 on the SRAMs.

Pin Functions

A0~A16	Address Inputs	D0~D31	Data Input/Output
CS1~4	Chip Selects	OE	Output Enable
WE3~4	Write Enables	PGM1~2	Programming Enables
V_{PP}	Programming Voltage	V_{cc}	Power(+5V)
GND	Ground		

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DC OPERATING CONDITIONS

The operation of the UV EPROMs is obviously different from the operation of the SRAMs. For this reason the technical data which follows is separated into an EPROM section (pages 3 to 10) and a SRAM section (pages 11 to 15), with both 8 and 16 bit modes covered for both types of memory. Note that the DC Characteristics in both sections are for the **entire** module, irrespective of whether they are in the EPROM part or the SRAM part.

Absolute Maximum Ratings ⁽¹⁾

Temperature Under Bias	T_{OPR}	-55 to +125 °C
Storage Temperature	T_{STG}	-65 to +150 °C
Voltage on Any Pin with respect to GND ⁽²⁾	V_{IN}	-0.6 to +7.0 V
Voltage on V_{PP} pin with respect to GND ⁽³⁾	V_{PT}	-2.0 to +14.0 V

Notes (1) Stresses above those listed may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions above those indicated in this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

(2) V_{IN} and V_{PT} minimum may be -1.0V for pulse width > 50ns.

Recommended Operating Conditions

			min	typ	max	
Supply Voltage	V_{CC}		4.75	5.0	6.25	V
Programming Voltage	Read	V_{PPR}	4.75	5.0	5.25	V
	Program	V_{PPW}	12.2	12.5	12.8	V
Input High Voltage	TTL	V_{IH}	2.2	-	$V_{CC}+1.0$	V
	CMOS	V_{IHC}	0.7 V_{CC}	-	$V_{CC}+1.0$	V
Input Low Voltage	TTL	V_{IL}	-0.3	-	0.8	V
	CMOS	V_{ILC}	-0.3	-	0.3	V
Operating Temperature	T_A		0	-	70	°C
	T_{AI}		-40	-	85	°C (-I suffix)
	T_{AM}		-55	-	125	°C (-M, MB suffix)

Capacitance ($T_A=25^\circ C$, $f=1\text{MHz}$) These parameters are calculated, not measured.

Parameter	Symbol	Test Condition	typ	max	Unit
Input Capacitance A1~10, A12~16, \overline{OE}	C_{IN1}	$V_{IN}=0V$	-	54	pF
	C_{IN2}	$V_{IN}=0V$	-	40	pF
	C_{IN3}	$V_{IN}=0V$	-	40	pF
	C_{IN4}	$V_{IN}=0V$	-	34	pF
Output Capacitance D0~D15	C_{OUT1}	$V_{OUT}=0V$	-	25	pF
D16~D31	C_{OUT2}	$V_{OUT}=0V$	-	15	pF

UV EPROM DATA SECTION

DC Electrical Characteristics

Read ($T_A = -55^\circ C$ to $+125^\circ C$, $V_{CC} = 5V \pm 5\%$, $V_{PP} = V_{CC}$)

Parameter	Symbol	Test Condition	min	typ ⁽²⁾	max	Unit
I/P Leakage Current PGM1~2, CS1~2	I_{U1}	$V_{CC} = V_{CC}$ max, $V_{IN} = 0V$ or $V_{CC}, V_{PP} = V_{PPL}$	-	-	± 8	μA
	I_{U2}	$V_{CC} = V_{CC}$ max, $V_{IN} = 0V$ or V_{CC}	-	-	± 4	μA
Output Leakage Current D0~D15	I_{LO1}	$V_{CC} = V_{CC}$ max, $V_{OUT} = 0V$ or V_{CC}	-	-	± 2	μA
V_{PP} Leakage Current	I_{PPS}	$V_{PP} - V_{CC}$	-	2	40	μA
V_{CC} Operating Current 16bit	I_{CC16}	$\overline{CS}^{(6)} = V_{IL}, I_{OUT} = 0mA$, Inputs Static.	-	-	66	mA
V_{CC} Average Read Current 16bit	I_{CC016}	$\overline{CS}^{(6)} = V_{IL}, I_{OUT} = 0mA, f = 5MHz$	-	-	106	mA
	I_{CC08}	As above	-	-	57	mA
V_{CC} Average Read Current 16bit	I_{CCA16}	$\overline{CS}^{(6)} = V_{IL}, I_{OUT} = 0mA, f = 10MHz$	-	-	146	mA
	I_{CCA8}	As above	-	-	77	mA
Standby Supply Current TTL	I_{SB1}	$\overline{CS}^{(6)} = V_{IH}$	-	-	8	mA
	I_{SB2}	$\overline{CS}^{(6)} = V_{IHC}, V_{ILC} \geq V_{IN} \geq V_{IHC}$	-	-	4	mA
V_{PP} Voltage During Read	V_{PPL}	Programming is inhibited if $V_{PP} = V_{PPL}$	4.75	-	5.25	V
Output Low Voltage D0~D15	V_{OL1}	$I_{OL} = 2.1mA$	-	-	0.45	V
Output High Voltage TTL loading	V_{OH1}	$I_{OH} = -1.0mA$ (D0~D15)	2.4	-	-	V
CMOS loading	V_{OH2}	$I_{OH} = -100\mu A$ (D0~D15)	$V_{CC} - 0.7$	-	-	V

Program ($T_A = 25^\circ C \pm 5^\circ C$, $V_{CC} = 6.0V \pm 0.25$, $V_{PP} = 12.5V \pm 0.3V$)⁽⁷⁾

