Regarding the change of names mentioned in the document, such as Mitsubishi **Electric and Mitsubishi XX, to Renesas Technology Corp.**

The semiconductor operations of Hitachi and Mitsubishi Electric were transferred to Renesas Technology Corporation on April 1st 2003. These operations include microcomputer, logic, analog and discrete devices, and memory chips other than DRAMs (flash memory, SRAMs etc.) Accordingly, although Mitsubishi Electric, Mitsubishi Electric Corporation, Mitsubishi Semiconductors, and other Mitsubishi brand names are mentioned in the document, these names have in fact all been changed to Renesas Technology Corp. Thank you for your understanding. Except for our corporate trademark, logo and corporate statement, no changes whatsoever have been made to the contents of the document, and these changes do not constitute any alteration to the contents of the document itself.

...ess opt Note: Mitsubishi Electric will continue the business operations of high frequency & optical devices and power devices.

Renesas Technology Corp. Customer Support Dept. April 1, 2003



256 × 8-BIT MAIL-BOX

DESCRIPTION

The M66220 is a mail box that incorporates a complete CMOS shared memory cell of 256×8 -bit configuration using high-performance silicon gate CMOS process technology, and is equipped with two access ports of A and B.

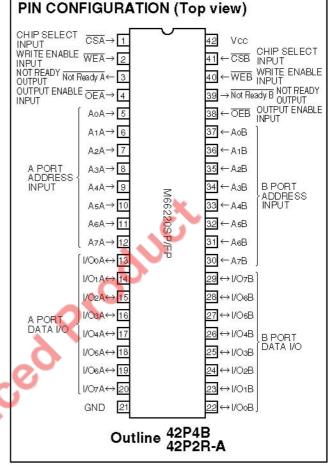
Access ports A and B are equipped with independent addresses \overline{CS} , \overline{WE} and \overline{OE} control pins and I/O pins to allow independent and asynchronous read/write operations from/to shared memory individually. This product also incorporates a port adjustment arbitration function in address contention from both ports.

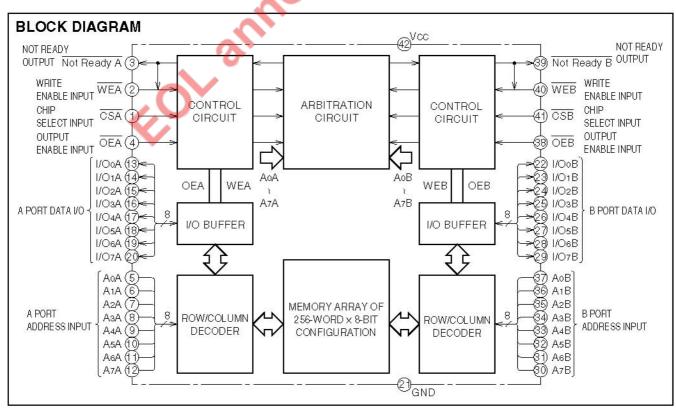
FEATURES

- Memory configuration of 256 × 8 bits
- · High-speed access, address access time 40ns (typ.)
- · Complete asynchronous accessibility from ports A and B
- · Completely static operation
- · Built-in port arbitration function
- · Low power dissipation CMOS design
- 5V single power supply
- Not Ready output pin is provided (open drain output)
- · TTL direct-coupled I/O
- · 3-state output for I/O pins

APPLICATION

Inter-MPU data transfer memory, buffer memory for image processing system.





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256 × 8-BIT MAIL-BOX

FUNCTION

The M66220 is a mail box most suitable for inter-MPU data transfer which is used in a multiport mode. Provision of two pairs of addresses and data buses in its shared memory cell of 256×8 bit configuration allows independent and asynchronous read/write operations from/to two access ports of A and B individually.

This allows access to shared memory as simple RAM when viewing from one MPU. The concurrent accessibility to shared memory from two MPUs provides remarkable improvement of a multiport mode processor system in throughput.

The arbitration function incorporated in the chip decides the first-in port to assign a higher priority to the access from one MPU, even if two MPUs contend for selection of the same address in shared memory from ports A and B. A Not Ready signal "L" is output to the last-in port and invalidates any access from the other MPU.

