

4826175 INTEL CORP (MIPRCS/PRPHL)

99D 59652 D



PRELIMINARY
T-52-33-05

83C152A
UNIVERSAL COMMUNICATION CONTROLLER
8-BIT MICROCOMPUTER WITH FACTORY
MASK PROGRAMMABLE ROM
80C152A
UNIVERSAL COMMUNICATION CONTROLLER
8-BIT MICROCOMPUTER

- Superset of 80C51BH Architecture
- Multi-Protocol Serial Communication I/O Port (1.5 Mbps/2.4 Mbps Max)
 - SDLC
 - HDLC
 - CSMA/CD
 - User Definable Protocols
- Full Duplex/Half Duplex
- MCS®-51 Compatible UART
- 12 MHz Maximum Clock Frequency
- Multiple Power Conservation Modes
- 64KB Program Memory Addressing
- 64KB Data Memory Addressing
- 256 Bytes On-Chip RAM
- Dual On-Chip DMA Channels
- Hold/Hold Acknowledge
- Two General Purpose Timer/Counters
- 56 Special Function Registers
- 11 Interrupt Sources
- Available in 48 Pin Dual-in-Line Package and 68 Pin Surface Mount PLCC Package

(See Packaging Spec. Order #231369)

The 80C152, which is based on the MCS®-51 CPU, is a highly integrated single-chip 8-bit microcontroller designed for cost-sensitive, high-speed, serial communications. It is well suited for implementing Integrated Services Digital Networks (ISDN), emerging Local Area Networks, and user defined serial backplane applications. In addition to the multi-protocol communication capability, the 80C152 offers traditional microcontroller features for peripheral I/O interface and control.

Silicon implementations are much more cost effective than multiwire cables found in board level parallel-to-serial and serial-to-parallel converters. The 83C152 contains, in silicon, all the features needed for the serial-to-parallel conversion. Other 83C152 benefits include: 1) better noise immunity through differential signaling or fiber optic connections, 2) data integrity utilizing the standard, designed in CRC checks, and 3) better modularity of hardware and software designs. All of these—cost, network parameter and real estate improvements apply to 83C152 serial links between boards or systems and 83C152 serial links on a single board.

