

MAS6116 Stereo Digital Volume Control

- Signal Voltage up to ± 18V
- Two Independent Channels
- Use of Differential DACs Possible

MAS6116 also features a peak detection circuitry that allows easy monitoring of the output signal.

MAS6116 has also a set of "instant gain change"

instructions that allow fast gain switching. The use

of external operational amplifier provides flexibility

for the operating voltage, signal swing, noise floor

• Serial Control Registers

DESCRIPTION

MAS6116 is a stereo volume control for audio systems, which require high output voltages (AC3). It has serial interface, which controls two audio channels. Simple serial interface allows microcontroller to control many MAS6116 chips on the same PCB board. "Clicking" between gain changes is eliminated by changing gain only when zero crossing has been detected in the input signal.

FEATURES

- Signal Voltage up to ± 18V
- Two Independent Channels
- Use of Differential DACs Possible
- Serial Control Registers
- Zero Cross Detection for Gain Changes
- Gain Range +15.5db...-111.5dB
- 0.5 dB Gain Step Size
- Mute Pin
- Power On/Off Transient Suppression
- Signal Peak Level Comparator with Adjustable
 Reference
- Independent Writing to Both Channels
- Instant Gain Change Function for Fast Gain Switching
- XMUTE Using the Zero Cross and Timeout Functions
- Write Operation Status Register

APPLICATION

and cost optimization.

- High End Audio Systems
- Multi-channel Audio Systems



BLOCK DIAGRAM





PIN CONFIGURATIONS

		SO16	
AVCC		16	
LMO		15	RMO
LFO	3	14 🛛	RFO
LIN	Ц4	13∐	RIN
LGND	□ 5	12 🛛	RGND
XCS	6	11 🛛	DGND
DVCC	7	10 🛛	CCLK
XMUTE	8	9 🛛	DATA

PIN DESCRIPTION

Din Name	Din	Din	Type	Function
Fill Name	SO16	QFN 4x5	туре	
AVCC	1	23	Р	Power Supply, for Analog
LMO	2	24	AI	External Amplifier Negative Input (Left)
LFO*	3	1	AI	Feedback Signal from External Amplifier Output (Left)
LIN*	4	3	AI	Input, Left Channel
LGND	5	4	AI	Signal Ground, Left Channel
XCS	6	7	DI	Chip Select Input of Serial Interface
DVCC	7	8	Р	Power Supply, for Digital
XMUTE	8	9	DI	Mute Input
DATA	9	11	DIO	Data Input and Output of Serial Interface, Tristate
CCLK	10	12	DI	Clock Input of Serial Interface
DGND	11	13	G	Ground for Digital
RGND	12	16	AI	Signal Ground, Right Channel
RIN*	13	17	AI	Input, Right Channel
RFO*	14	19	AI	Feedback Signal from External Amplifier Output (Right)
RMO	15	20	AI	External Amplifier Negative Input (Right)
AGND	16	21	G	Ground for Analog

*) Note: These pins have limited ESD protection. See Absolute Maximum Ratings on page 9 for further details.



GENERAL DESCRIPTION

Main features

MAS6116 is a stereo digital volume control designed for audio systems. The levels of the left and right analog channels are set by the serial interface. Both channels can be programmed independently. The channel gains can be programmed from -111.5 dB to +15.5 dB with 0.5 dB resolution. The code for -112 dB (00_{HEX}) activates mute for maximum attenuation. MAS6116 operates from single +5V supply and accepts analog input signal levels up to ±18V.

MAS6116 has a zero cross detect function that changes the channel gain only when a zero crossing has been detected in the input signal. This eliminates clicking sounds from the output signal when the gain is changed. The zero cross detection circuit is also equipped with a timeout function to make sure the gain value is updated even when there is no input signal.

Channel gains can also be changed instantly without using the zero cross detect function. This can be done with dedicated instant gain change commands specified in *Register Description* on page 7. Using this feature to change channel gains in large increments is not recommended because it may cause large transients in the output signal. See chapter *Changing the gain of the channels* and chapter *Write operation status register* for further details.

The XMUTE pin in MAS6116 always uses the zero cross detection and timeout functions when entering to or returning from the MUTE state. This prevents fast transients from occurring in the output signal.

Serial interface

Control information is written into or read back from the internal register via the serial control port. Serial control port consists of a bi-directional pin for data (DATA), chip select pin (XCS) and control clock (CCLK) and supports the serial communication protocol. All control instructions require two bytes of data.