Parameter	Symbol	Test Condition	min	typ ⁽²⁾	max	Unit
I/P Leakage Current A0~A16, OE	I_{U1}	$V_{CC} = V_{CC}$ max, $V_{IN} = 0V$ or $V_{CC}, V_{PP} = V_{PPL}$	-	-	± 8	μA
	I_{U2}	$V_{CC} = V_{CC}$ max, $V_{IN} = 0V$ or V_{CC}	-	-	± 4	μA
Output Leakage Current D0~D15	I_{LO}	$V_{CC} = V_{CC}$ max, $V_{OUT} = 0V$ or V_{CC}	-	-	± 2	μA
V_{CC} Program Current 16bit	I_{CCP16}	$\overline{CS}^{(1)} = \overline{PGM}^{(1)} = V_{IL}$, Program in progress	-	-	66	mA
	I_{CCP8}	As above	-	-	37	mA
V_{PP} Byte Program Current 16bit	I_{PPB16}	$V_{PP} = V_{PPH}$, Byte Program in progress	-	-	80	mA
	I_{PPB8}	As above	-	-	40	mA
V_{PP} Page Program Current 16bit	I_{PPP16}	$V_{PP} = V_{PPH}$, Page Program in progress	-	-	100	mA
	I_{PPP8}	As above	-	-	50	mA
V_{CC} Voltage During Program	V_{CCP}		5.75	6.0	6.25	V
V_{PP} Voltage During Program	V_{PPH}		12.2	12.5	12.8	V
Output Low Voltage D0~D15	V_{OLV}	$I_{OL} = 2.1mA$, Verify in progress	-	-	0.45	V
Output High Voltage D0~D15	V_{OHV}	$I_{OH} = -400\mu A$, Verify in progress	2.4	-	-	V

Notes (1) UV EPROM devices are controlled by input lines $\overline{CS1}$, $\overline{CS2}$, $\overline{PGM1}$, $\overline{PGM2}$ and \overline{OE} .

(2) Typical figures are measured at $25^\circ C$ and nominal V_{CC}

(3) Maximum program current is the sum of I_{CC} and I_{PP} .

(4) **CAUTION:** the PUMA 2US2500 must not be removed from or inserted into a socket when V_{CC} or V_{PP} is applied.

(5) During the above operations, $\overline{CS3} \sim \overline{4}$ and $\overline{WE3} \sim \overline{4}$ must be held at a logic high level.

(6) \overline{CS} above are accessed through CS1~2. These inputs must be operated simultaneously for 16 bit operation and singly for 8 bit mode.

(7) Information stated for design purposes only.

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Operating Modes

This table shows the logic inputs required to control the operating modes of each EPROM on the PUMA2US2500.

Mode	\overline{CS}	\overline{OE}	\overline{PGM}	V_{PP}	V_{CC}	Outputs
Read	0	0	1	5V	5V	Data Out
Output Disable	0	1	1	5V	5V	High Z
Standby	1	X	X	5V	5V	High Z
Program	0	1	0	12.5V	6V	Data In
Program Verify	0	0	1	12.5V	6V	Data Out
Page Data Latch	1	0	1	12.5V	6V	Data In
Page Program	1	1	0	12.5V	6V	High Z
Program Inhibit	0	0	0	12.5V	6V	High Z
	0	1	1	12.5V	6V	
	1	0	0	12.5V	6V	
	1	1	1	12.5V	6V	

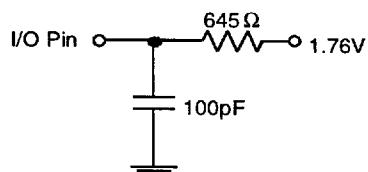
1 = V_{IH}
 0 = V_{IL}
 X = Don't Care

Note: \overline{CS} is accessed through $\overline{CS1}$ and $\overline{CS2}$ while $\overline{CS3}$ and $\overline{CS4}$ are both held high. Also, where TTL or CMOS levels are applied they are used on all Chip Selects at the same time i.e. if $CS1,2 = V_{IL}$ then $CS3,4 = V_{IH}$

AC Test Conditions

Output Load

- * Input pulse levels: 0V to 3.0V.
- * Input and Output timing reference levels: 1.5V
- * Input rise and fall times: -10ns.
- * Output load : see diagram
- * Module is tested in 8 bit mode.



AC Characteristics**Read**

Parameter	Symbol		-10	min	max	-12	min	max	-15	min	max	Unit
Address to Output Delay	t_{ACC}		-	100	-	120	-	150	ns			
Chip Select to Output Delay	t_{CS}		-	100	-	120	-	150	ns			
Output Enable to Output Delay	t_{OE}		-	60	-	60	-	70	ns			
OE or CS High to Output Float ⁽¹⁾	t_{DF}	0	50	0	50	0	60	ns				
Output Hold from Address, \overline{CS} or \overline{OE}	t_{OH}	0	-	0	-	0	-	ns				

Parameter	Symbol		-17	min	max	-20	min	max	-25	min	max	Unit
Address to Output Delay	t_{ACC}		-	170	-	200	-	250	ns			
Chip Select to Output Delay	t_{CS}		-	170	-	200	-	250	ns			
Output Enable to Output Delay	t_{OE}		-	70	-	80	-	100	ns			
OE or \overline{CS} High to Output Float ⁽¹⁾	t_{DF}	0	60	0	60	0	60	ns				
Output Hold from Address, \overline{CS} or \overline{OE}	t_{OH}	0	-	0	-	0	-	ns				

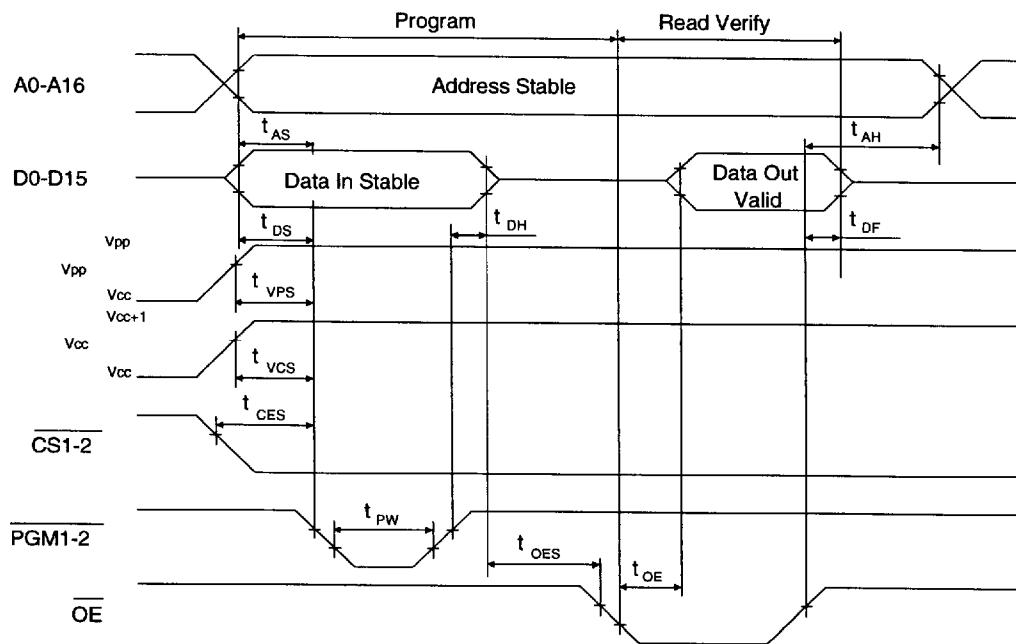
Notes: (1) t_{DFZ} is defined as the time at which the outputs achieve the open circuit conditions and is not referenced to output voltage levels. This parameter is sampled and not 100% tested.