As a write operation to memory, one of addresses Ao to A7 is specified.

The $\overline{\text{CS}}$ signal is set to "L" to place one of I/O pins in the input mode. Also, the $\overline{\text{WE}}$ signal is set to "L". Data at the I/O pin is thus written into memory.

As a read operation, the \overline{WE} signal is set to "H". Both \overline{CS} signal and \overline{OE} signal are set to "L" to place one of I/O pins in the output mode. One of addresses Ao to A7 is specified. Data at the specified address is output to the I/O pin.

When the \overline{CS} signal is set to "H", the chip enters a non-select state which inhibits a read and write operation. At this time, the output is placed in the floating state (high impedance state), thus allowing OR tie with another chip. When the \overline{OE} signal is set to "H", the output enters the floating state. In the I/O bus mode, setting the \overline{OE} signal to "H" at a write time avoids contention of I/O bus data. When the \overline{CS} signal is set to Vcc, the output enters the full stand-by state to minimize supply current (See Tables 1 and 2).

Table 1 Mode Settings of Ports (AoA ~ A7A ≠ AoB ~ A7B)

1	A port inpu	it	Е	port inpu	ıt	FI	ag	40
CSA	WEA	ŌĒĀ	CSB	WEB	OEB	Not Ready A	Not Ready B	Operation
Н	×	×	×	×	×	Н	H	A port is set to the non-select mode.
×	×	×	Н	×	×	Н	Н (B port is set to the non-select mode.
L	L	×	×	×	×	Н	H	A port is set to the write mode for memory.
L	Н	L	×	×	×	Н	Н	A port is set to the read mode for memory.
×	×	×	L	L	×	H	H	B port is set to the write mode for memory.
×	×	×	L	Н	L	Н	Н	B port is set to the read mode for memory.

Table 2 Basic Functions of Ports

cs	WE	ŌĒ	Mode	VO pin	lcc
Н	×	×	Non-select	High impedance	Stand-by
L	L	×	Write	DIN	Operation
L	Н	L	Read	Dout	Operation
L	Н	Н		High impedance	Operation

Note 1: xindicates "L" or "H". (Irrelevant)
"H" = High level, "L" = Low level



256 × 8-BIT MAIL-BOX

FUNCTIONAL DESCRIPTION Arbitration Function

The M66220 has asynchronous accessibility from two independent ports to shared memory, thus remarkably improving the throughput of the entire processor system used in the multiport mode. On the other hand, this accessibility causes a problem of contending for selecting the same address in shared memory during the addressing from both ports.

If the same address is contentionally selected, the following four basic operations are possible depending on an access mode set from both ports:

(1) A port Read	B port Read
(2) A port Read	B port Write
(3) A port Write	B port Read
(4) A port Write	B port Write

In this case, when both ports are operating in the read mode as given in (1), correct data is read to both ports and the contents of memory are not destroyed. There is no special problem. If the other port is in the read mode while one port is operating in the write mode as given in (2) or (3), however, data is written correctly but the data read from the other port in the read mode may change during the same cycle. between the other port in the read mode may change during the same cycle.

This comes into question. When both ports are operating in the write mode as given in(4), reverse data is written into each port and the contents of memory may become uncertain. Consequently, no result will be guaranteed.

The M66220 incorporated an arbitration function circuit to solve such problems when contentionally selecting an address from both ports. The arbitration function decides which of A and B ports determines an address first, and unconditionally assigns access priority to the first-in port (At this time, the Not Ready signal holds "H"). As for the last-in port operation, the function inhibits any write to that port from MPU at the same time when "L" is output to the Not Ready output pin at the port regardless of a read or write operation during the period of address matching of both ports. If the address of the first-in port changes after that and both ports do not have the same address, the Not Ready output is reset to "H" and the access in the stopped state is accepted from the last-in port. If the same address is selected by an address input from both ports simultaneously, a decision by the arbitration function on the chip also affords access only from one port, and outputs "L" to the Not Ready output for the other port invalidate any access from MPU. Tables 3 and 4 give the relationship between the port arbitration function and port access.