To shift the data in CCLK must be pulsed 16 times when XCS is low. The data is shifted into the serial input register on the rising edges of CCLK pulses. The first 8 bits contain address information. The second byte contains the control word. XCS must return to high after the second byte. That is, after the 16th CCLK XCS must be returned to high. See chapter *Serial interface timing* diagram on page 12.

The same process takes place for reading the information. XCS will remain low for next 16 CCLK pulses. The data is shifted out on the falling edges of CCLK. When XCS is high, the DATA pin is in high impedance state, which enables DATA pins of other devices to be connected together.

On the PCB board the same DATA and CCLK lines can be routed to every MAS6116 chip. If the XCS-pin is not active (low), DATA pin of that chip is in high-impedance state. This allows using a simple PCB board for multi-channel audio systems.



GENERAL DESCRIPTION

Operating modes

When power is first applied, power-on reset initializes control registers and sets MAS6116 into mute state, ignoring the state of the XMUTE pin. The activation of the device requires that XMUTE pin is high and a control byte with a greater than the default value (00_{HEX}) is written in the gain register. It is possible to return to the mute state either by setting XMUTE pin low or writing zero (00_{HEX}) to the gain register. Setting the XMUTE pin low will mute both channels. Setting the XMUTE pin back high will return the channels to previously written gain values. The zero cross detector function is used when entering and returning from the mute state to prevent large transients in the output signal (see chapter *Changing the gain of the channels*).

The device has a special test mode register, which is used only for internal testing of the device. It is strongly recommended not to change the default value (00_{HEX}) of the test register during normal operation. For device testing the XMUTE pin is bi-directional. When the test register bit 1 is set to high, XMUTE pin is in output mode. In the test mode internal signals can be directed to the XMUTE pin. Note: In the test mode both analog outputs are in mute state and the device will not allow new gain values to be written in the gain registers. An exception to this is the force latch command specified in table *Test Register CR5 Description*, which can be used to instantly change the gain of both channels. This function is intended to be used in the test mode only, and it is recommended to use the commands specified in *Register Description* to instantly change the channel gains.

Changing the gain of the channels

When a new gain value is written to the gain register the device will activate the zero crossing detection and delay generator for the selected channel. MAS6116 will wait until a rising edge of the input signal is detected to change the gain value. This is done to ensure that no audible clicks are produced to the output signal during the gain change operation. The zero cross detection circuit has also a timeout delay generator that will force the gain change. The delay generator generates a typical delay of 22 ms.

If a new gain value is written before the previous write operation has finished, the previously written value will be overwritten and will not be set to the output. If it is desired that each gain value is set to the output, it is recommended to read the status bit from the write operation status register (CR6) or wait for at least 30 ms before the next gain change instruction.

Both channels can be programmed independently with separate commands. In this case the gain values will be set to the output in the order of writing. Both channels can also be programmed to the same value by writing only one instruction (see the *Register Description* on page 7).

Note: Due to the input signal dependency of the zero cross detection circuits the order of the gain changes may differ from the order of writing to the registers if the input signals to the channels are different. This applies to all instructions that use the zero cross detection and timeout functions, i.e. instructions that are not labeled as "instant" in the register description.

The new gain value can be set instantly to the output by using the instant gain change function. By using this command function the gain is set to the output instantly after the write operation has finished, without waiting a zero cross to occur in the input signal or a delay to pass. The gains can be set independently to both channels using different commands, or both channels can be set to the same gain value by using a single command. Using the instant gain change function to change the gain value in larger than 0.5 dB steps may produce audible clicks to the output signal.



GENERAL DESCRIPTION

Peak level detection

MAS6116 has a 8-bit digital-to-analog converter (DAC) used to monitor the peak level of the output signal. The reference value is programmed using the serial interface and the same reference value is used for both channels. The reference value V REF can be calculated using the following formula.

VREF = (0.0036 + 0.0145 · CODE) · AVCC

where CODE is the decimal value of the control byte (0...255) and AVCC is the analog supply voltage of the MAS6116 device. With nominal analog supply voltage of 5V the reference value is

 $VREF = 18mV + 72.5mV \cdot CODE$

When a positive peak signal level at the output exceeds the V REF value, bits 0 and 1 of the status register are set (see register description). When set, the register contents will remain high until the value of the status register has been read.

Write operation status register

MAS6116 features a status register that can be used to determine if the channel registers are ready to accept new gain values. The status register bits 0 and 1 are set high at the start of a gain write operation, and are set back low when the new gain value has been set to the output. This happens when a positive zero crossing is detected in the input signal or the timeout delay has passed.

