

## Single Phase Half Controlled Bridges with freewheeling diode

**PSCH 125**

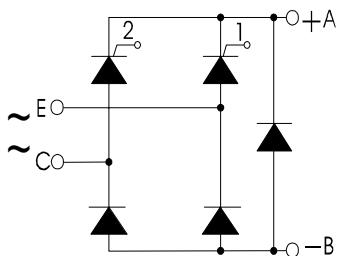
$I_{dAV}$   
 $V_{RRM}$

= 123 A  
= 400-1600 V

### Preliminary Data Sheet

$V_{RSM}$	$V_{RRM}$	Type
$V_{DSM}$	$V_{DRM}$	
500	400	PSCH 125/04
900	800	PSCH 125/08
1300	1200	PSCH 125/12
1500	1400	PSCH 125/14
*1700	*1600	PSCH 125/16

\* Delivery on request



Symbol	Test Conditions	Maximum Ratings		
$I_{dAV}$	$T_C = 85^\circ\text{C}$ , module	123	A	
$I_{FSM}, I_{TSM}$	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0$ $T_{VJ} = T_{VJM}$ $V_R = 0$	1500 1600 1350 1450	A	
$\int i^2 dt$	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0$ $T_{VJ} = T_{VJM}$ $V_R = 0$	11 200 10 750 9100 8830	$\text{A}^2 \text{s}$	
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 400\text{Hz}$ , $t_p = 200\mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 \text{ A}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	repetitive, $I_T = 50 \text{ A}$ non repetitive, $I_T = 1/3 \cdot I_{dAV}$	150	$\text{A}/\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$ , method 1 (linear voltage rise)	1000	$\text{V}/\mu\text{s}$	
$P_{GM}$	$T_{VJ} = T_{VJM}$ $I_T = I_{TAVM}$	$t_p = 30\mu\text{s}$ $t_p = 500\mu\text{s}$	$\leq 10$ $\leq 5$	W
$P_{GAVM}$			0.5	W
$V_{RGM}$			10	V
$T_{VJ}$			-40 ... + 125	$^\circ\text{C}$
$T_{VJM}$			125	$^\circ\text{C}$
$T_{stg}$			-40 ... + 125	$^\circ\text{C}$
$V_{ISOL}$	50/60 HZ, RMS $I_{ISOL} \leq 1 \text{ mA}$	$t = 1 \text{ min}$ $t = 1 \text{ s}$	2500 3000	$\text{V} \sim$
$M_d$	Mounting torque Terminal connection torque	(M6)	5 5	Nm
Weight	typ.		270	g

### Features

- Package with screw terminals
- Isolation voltage 3000 V~
- Planar glasspassivated chips
- Low forward voltage drop
- UL released, E 148688

### Applications

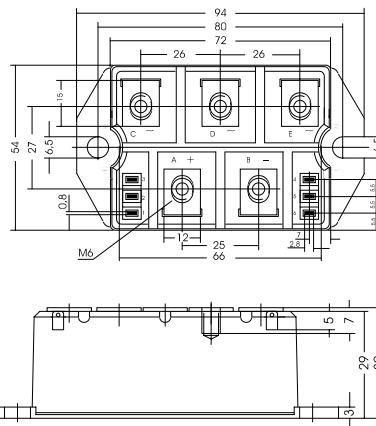
- Heat and temperature control for industrial furnaces and chemical processes
- Lighting control
- Motor control
- Power converter

### Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling capability
- High power density

### Package, style and outline

Dimensions in mm (1mm = 0.0394")