Write

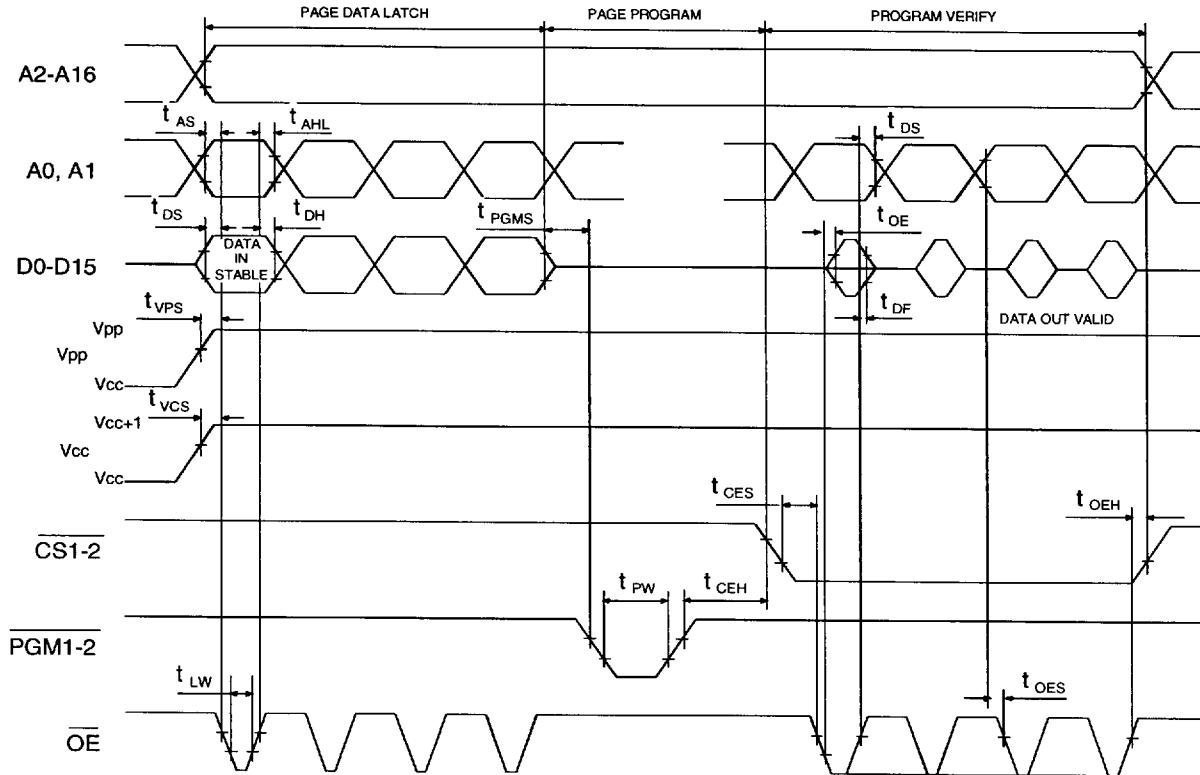
Parameter	Symbol	min	typ	max	Unit
Address Setup Time	t_{AS}	2	-	-	μs
Output Enable Setup Time	t_{OES}	2	-	-	μs
Output Enable Hold Time	t_{OEH}	2	-	-	μs
Data Setup Time	t_{DS}	2	-	-	μs
Address Hold Time	t_{AH}	0	-	-	μs
	t_{AHL}	2	-	-	μs
Data Hold Time	t_{DH}	2	-	-	μs
Output Enable High to Output Float Delay ⁽¹⁾	t_{DF}	0	-	130	ns
V_{PP} Setup Time	t_{VPS}	2	-	-	μs
V_{CC} Setup Time	t_{VCS}	2	-	-	μs
Program Initial Program Pulse Width ⁽²⁾	t_{PW}	0.19	0.2	0.21	ms
Program Overprogram Pulse Width ⁽³⁾	t_{OPW}	0.19	-	5.25	ms
Data Valid from Output Enable	t_{OE}	0	-	150	ns
Program Setup Time	t_{PGMS}	2	-	-	μs
Chip Select Setup Time	t_{CES}	2	-	-	μs
Chip Select Hold Time	t_{CSH}	2	-	-	μs
Output Enable Pulse Width during Data Latch	t_{LW}	1	-	-	μs