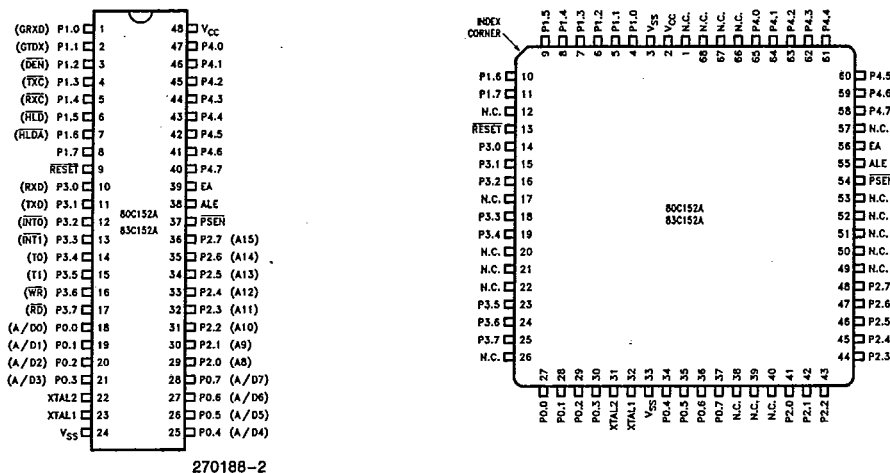


Figure 1. Connection Diagrams

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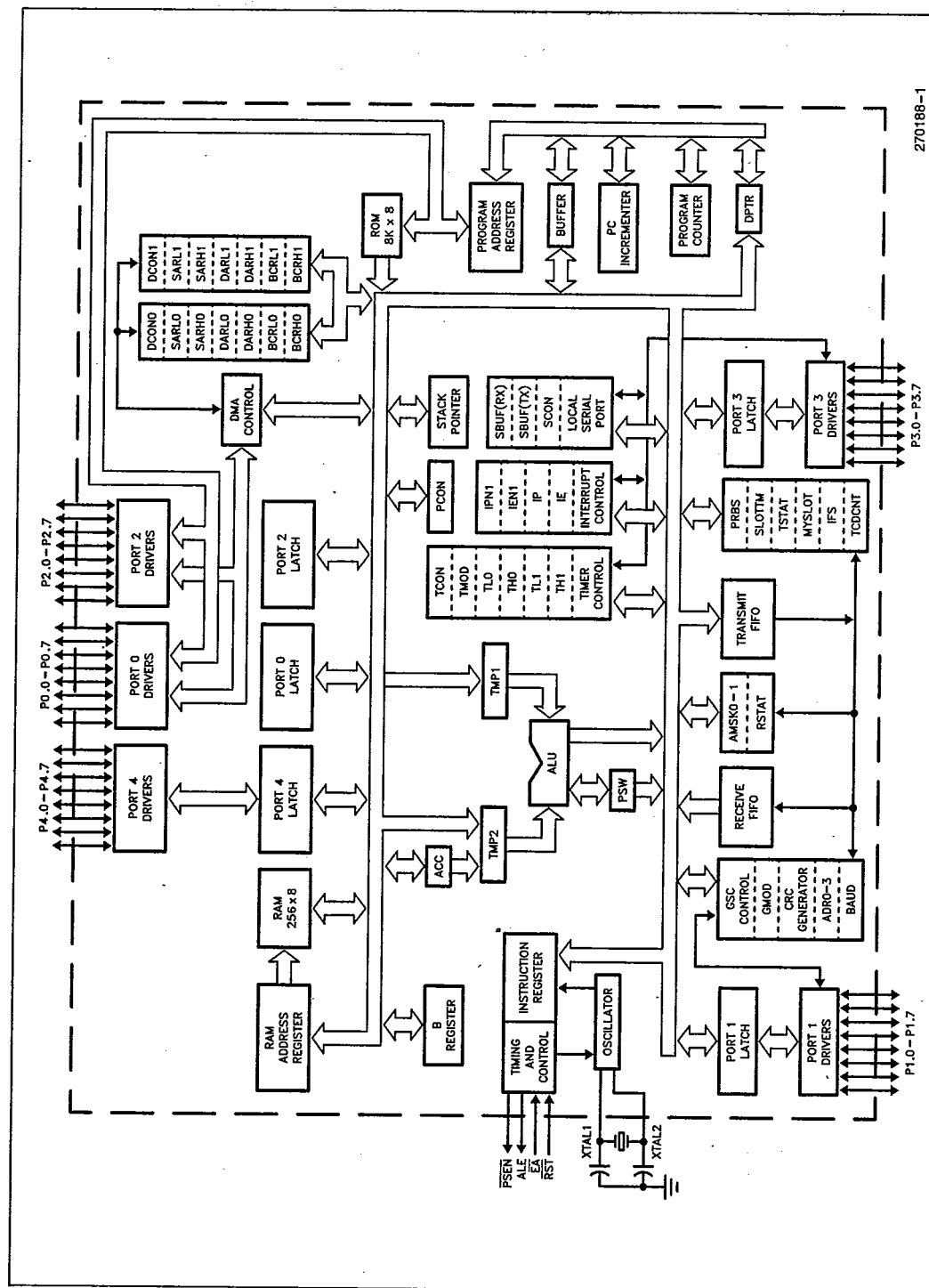