Symbol	Test Conditions		Characteristic Value		
$I_D, I_R$	$T_{VJ} = T_{VJM}$ , $V_R = V_{RRM}$ , $V_D = V_{DRM}$		$\leq$	5	mA
$V_T$	$I_T = 200A$ , $T_{VJ} = 25^\circ C$		$\leq$	1.57	V
$V_{TO}$	For power-loss calculations only ( $T_{VJ} = T_{VJM}$ )			0.85	V
$r_T$				3.5	$m\Omega$
$V_{GT}$	$V_D = 6V$	$T_{VJ} = 25^\circ C$	$\leq$	1.5	V
		$T_{VJ} = -40^\circ C$	$\leq$	1.6	V
$I_{GT}$	$V_D = 6V$	$T_{VJ} = 25^\circ C$	$\leq$	100	mA
		$T_{VJ} = -40^\circ C$	$\leq$	200	mA
$V_{GD}$	$T_{VJ} = T_{VJM}$	$V_D = 2/3 V_{DRM}$	$\leq$	0.2	V
$I_{GD}$	$T_{VJ} = T_{VJM}$	$V_D = 2/3 V_{DRM}$	$\leq$	5	mA
$I_L$	$T_{VJ} = 25^\circ C$ , $t_P = 30\mu s$		$\leq$	450	mA
	$I_G = 0.3A$ , $dI_G/dt = 0.3A/\mu s$				
$I_H$	$T_{VJ} = 25^\circ C$ , $V_D = 6V$ , $R_{GK} = \infty$		$\leq$	200	mA
$t_{gd}$	$T_{VJ} = 25^\circ C$ , $V_D = 1/2 V_{DRM}$		$\leq$	2	$\mu s$
	$I_G = 0.3A$ , $dI_G/dt = 0.3A/\mu s$				
$t_q$	$T_{VJ} = T_{VJM}$ , $I_T = 20A$ , $t_P = 200\mu s$ , $V_R = 100V$			150	$\mu s$
	$-di/dt = 10A/\mu s$ , $dv/dt = 15V/\mu s$ , $V_D = 2/3 V_{DRM}$				
$R_{thJC}$	per thyristor; sine 180°el			0.46	K/W
	per module			0.092	K/W
$R_{thJK}$	per thyristor; sine 180° el			0.55	K/W
	per module			0.11	K/W
$d_s$	Creeping distance on surface			10	mm
$d_A$	Creeping distance in air			9.4	mm
$a$	Max. allowable acceleration			50	$m/s^2$

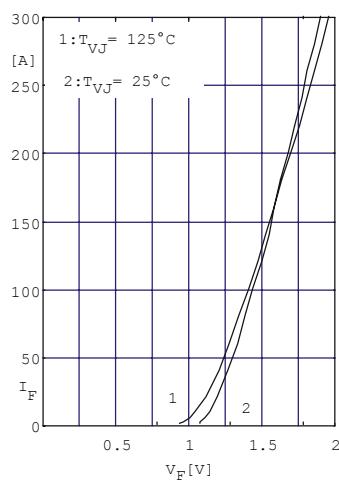


Fig. 1 Forward current vs. voltage drop per diode or thyristor

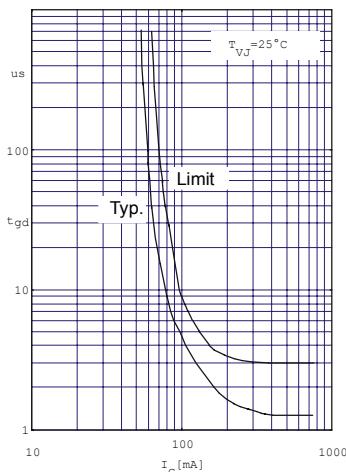


Fig. 2 Gate trigger delay time

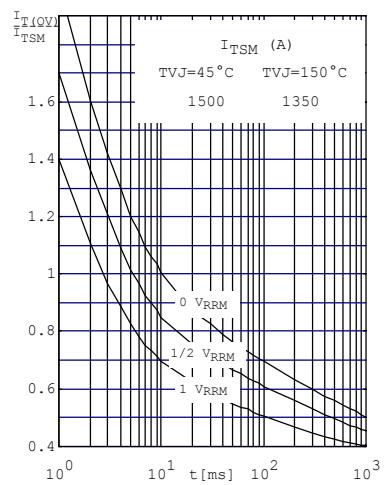


Fig. 3 Surge overload current per diode (or thyristor)  $I_{FSM}$ ,  $I_{TSM}$ : Crest value  $t$ : duration