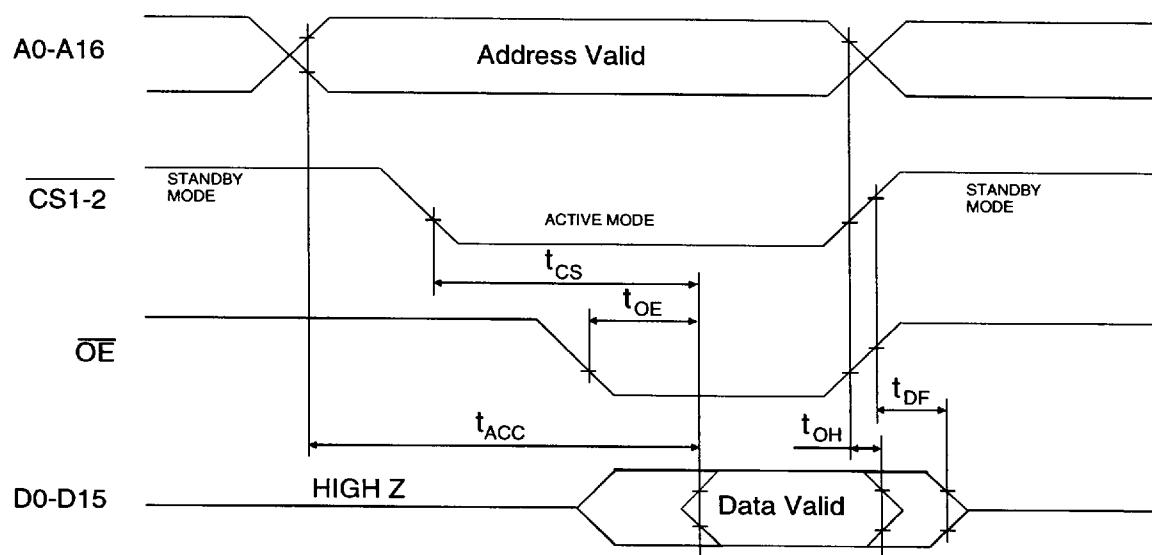
Notes (1) Defines the time at which the output achieves the open circuit condition and is no longer driven.
(2) The value of this pulse is 0.2 ms ± 5%.
(3) Length of this pulse may vary as a function of the iteration counter value n.

Single Byte Programming



Page Mode Programming



Read Cycle Timing Waveform

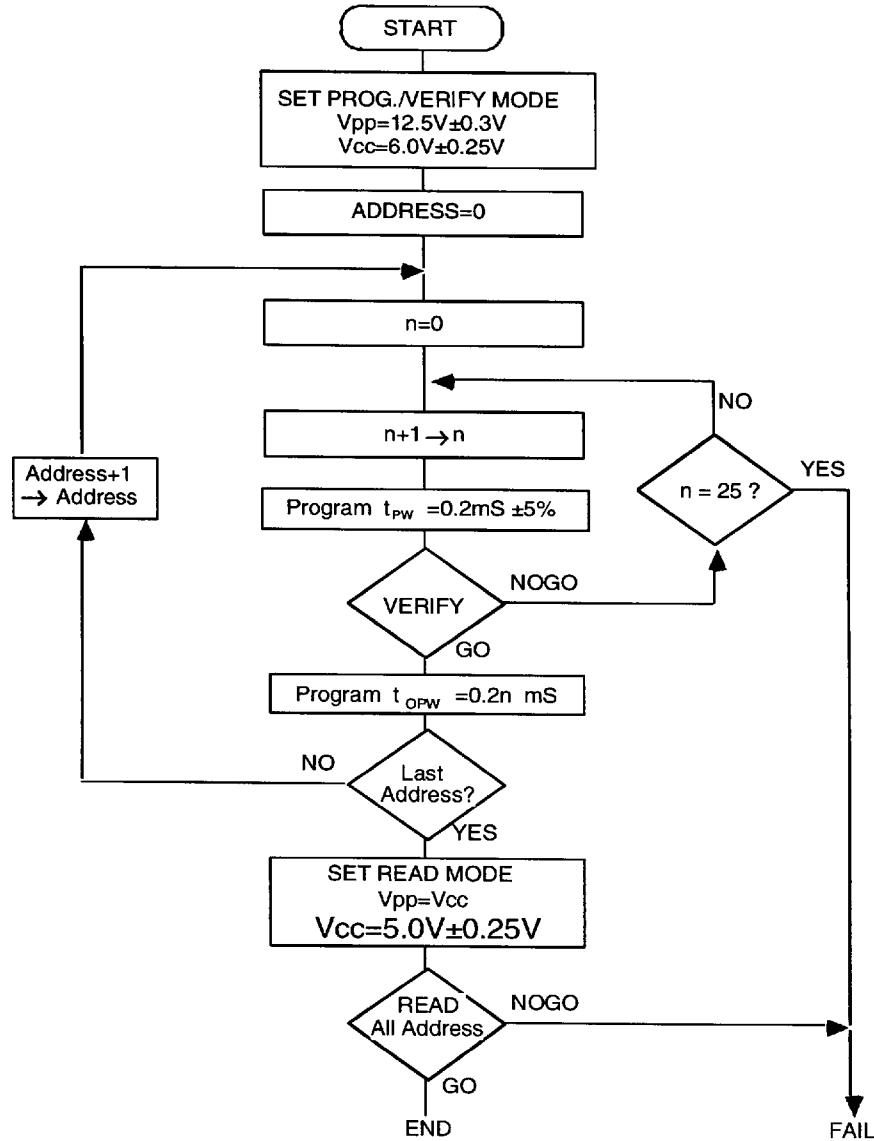
DEVICE OPERATION

High Performance Programming Algorithm

The PUMA 2US2500 can be programmed using either of the algorithms shown below. These allow faster programming times without stressing the device or causing deterioration in Data Retention Time. Two methods are described here, Single Byte and Page Mode; see the Truth Table on page 4 for selection of these modes.

Single Byte

When the Program logic conditions are satisfied, the location is designated by A0~A16, and the data to be programmed is applied 8 bits in parallel on D0~D7. In this state, Byte programming is completed when PGM is at a low level.



**NOTE: THE ALGORITHM SHOWN HERE MUST BE USED
TO ENSURE CORRECT PROGRAMMING OF THE
PUMA 2US2500. THIS MAXIMISES THE DATA
RETENTION TIME OF THE DEVICE AND DOES
NOT STRESS THE MEMORY CELLS.**