256 × 8-BIT MAIL-BOX

Arbitration Function and Port Access

Contention No.1 (Address control)

Table 3 gives the port access states and the $\overline{\text{Not Ready}}$ signal output states if the same address is selected in shared memory by an address

input set from A and B ports with $\overline{CSA} = \overline{CSB} = "L"$.

Table 3 Contention Processing by Address Input

 $\overline{CSA} = \overline{CSB} = "L"$

Address setting when selecting		A port		B port			
same address	Mode setting	Access	Not Ready A	Mode setting	Access	Not Ready B	
First-in A port	Read	y.	Н	Read		L	
First-in B port	Read	a a	L	Read	r	Н	
First-in A port	Read	i z	Н	Write	×	L	
First-in B port	Read	7	L	Write	P	Н	
First-in A port	Write	j.	Н	Read	- E	Ĺ	
First-in B port	Write	×	L	Read		Н	
First-in A port	Write	Ģ.	Н	Write	×	Ĺ	
First-in B port	Write	×	L	Write		Н	
Simultaneous A and B ports	Ar	bitration Resolv	ved	A	rbitration Resol	ved	

Contention No.2 (CS control)

Table 4 gives the port access states and the $\overline{\text{Not Ready}}$ signal output states when setting the $\overline{\text{CS}}$ inputs from A and B ports valid, and

selecting the same address in shared memory with AoA to A7A=AoB to A7B.

Table 4 Contention Processing by CS Input

A0A ~ A7A = A0B ~ A7B

CS input set when selecting		A port				
same address	Mode setting	Access	Not Ready A	Mode setting	Access	Not Ready B
First-in A port	Read	2	Н	Read	r	L
First-in B port	Read		L	Read	r	Н
First-in A port	Read		Н	Write	×	L
First-in B port	Read		L	Write	ř	Н
First-in A port	Write		Н	Read	r	L
First-in B port	Write	×	L	Read		Н
First-in A port	Write	æ	Н	Write	×	L
First-in B port	Write	×	L	Write	r	Н
Simultaneous A and B ports	Ar	bitration Resolv	ed	Ar	bitration Resolv	/ed

Note 2: "H" = High level, "L" = Low level



256 × 8-BIT MAIL-BOX

ABSOLUTE MAXIMUM RATINGS (Ta = 0 ~ 70°C, unless otherwise noted)

Symbol	Parameter	Conditions	Ratings	Unit
Vcc	Supply voltage Input voltage When defining GND pin as a reference.		-0.3 ~ +7.0	V
VI			-0.3 ~ Vcc + 0.3	V
Vo	Output voltage	Teleferice.	0 ~ Vcc	V
Pd	Maximum power dissipation	Ta = 25°C	700	mW
Tstg	Storage temperature range		−65 ~ 150	°C

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter		Limits				
Symbol	r arameter	Min.	Тур.	Max.	Unit		
Vcc	Supply voltage	4.5	5.0	5.5	V		
GND	Ground		0		V		
VI	Input voltage	0		Voc	V		
Topr	Operating temperature range	0		70	°C		

ELECTRICAL CHARACTERISTICS (Ta = 0 ~ 70°C, Vcc=5V±10%, unless otherwise noted)