It is allowed to write a new gain value to a channel that is busy (i.e. waiting for a zero cross in the input signal). The new value will overwrite the previous one and the timeout delay will be reset. This means that the previously written gain value will not be set to the channel gain registers. To prevent this from happening it is recommended to read the write operation status register prior to setting a new gain value to determine if the write operation can be safely executed.



REGISTER DESCRIPTION

Register				Addr	ess E	Byte				Data Byte	
	7	6	5	4	3	2	1	0	msblsb	Function	
Write Operation Status CR6	Х	1	0	1	0	R	X	Х	Output code 00000000 00000001 00000010 00000011	Both channels ready Right channel busy Left channel busy Both channels busy	
Peak Detector Status CR4	X	1	0	1	1	R	X	Х	Output code 00000000 00000001 00000010 00000011	No overload Right overload Left overload Both overload	
Peak Detector Reference CR3	X	1	1	0	0	R/W	X	X	Input code 11111111 1111110 11111101 • • 00000010 0000001 0000000	DAC output, Note 1. VREF(255) VREF(254) VREF(253) • • VREF(2) VREF(2) VREF(1) VREF(0)	
Left Channel Gain CR2	X	1	1	0	1	R/W	X	x	Input code 11111111 1111110 11111101 • • 11100000 00000010 00000001 00000000	Gain dB +15.5 +15.0 +14.5 • 0.0 -111.0 -111.5 Mute	
Right Channel Gain CR1	X	1	1	1	0	R/W	X	X	Input code 11111111 1111110 1111110 11111101 • • • 11100000 00000010 00000001 00000000	Gain dB +15.5 +15.0 +14.5 • • 0.0 -111.0 -111.5 Mute	
Test Mode, CR5	Х	1	1	1	1	R/W	Х	Х		Reserved	
Normal Write, Both	X	1	0	0	1	W	X	X	Write	to both gain registers	
Instant Write, Left (CR2) Instant Write, Right (CR1)	X X	0	1	0	1	W	X X	X X	Instant gain set to left channel Instant gain set to right channel		
Instant Write, Both	Х	0	1	1	1	W	X	X	Instant g	ain set to both channels	

Note 1. Reference voltage is calculated from VREF = (0.0036 + 0.0145 • CODE) • AVCC

Address byte bits:

- Bit 2 is read/write bit (1=read, 0=write).
- Bits marked as X are don't care bits. ٠
- The instant write commands write values to CR1 and CR2 registers for right and left channels respectively. • These values can be read by using the specified read commands for CR1 and CR2 registers.



Data byte bits:

- All registers are set to their default values 00_{HEX} except CR3 which is set to FF_{HEX} during power-on reset.
- Default value for all bits is zero (00_{HEX}).

TEST REGISTER CR5 DESCRIPTION

Note: Test register is intended for internal testing of the device only and not supposed to be used in normal operation. It is strongly recommended not to change initial test register value from the default (00_{HEX}) .

The XMUTE pin is in output mode when bit 1 in the test register CR5 is set. Bits 2, 3 and 4 select the internal signal to be routed to the XMUTE pin in the test mode.

Condition		Data Byte bits				Function			
	7	6	5	4	3	2	1	0	
XMUTE=in	0	0	0	0	0	0	0	0	Normal operation
Test, XMUTE=in	0	0	0	0	0	0	0	1	Force latch, note 2
Test, XMUTE=out	0	0	0	0	0	0	1	0	Left delay generator
Test, XMUTE=out	0	0	0	0	0	1	1	0	Left peak detector
Test, XMUTE=out	0	0	0	0	1	0	1	0	Left zero crossing
Test, XMUTE=out	0	0	0	0	1	1	1	0	Left gain set enable
Test, XMUTE=out	0	0	0	1	0	0	1	0	Right delay generator
Test, XMUTE=out	0	0	0	1	0	1	1	0	Right peak detector
Test, XMUTE=out	0	0	0	1	1	0	1	0	Right zero crossing
Test, XMUTE=out	0	0	0	1	1	1	1	0	Right gain set enable

Note 2. Forces the new gain value to be set without waiting for a zero crossing to occur in the input signal or the timeout delay to pass. When force latch is used, both channels are latched with the same gain value.

POWER-ON RESET

MAS6116 has a Power-On Reset circuit (POR) that ensures that the circuit is set to a known state when power is applied. The device can be activated as described in chapter *Operating modes* after the POR delay has passed.

In addition MAS6116 has a supply voltage monitoring circuit, that monitors the digital supply voltage (DVCC) level. If the digital supply voltage drops below the specified level, the circuit is set to RESET state. The voltage monitoring circuit is functional only when sufficient analog supply voltage (AVCC) is present.