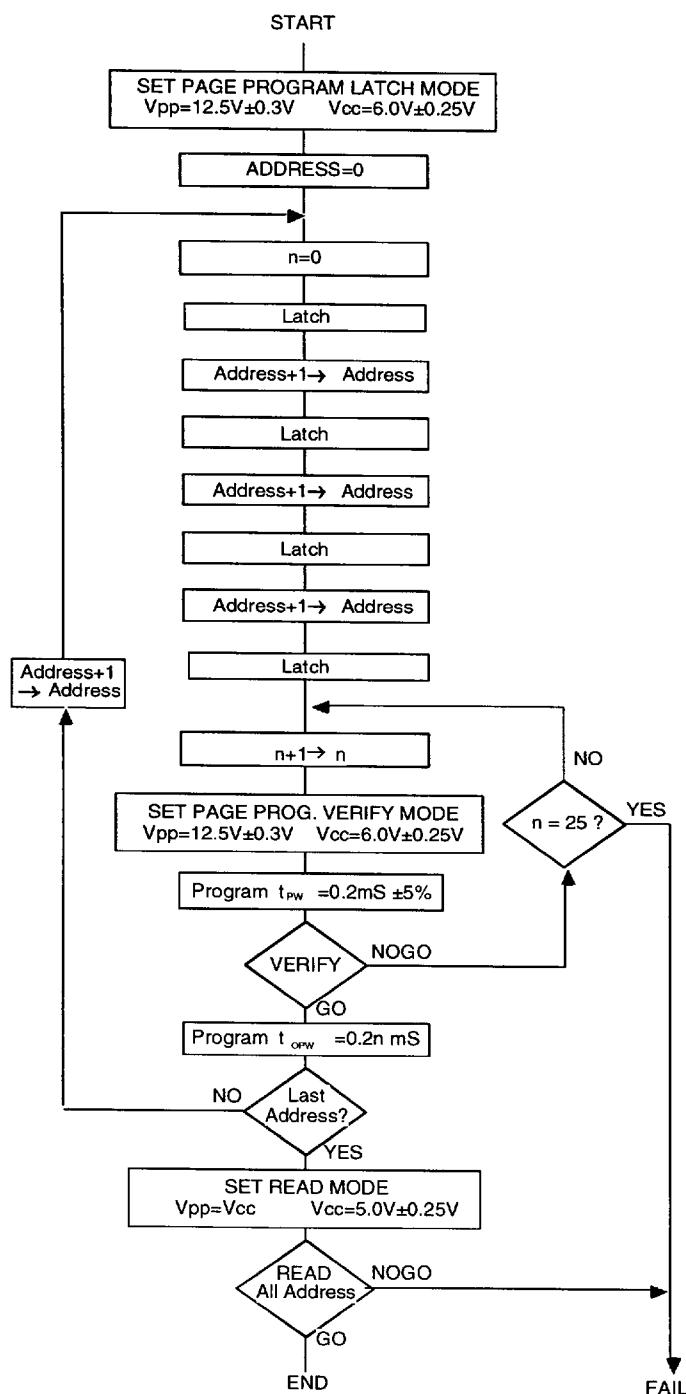
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Page Mode

Page Mode allows 4 bytes of data to be simultaneously programmed. The destination address for a Page Programming operation must reside on the same page i.e. A2~A16 must not change. When the logic conditions in the Truth Table are satisfied, Page Mode Programming is activated. The four locations in the same page are designated by A0~A1, and the data is applied in parallel on D0~D7. In this state the data latch (4 bytes) is completed, and the data is programmed when OE is high. Programming is completed when PGM is low.



Programming Notes

Upon delivery, or after each erasure, the PUMA 2US2500 has all 2,097,152 bits in the ONE or HIGH state. ZEROS are loaded into the devices through the procedure of programming.

The UV EPROMs are byte/page programmable using a fast high reliability programming algorithm, with complete device programming being possible in 14 seconds (in 16 bit mode). Both of these devices are erased by irradiating them with ultra violet light via the window on the top of the LCC packages. Note that normally, in order to automatically match UV EPROM devices to their correct programming algorithm, both manufacturer and device codes are accessible by placing 12.0V onto address line A9. On this mixed memory technology PUMA this is not **possible**, so the actual device type and relevant codes are given below:

Manufacturer	Code	Device Number	Code
Hitachi	07H	HN27C101A	38H

This mode is entered when $12.5V \pm 0.3V$ is applied to the V_{PP} pin, $CS1 \sim 2$ and $PGM1 \sim 2$ are at V_{IL} and OE is at V_{IH} , as shown on the Table on page 4.

The algorithms reduce programming time by using 200µs pulses followed by byte verification to determine if the byte has been successfully programmed. If the data does not verify, up to 25 such pulses (n) can be applied, after which, if verification fails, programming stops. This process is repeated for each memory location within the PUMA 2US2500. After successful programming each memory location is given an overprogram pulse of n times 0.2 ms duration to ensure that all bits have an adequate margin.

The algorithms program at $V_{cc} = 6.0V$ in order to ensure that each EPROM bit is programmed to a sufficiently high threshold voltage. After programming is complete, all bytes are compared with the original data with $V_{cc} = 5.0V \pm 5\%$.

In order to overcome the voltage drop caused by the inductive effects of the printed circuit board on which the PUMA 2US2500 is used, it is recommended that a 4.7µF electrolytic capacitor is used between V_{cc} and GND for every two devices. This capacitor should be placed close to the point where the power supply is routed to the UV EPROM array.

Erase

Complete erasure of the PUMA 2US2500 is performed by exposure to an ultraviolet light source giving a dosage of 15WS/cm². This dosage can be obtained by using an ultraviolet lamp with a wavelength of 2537 Å at a minimum intensity of 12,000µW/cm², for approximately 15~20 minutes. The PUMA 2US2500 should be directly under and about 1 inch from the light source.

Note that sunlight and fluorescent light may contain sufficient ultraviolet light to erase the programmed information. Although erasure times will be much longer at these levels, the transparent lids on this module should be covered with an opaque label to realise maximum system reliability.

SRAM DATA SECTION

DC Electrical Characteristics ($V_{CC}=5V \pm 5\%$, $T_A=-55^{\circ}C$ to $+125^{\circ}C$)

Read and Write

Parameter	Symbol	Test Condition	min	typ ⁽¹⁾	max	Unit
I/P Leakage Current	I_{L13}	$V_{IN}=0V$ to V_{CC}	-	-	± 8	μA
	I_{L14}	As above	-	-	± 4	μA
Output Leakage Current	I_{LO2}	$CS^{(2)}=V_{IH}$ or $\overline{OE}=V_{IH}$, $V_{I/O}=0V$ to V_{CC}	-	-	± 2	μA
Operating Supply Current	I_{CC16A}	$CS^{(2)}=V_{IL}$, $I_{I/O}=0mA$, Inputs Static	-	18	60	mA
Average Supply Current	I_{CCV16}	$CS^{(2)}=V_{IL}$, Minimum cycle, $I_{I/O}=0mA$	-	102	142	mA
	I_{CCV8}	As above	-	55	75	mA
Standby Supply Current	I_{SB1}	$CS^{(2)}=V_{IH}$	-	2	8	mA
	I_{SB2}	$CS^{(2)} \square V_{IHC}$, $V_{ILC} \square V_{IN} \square V_{IHC}$	-	0.085	4	mA
Output Voltage Low	V_{OL}	$I_{OL}=2.1mA$	-	-	0.4	V
Output Voltage High	V_{OH}	$I_{OH}=-1.0mA$	2.4	-	-	V

Notes: (1) Typical values are at $V_{CC}=5.0V$, $T_A=25^{\circ}C$ and specified loading.