Symbol	Parameter		Toot conditions		Unit		
Symbol		Parameter	Test conditions	Min.	Тур.	Max.	Unit
VIH	"H	" input voltage		2.2		Vcc+0.3	V
VIL	"L'	" input voltage	01	-0.3		0.8	V
Voh	"H	" output voltage (I/O)	IOH = -2mA	2.4			V
Vol	"L'	output voltage (I/O)	IOL = 4mA			0.5	V
Vol	Op	oen drain "L" output voltage (Not Ready)	IOL = 8mA			0.5	V
liH	"H	" input current	VI = VCC			10.0	μА
liL	"L'	input current (VI = GND			-10.0	μА
lozн	Of	ff state "H" output current	CS = VIH or OE = VIH Vo = VCC			10.0	μА
lozL	Of	ff state "L" output current	OS = VIH or OE = VIH Vo = GND			-10.0	μА
lcc	St	atic current dissipation (active)	CS < 0.2V, Another input VIN > VCC - 0.2V or VIN < 0.2V, Output pin open			60	mA
ISB1		Two-port stand-by	CSA, CSB = VIH	*		5	mA
ISB2	ent	One-port stand-by	CSA or CSB = VIH IOUT = 0mA (Active port output pin open)			60	mA
ISB3	Stand-by current	Two-port full stand-by	CSA, CSB > Vcc - 0.2V Another input Vin > Vcc - 0.2V or Vin < 0.2V			0.1	mA
ISB4	Stal	One-port full stand-by	CSA or CSB > VCC - 0.2V Another input VIN > VCC - 0.2V or VIN < 0.2V, IOUT = 0mA (Active port output pin open)			30	mA
CI	In	put capacitance				10	pF
Co	Oi	utput capacitance in off state				15	pF

Notes 3: The direction in which current flows into the IC is defined as positive (no sign).



^{4:} The above typical values are standard values for Vcc = 5V and Ta = 25°C.

256 × 8-BIT MAIL-BOX

SWITCHING CHARACTERISTICS (Ta = $0 \sim 70^{\circ}$ C, Vcc = $5V\pm10\%$, unless otherwise noted) **Read cycle**

Symbol	Doromotor		Limits				
Symbol	Parameter	Min.	Тур.	Max.	Unit		
ton	Read cycle time	70			ns		
ta(A)	Address access time			70	ns		
ta(CS)	Chip select access time			70	ns		
ta(OE)	Output enable access time			35	ns		
tdis(CS)	Output disable time after CS (Note 5)			35	ns		
tdis(OE)	Output disable time after OE (Note 5)			35	ns		
ten(CS)	Output enable time after CS (Note 5)	5			ns		
ten(OE)	Output enable time after OE (Note 5)	5			ns		
tv(A)	Data effective time after Address	10			ns		

TIMING REQUIREMENTS (Ta = 0 \sim 70°C, Vcc = 5V \pm 10%, unless otherwise noted) Write cycle

Symbol	Desembles		Limits			
	Parameter	Min.	Тур.	Max.	Unit	
tow	Write cycle time	70			ns	
tw(WE)	Write pulse width	45			ns	
tsu(A)	Address setup time	0			ns	
tsu(A-WEH)	Address setup time for rise of WE.	65			ns	
tsu(CS)	Chip select setup time (for WE)	65			ns	
tsu(D)	Data setup time	40			ns	
th(D)	Data hold time	0			ns	
trec(WE)	Write recovery time	0	ĺ		ns	
tdis(WE)	Output disable time after WE (Note 5)			35	ns	
tdis(OE)	Output disable time after OE (Note 5)			35	ns	
ten(WE)	Output enable time after WE (Note 5)	0			ns	

Note 5: The time required for the output to change from a steady state to ±500mV under the load conditions shown in Fig 2. This parameter is guaranteed but is not tested at shipment.

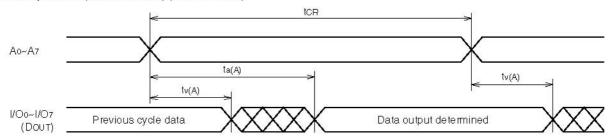
NOT READY TIMING (Ta = 0 ~ 70°C, Vcc = 5V±10%, unless otherwise noted)

Sumbol	Parameter		11		
Symbol	Parameter	Min.	Тур.	Max.	Unit
tnaa	Not Ready access time from Address			50	ns
tnda	Not Ready disable time from Address		,	50	ns
tNAC	Not Ready access time from CS			50	ns
tNDC	Not Ready disable time from CS			50	ns
taps	Arbitration priority setup time	15			ns
tno	Data output access time from Not Ready.			0	ns
tnw	Write hold time from Not Ready.	65			ns