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
POR delay	T _{POR}	From DVCC=5V to POR rising edge		450		μs
Monitored DVCC level	V_{mon}	Measured from DGND		2.8		V
AVCC level to enable DVCC monitoring	V _{AVCC}	Measured from AGND	2.5			V



ABSOLUTE MAXIMUM RATINGS

All voltages with respect to ground.

Parameter	Symbol	Conditions	Min	Max	Unit
Signal Voltage	RIN, RFO, LIN, LFO		-20	+20	V
Positive Supply Voltage	AVCC, DVCC		-0.5	+6.0	V
All other pins	DATA, CLK, XCS, XMUTE	Note 3.	-0.3	AVCC +0.3	V
Storage Temperature	TS		-55	+125	°C
Operating Temperature	TA		-40	+95	°C
ESD (HBM) pins 3, 4, 13 and 14			200		V
ESD (HBM) all other pins			2000		V

Note 3. Pin voltage must not exceed +6V under any circumstances.

Stresses beyond those listed may cause permanent damage to the device. The device may not operate under these conditions, but it will not be destroyed.

RECOMMENDED OPERATION CONDITIONS

		(AVCC=+5.0 V, AGND=0 V, TA=+25°C unless otherwise noted					
Parameter	Symbol	Conditions	Min	Тур	Max	Unit	
Signal Voltage	RIN, RFO, LIN, LFO		-18		+18	V	
Positive Supply Voltage	AVCC,DVCC		4.5	5	5.5	V	
Negative Supply Voltage	AGND,DGND			0		V	
Signal Grounds	LGND,RGND			0		V	
Operating Temperature	ТА		-30	+25	+85	°C	

ANALOG CHARACTERISTICS

Analog Inputs/Outputs

(AVCC=+5.0 V, AGND=0 V, TA=+25°C unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Мах	Unit
Input impedance	RIN	Average impedance, note 4	7	10	13	kΩ
Input capacitance	CIN	For any gain value		2		pF
Input offset voltage	VIH	External OpAmp, Gain = 15.5 dB Note 5		0.23		mV
Supply current	IVCC	From AVCC		0.6	2.2	mA
Supply current	IGND	From AGND				mA
Power supply rejection ratio ¹	PSRR	From AVCC		80		dB

Note 4. Average input impedance is calculated as an average of the impedance measured for all gain values.

Note 5. Output offset voltage depends on external opamp and selected gain. Low input offset voltage and input bias current opamp is recommended to be used for minimum output offset.



ANALOG CHARACTERISTICS

♦ Gain Control

(AVCC=+5.0 V, AGND=0 V, TA=+25°C unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Gain range	G		-111.5		+15.5	dB
Step size	D			0.5		dB
Absolute gain	GABS	Absolute gain value with setting G=255	+15	+15.5	+16	dB
Gain step error	DE	Relative to GABS, note 6	-0.5	0	0.5	dB
Gain match error ¹	ME	Between channels, note 7	-0.2	0	0.2	dB
Mute attenuation	MATT	AC measurement	96			dB

Note 6. Gain value for each gain setting is measured as AC measurement relative to GABS assuming a gain step size of 0.5dB. Gain settings 65...255 are tested in production. Gain error for lower gain settings is guaranteed by design only.

Note 7. Gain mismatch is tested in production for gain settings 90...255. Mismatch for lower gain settings is guaranteed by design only.

◆ Audio Performance

(AVCC=+5.0 V, AGND=0 V, TA=+25°C unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Noise	Ν	Vin = 0V, Vout with OP2277,				
		A-weighting				
		gain=0dB		11		
		gain=-40dB		3.7		μVrms
		gain=-60dB		2.2		
		gain=mute		1.8		
3rd harmonic	3 rd HD	Vin=5Vrms, gain=0dB,			-75	dB
component		fin=800Hz				
Total harmonic	THD	Vin=5Vrms, gain=0dB,		-72	-68	dB
distortion plus noise		fin=800Hz, 10 harmonics				
Signal to noise ratio	SNR	Vin=5Vrms, gain=0dB,	100			dB
-		fin=800Hz, non-weighted				
Crosstalk	CR	Between channels, Vin =		-110		dB
		5Vrms, gain= 0dB, fin = 1kHz				

Peak Level Detection

(AVCC=+5.0 V, AGND=0 V, TA=+25°C unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Peak detector minimum level	VMIN	PD reference = 0	0	18	500	mV
Peak detector maximum level	VMAX	PD reference = 255	18	18.5	20	V
Peak detector step size	VSTEP		60	72.5	90	mV