- (2) \overline{CS} above is accessed through $CS3 \sim 4$. These inputs must be operated simultaneously for 16 bit mode and singly for 8 bit mode.
- (3) **CAUTION:** the PUMA 2US2500 must not be removed from or inserted into a socket when V_{CC} or V_{PP} is applied.
- (4) During the above operation, $CS1 \sim 2$ and $WE1 \sim 2$ must be held at a logic high level.
- (5) SRAMs are controlled by lines $CS3$, $CS4$, $WE3$, $WE4$ and \overline{OE} .

Operating Modes

This Table shows the inputs required to control the operating modes of the SRAMs on the PUMA 2US2500 and shows the SRAMs operating in 16 bit mode. If 8 bit operation is required, $CS3 \sim 4$ and $WE3 \sim 4$ are controlled independently.

Note that during 16 bit operation, $CS1 \sim 2$ and $WE1 \sim 2$, which control the EPROM devices on the PUMA 2US2500, must be at a high level.

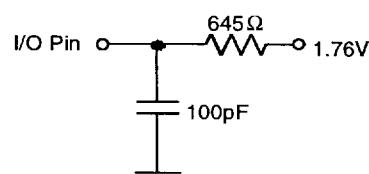
Mode	$CS3 \sim 4$	\overline{OE}	$WE3 \sim 4$	$D16 \sim D31$	Reference Cycle
Standby	1	X	X	High Z	-
Read	0	0	1	D_{OUT}	Read Cycle 1,2,3
Write	0	1	0	D_{IN}	Write Cycle 1
Write	0	0	0	D_{IN}	Write Cycle 2

1 = V_{IH} 0 = V_{IL} X = V_{IL} or V_{IH}

AC Test Conditions

Output Load

- * Input pulse levels: 0.45V to 2.4V.
- * Input and Output timing reference levels: 0.8V and 2.0V
- * Input rise and fall times: -10ns.
- * Output load : see diagram
- * Module is tested in 8 bit mode.

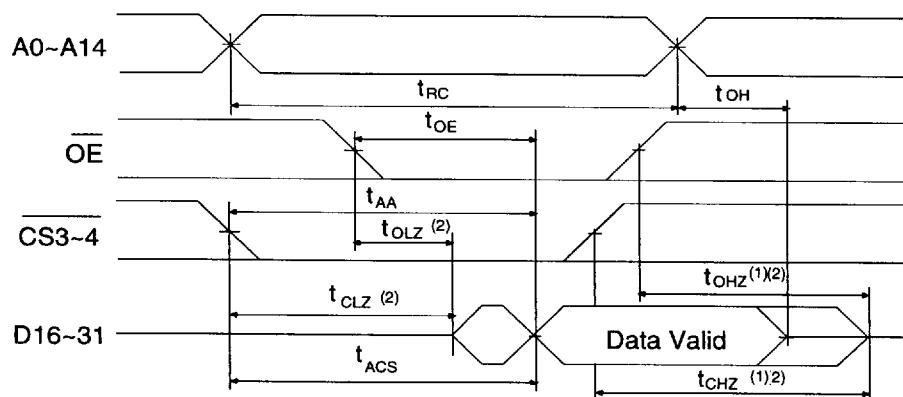
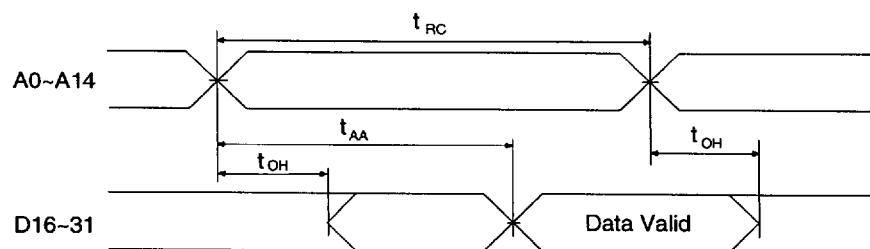
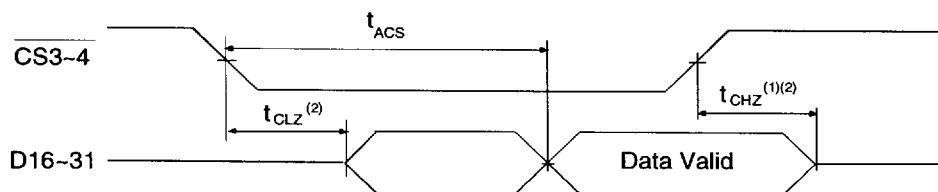