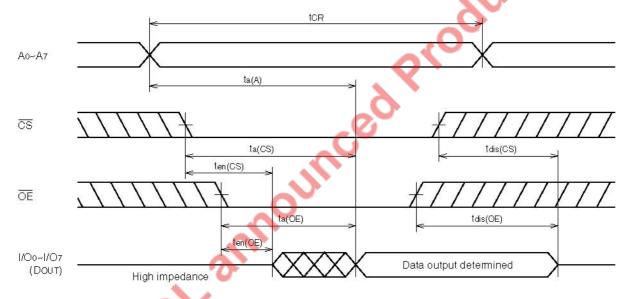


TIMING DIAGRAM Read Cycle (WE = VIH)

Read cycle No.1 (Address control) $\overline{(CS = \overline{OE} = VIL)}$

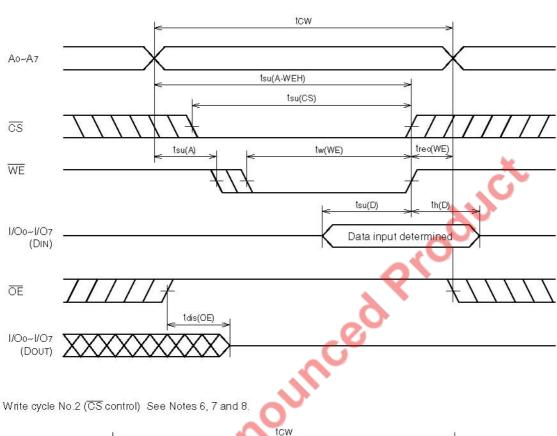


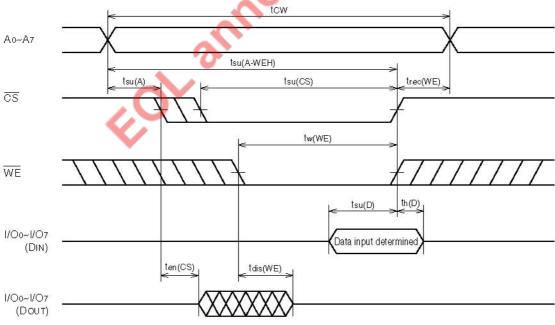
Read cycle No.2 (CS control)



Write Cycle

Write cycle No.1 (WE control) See Notes 6, 7 and 8.



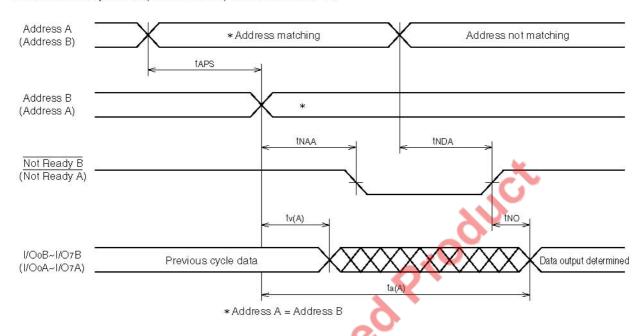


- Notes 6: The $\overline{\text{WE}}$ of the port must be set to "H" when an address input changes. 7: A write operation is performed during the overlap period when both $\overline{\text{CS}}$ and $\overline{\text{WE}}$ are "L".
 - 8: Do not apply any negative-phase signal from outside when an I/O pin is in output state.
 - 9: The shaded part means a state in which a signal can be "H" or "L"

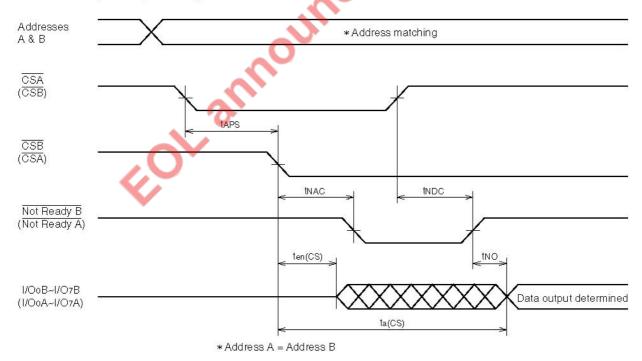


Contention Read Cycle (WE = VIH, OE = VIL)

Contention read cycle No.1 (Address control) See Notes 10 and 11.