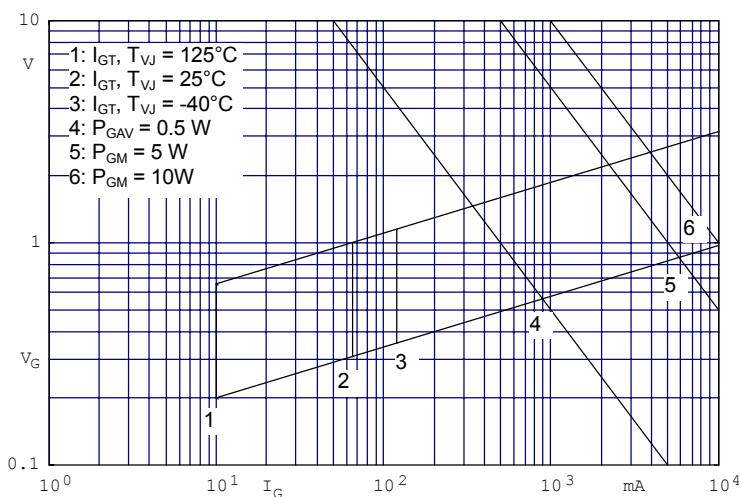


Fig.4 Gate trigger characteristic

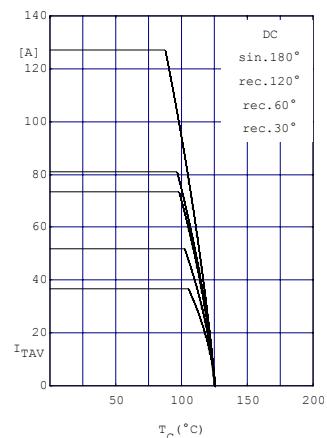


Fig.5 Maximum forward current at case temperature

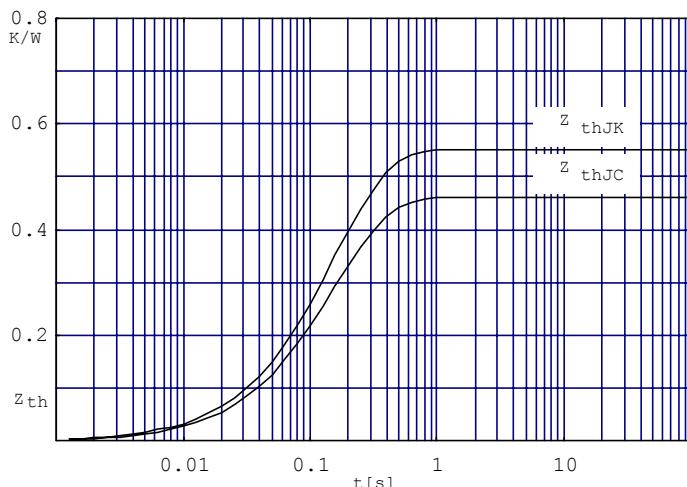


Fig.6 Transient thermal impedance per thyristor or diode (calculated)

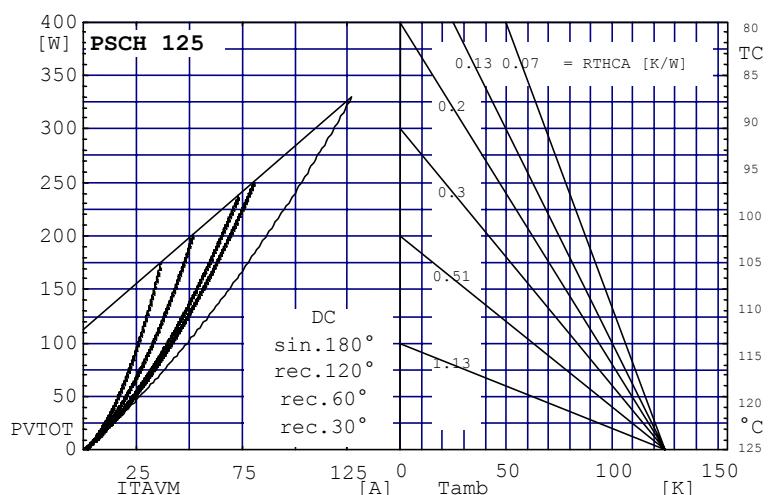


Fig. 7 Power dissipation vs. direct output current and ambient temperature