Electrical Characteristics & Recommended AC Operating Conditions**Read Cycle**

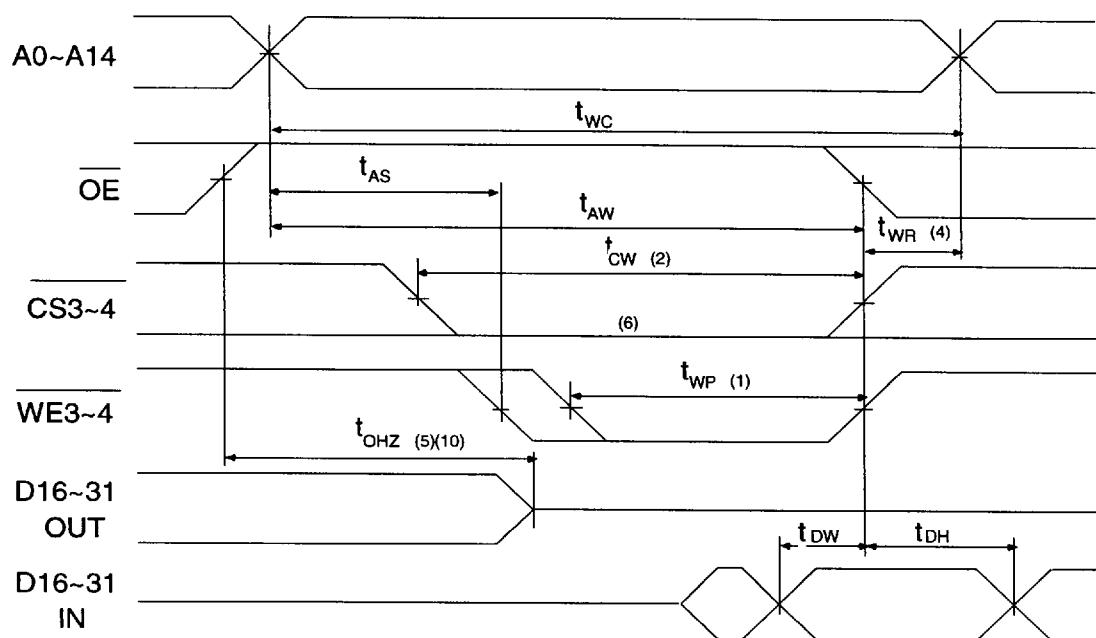
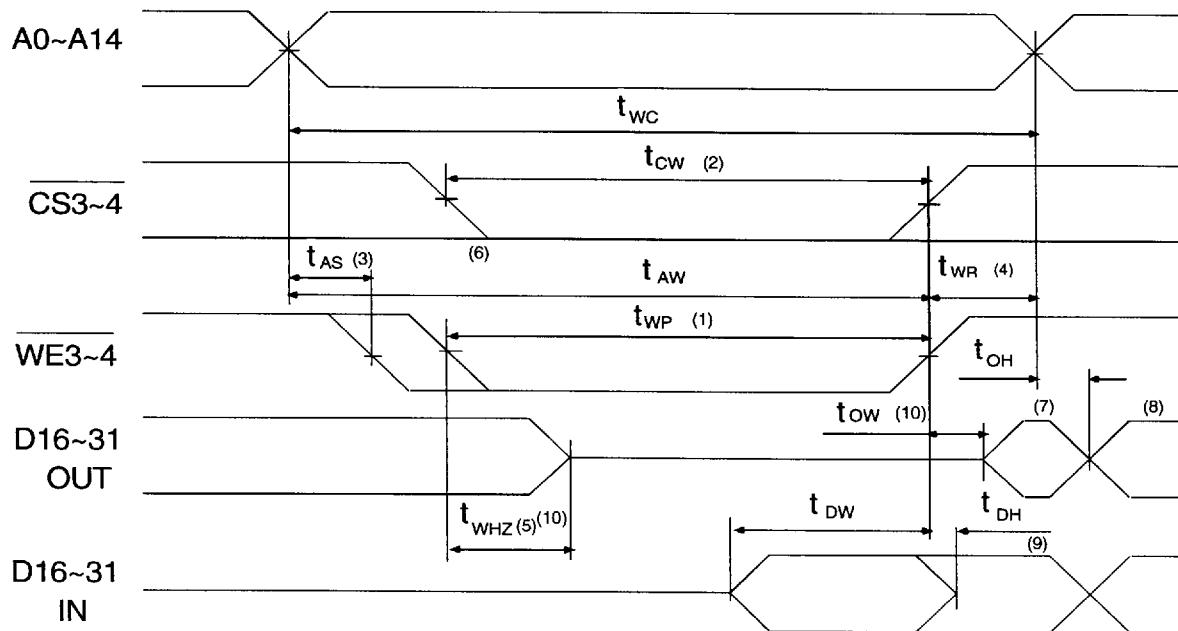
Parameter	Symbol	-85 min	-85 max	-10 min	-10 max	-12 min	-12 max	-15 min	-15 max	Unit
Read Cycle Time	t_{RC}	85	-	100	-	120	-	150	-	ns
Address Access Time	t_{AA}	-	85	-	100	-	120	-	150	ns
Chip Select Access Time	t_{ACS}	-	85	-	100	-	120	-	150	ns
Output Enable to Output Valid	t_{OE}	-	45	-	50	-	60	-	70	ns
Output Hold from Address Change	t_{OH}	5	-	10	-	10	-	10	-	ns
Chip Selection to Output in Low Z ⁽³⁾	t_{CLZ}	10	-	10	-	10	-	10	-	ns
Output Enable to Output in Low Z ⁽³⁾	t_{OLZ}	5	-	5	-	5	-	5	-	ns
Chip Deselection to Output in High Z ⁽³⁾	t_{CHZ}	0	30	0	35	0	40	0	50	ns
Output Disable to Output in High Z ⁽³⁾	t_{OHZ}	0	30	0	35	0	40	0	50	ns

Write Cycle

Parameter	Symbol	-85 min	-85 max	-10 min	-10 max	-12 min	-12 max	-15 min	-15 max	Unit
Write Cycle Time	t_{WC}	85	-	100	-	120	-	150	-	ns
Chip Selection to End of Write	t_{CW}	75	-	80	-	85	-	100	-	ns
Address Valid to End of Write	t_{AW}	75	-	80	-	85	-	100	-	ns
Address Setup Time	t_{AS}	0	-	0	-	0	-	0	-	ns
Write Pulse Width	t_{WP}	60	-	60	-	70	-	90	-	ns
Write Recovery Time	t_{WR}	10	-	0	-	0	-	0	-	ns
Write to Output in High Z ⁽¹¹⁾	t_{WHZ}	0	30	0	35	0	40	0	50	ns
Data to Write Time Overlap	t_{DW}	40	-	40	-	50	-	60	-	ns
Data Hold from Write Time	t_{DH}	0	-	0	-	0	-	0	-	ns
Output Disable to Output in High Z ⁽¹¹⁾	t_{OHZ}	0	30	0	35	0	40	0	50	ns
Output Active from End of Write	t_{OW}	5	-	5	-	5	-	5	-	ns