◆ Zero Cross Detection Timeout

(AVCC=+5.0 V, AGND=0 V, TA=+25°C unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Zero cross	TDEL		15	22	30	ms
detection timeout						



DIGITAL CHARACTERISTICS

◆ Digital Inputs/Outputs

(AVCC=+5.0 V, AGND=0 V, TA=+25°C unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Input low voltage	VIL	All digital inputs, DC			0.3* DVCC	V
Input high voltage	VIH	All digital inputs, DC	0.7* DVCC			V
Output low voltage	VOL	All digital outputs, IL=2mA			0.3* DVCC	V
Output high voltage	VOH	All digital outputs, IH=-2mA	0.7* DVCC			V

♦ Serial Interface Timing

(AVCC=+5.0 V, AGND=0 V, TA=+25°C unless otherwise noted)

Parameter	Symbol	Conditions	Min	Тур	Мах	Unit
Frequency of CCLK	FCCLK				10	MHz
Period of CCLK high	TWHC	Measured from VIH to VIH	50			ns
Period of CCLK low	TWLC	Measured from VIL to VIL	50			ns
Rise time of CCLK	TRC	Measured from VIL to VIH			100	ns
Fall time of CCLK	TFC	Measured from VIH to VIL			100	ns
Hold time, CCLK high to XCS low	THCHS		20			ns
Setup time, XCS low to CCLK high	TSSLCH		100			ns
Setup time, valid CI to CCLK high	TSDCH		100			ns
Hold time, CCLK high to invalid CI	THCHD		100			ns
Delay time, CCLK low to valid CI	TDCLD	Load=100pF			50	ns
Delay time, XCS high or 8 th CCLK low to invalid CI	TDSZ	Load=3.3k Ω	50		150	ns
Hold time, 16 th CCLK high to XCS high	THLCHS		200			ns
Setup time, XCS high to CCLK high	TSSHCH		200			ns



SERIAL INTERFACE TIMING





APPLICATION INFORMATION

Application Note 1 – Typical application



Application Note 2 - Configuration for balanced output DAC (only one channel shown)





APPLICATION INFORMATION

Application Note 3 – Single supply voltage usage

Single supply voltage circuit below is based on signal AC coupling and biasing output opamp in the middle point of supply voltages. Note that only right channel circuit is presented. The left channel circuit would be exactly the same. The component values have been chosen to limit overall lower corner frequency to about 10 Hz.



Application Note 4 – Lower supply voltage MCU communication example 1

If the serial control interface is driven from MCU which operates from lower supply voltage than MAS6116 which is using higher 5V voltage supply there is level shifting needed for keeping the digital signal levels proper in the communication. The bi-directional DATA line requires additionally level shifting in both directions. Figure below shows an example of serial interface level shifting between 3V and 5V voltage supplies. In this example level shifters with output enable function are used. The output enable function is used to disable level shifter output when data direction changes in the bi-directional data line of MAS6116.





APPLICATION INFORMATION

Application Note 5 – Lower supply voltage MCU communication example 2

Second example of communication with lower supply voltage MCU is shown in the figure below. There are open drain buffers used in the level shifting between 3V and 5V signal levels. In this example the DATA signal line communication is bi-directional also on the MCU side.





SO-16 PACKAGE OUTLINE



All dimensions are in accordance with JEDEC standard MS-013.

SOLDERING INFORMATION

◆ For Lead-Free / Green QFN 4mm x 5mm

Resistance to Soldering Heat	According to RSH test IEC 68-2-58/20
Maximum Temperature	260°C
Maximum Number of Reflow Cycles	3
Reflow profile	Thermal profile parameters stated in IPC/JEDEC J-STD-020
	should not be exceeded. http://www.jedec.org
Lead Finish	Solder plate 7.62 - 25.4 µm, material Matte Tin



REEL SPECIFICATIONS



Dimension	Min	Max	Unit
A		178	mm
В	1.5		mm
C	12.80	13.50	mm
D	20.2		mm
Ν	50		mm
W ₁ (measured at hub)	8.4	9.9	mm
W ₂ (measured at hub)		14.4	mm
Trailer	160		mm
Leader	390, of which minimum 160 mm of empty carrier tape sealed with cover tape		mm



ORDERING INFORMATION

Product Code	Product	Package	Quantity	Comments
MAS6116AA1SA306	MAS6116	16-pin Plastic SOIC, RoHS compliant	1000 pcs/reel in MBB	MBB=Moisture Barrier Bag
MAS6116AA1SA308	MAS6116	16-pin Plastic SOIC, RoHS compliant	46 pcs/tube	MSB0091A Bake recommendation for surface mounted devices

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