Contention read cycle No.2 (CS control) See Notes 10 and 12



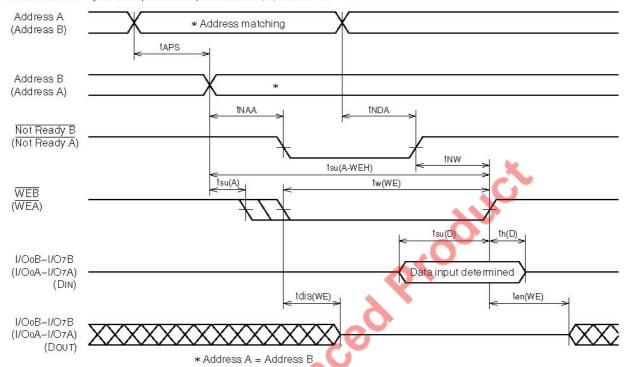
Notes 10: The Not Ready output of the first-in port holds "H"

- 11: When $\overline{\text{CS}}$ is set to "L" before the address input is determined.
- 12: When the address input is determined before $\overline{\text{CS}}$ transition to "L".

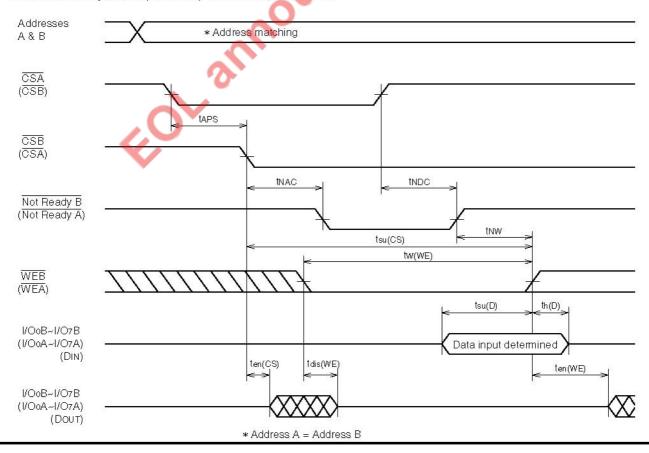


Contention Write Cycle

Contention write cycle No.1 (WE control) See Notes 6, 8, 10 and 11.



Contention write cycle No.2 (CS control) See Notes 6, 8, 10 and 12.





SWITCHING CHARACTERISTICS MEASUREMENT CIRCUIT

: VIH = 3.0 V, VIL = 0V Input pulse level

Input pulse rise/fall time tr/tf = 5nsInput timing reference voltage : 1.5V Output timing decision voltage : 1.5V

Output load : Figure 1 ~ 3 (The capacitance includes stray wiring capacitance and the probe input capacitance.)

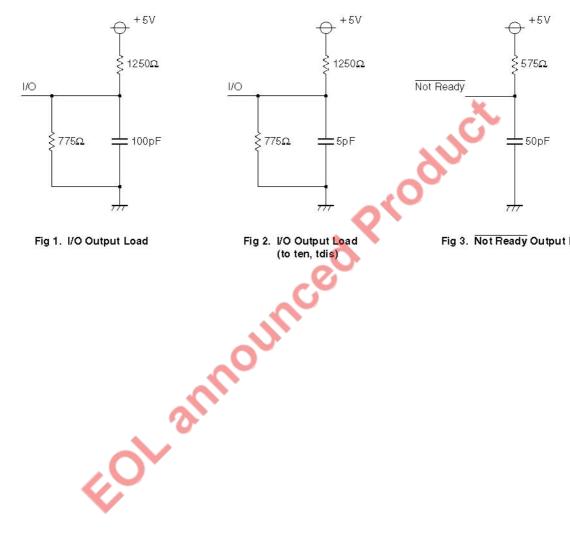


Fig 1. I/O Output Load

Fig 2. I/O Output Load

Fig 3. Not Ready Output Load