Read Cycle 1 Timing Waveform (3)**Read Cycle 2 Timing Waveform (3)(4)(6)****Read Cycle 3 Timing Waveform (3)(5)(6)**

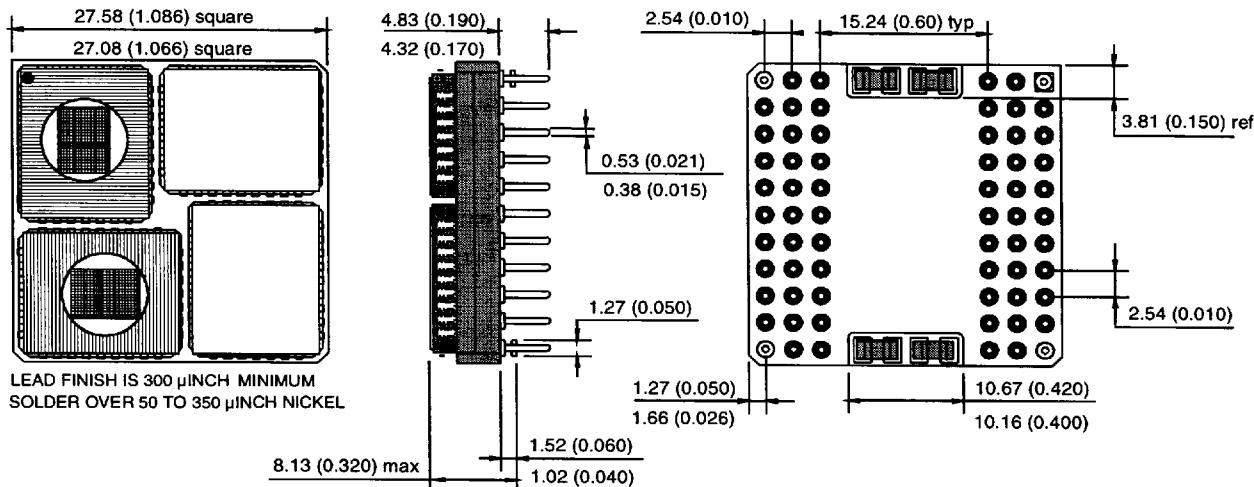
- Notes:
- (1) t_{CHZ} and t_{OHZ} are defined as the time at which the outputs achieve the open circuit conditions and are not referenced to output voltage levels.
 - (2) These parameters are sampled and not 100% tested.
 - (3) WE is High for Read Cycle.
 - (4) Device is continuously selected, $\overline{CS}=V_{IL}$.
 - (5) Address valid prior to or coincident with \overline{CS} transition Low.
 - (6) $\overline{OE}=V_{IL}$.

Write Cycle 1 Timing Waveform (\overline{OE} Clock)**Write Cycle 2 Timing Waveform (\overline{OE} Low)**

AC Write Characteristics Notes

- (1) A write occurs during the overlap (t_{WP}) of a low Chip Select and a low Write Enable. A write begins at the later transition of Chip Select going low or Write Enable going low. A write ends at the earlier transition of Chip Select going high or Write Enable going high. t_{WP} is measured from the beginning of write to the end of write.
- (2) t_{CW} is measured from Chip Select going low to the end of write cycle.
- (3) t_{AS} is measured from the address valid to the beginning of write.
- (4) t_{WR} is measured from the earlier of Chip Select or Write Enable going high to the end of write cycle.
- (5) During this period, I/O pins are in the output state. Input signals out of phase must not be applied.
- (6) If the Chip Select low transition occurs simultaneously with the Write Enable low transition or after the Write Enable low transition, outputs remain in a high impedance state.
- (7) D_{OUT} is in the same phase as written data of this write cycle.
- (8) D_{OUT} is the read data of next address.
- (9) If Chip Select is low during this period, I/O pins are in the output state. Input signals out of phase must not be applied to I/O pins.
- (10) This parameter is sampled and not 100% tested.
- (11) t_{OHZ} and t_{WHZ} are defined as the time at which the outputs achieve the open circuit conditions and are not referenced to output voltage levels.

Package Details - Dimensions in Inches (Millimeters)



Military Screening Procedure

Module Screening Flow for high reliability product, in accordance with MIL-STD-883, is shown below

MB MODULE SCREENING FLOW		
SCREEN	TEST METHOD	LEVEL
Visual and Mechanical		
External visual Temperature cycle	2017 Condition B (or manufacturers equivalent) 1010 Condition C (10 Cycles, -65°C to +150°C)	100% 100%
Burn-In		
Pre Burn-in Electrical Burn-In	Per Applicable device Specifications at $T_A = +25^\circ\text{C}$ (optional) Method 1015, Condition D, $T_A = +125^\circ\text{C}$	100% 100%
Final Electrical Tests	Per applicable Device Specification	
Static(dc)	a) @ $T_A = +25^\circ\text{C}$ and power supply extremes b) @ temperature and power supply extremes	100% 100%
Functional	a) @ $T_A = +25^\circ\text{C}$ and power supply extremes b) @ temperature and power supply extremes	100% 100%
Switching(ac)	a) @ $T_A = +25^\circ\text{C}$ and power supply extremes b) @ temperature and power supply extremes	100% 100%
Percent Defective Allowable (PDA)	Calculated at Post Burn-in at $T_A = +25^\circ\text{C}$	10%
Quality Conformance	Per applicable Device Specification	Sample
External Visual	2009 Per HMP or customer specification	

Ordering Information**PUMA2US2500MB-1085**

	SRAM Speed	85 = 85 ns 10 = 100 ns 12 = 120 ns 15 = 150 ns
	EPROM Speed	10 = 100 ns 12 = 120 ns 15 = 150 ns 17 = 170 ns 20 = 200 ns 25 = 250 ns
	Temperature range	Blank = Commercial Temperature Range. I = Industrial Temperature Range. M = Military Temperature Range.
		MB = Screened in accordance with MIL-STD-883
Organisation	US2500	= 128K x 16 EPROM on sites 1 and 2 32K x 16 SRAM on sites 3 and 4 (both user configurable as x8)
Module Type	PUMA 2	= Ceramic 66 Pin Grid Array