Figure 2. Block Diagram

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| Pin # | | Pin Description | | | | | | | | | | | | | | | | | | | | | | | | | |
|-----------------|----------------------------|---|-----|------|--------------------|------|------|--------------------|------|------|---------------------|------|------|--|------|------|---|------|-----|--|------|-----|------------------------|------|------|-----------------------------------|------|
| DIP | PLCC(1) | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 48 | 2 | V _{CC} —Supply voltage. | | | | | | | | | | | | | | | | | | | | | | | | | |
| 24 | 3,33(2) | V _{SS} —Circuit ground. | | | | | | | | | | | | | | | | | | | | | | | | | |
| 18-21, 25-28 | 27-30, 34-37 | <p>Port 0—Port 0 is an 8-bit open drain bidirectional I/O port. As an output port each pin can sink 8 LS TTL inputs. Port 0 pins that have 1s written to them float, and in that state can be used as high-impedance inputs.</p> <p>Port 0 is also the multiplexed low-order address and data bus during accesses to external memory. In this application it uses strong internal pullups when emitting 1s.</p> <p>Port 0 also outputs the code bytes during program verification. External pullups are required during program verification.</p> | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1-8 | 4-11 | <p>Port 1—Port 1 is an 8-bit bidirectional I/O port with internal pullups. Port 1 pins that have 1s written to them are pulled high by the internal pullups, and in that state can be used as inputs. As inputs, Port 1 pins that are externally being pulled low will source current (I_{IL}, on the data sheet) because of the internal pullups.</p> <p>Port 1 also serves the functions of various special features of the 8XC152, as listed below:</p> | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | <table><tr><th>Pin</th><th>Name</th><th>Alternate Function</th></tr><tr><td>P1.0</td><td>GRXD</td><td>GSC data input pin</td></tr><tr><td>P1.1</td><td>GTxD</td><td>GSC data output pin</td></tr><tr><td>P1.2</td><td>DEN</td><td>GSC enable signal for an external driver</td></tr><tr><td>P1.3</td><td>TXC</td><td>GSC input pin for external transmit clock</td></tr><tr><td>P1.4</td><td>RXC</td><td>GSC input pin for external receive clock</td></tr><tr><td>P1.5</td><td>HLD</td><td>DMA hold input/output</td></tr><tr><td>P1.6</td><td>HLDA</td><td>DMA hold acknowledge input/output</td></tr></table> | Pin | Name | Alternate Function | P1.0 | GRXD | GSC data input pin | P1.1 | GTxD | GSC data output pin | P1.2 | DEN | GSC enable signal for an external driver | P1.3 | TXC | GSC input pin for external transmit clock | P1.4 | RXC | GSC input pin for external receive clock | P1.5 | HLD | DMA hold input/output | P1.6 | HLDA | DMA hold acknowledge input/output | |
| Pin | Name | Alternate Function | | | | | | | | | | | | | | | | | | | | | | | | | |
| P1.0 | GRXD | GSC data input pin | | | | | | | | | | | | | | | | | | | | | | | | | |
| P1.1 | GTxD | GSC data output pin | | | | | | | | | | | | | | | | | | | | | | | | | |
| P1.2 | DEN | GSC enable signal for an external driver | | | | | | | | | | | | | | | | | | | | | | | | | |
| P1.3 | TXC | GSC input pin for external transmit clock | | | | | | | | | | | | | | | | | | | | | | | | | |
| P1.4 | RXC | GSC input pin for external receive clock | | | | | | | | | | | | | | | | | | | | | | | | | |
| P1.5 | HLD | DMA hold input/output | | | | | | | | | | | | | | | | | | | | | | | | | |
| P1.6 | HLDA | DMA hold acknowledge input/output | | | | | | | | | | | | | | | | | | | | | | | | | |
| 29-36 | 41-48 | <p>Port 2—Port 2 is an 8-bit bidirectional I/O port with internal pullups. Port 2 pins that have 1s written to them are pulled high by the internal pullups, and in that state can be used as inputs. As inputs, Port 2 pins that are externally being pulled low will source current (I_{IL}, on the data sheet) because of the internal pullups.</p> <p>Port 2 emits the high-order address byte during fetches from external Program Memory and during accesses to external Data Memory that use 16-bit addresses (MOVX @ DPTR and DMA operations). In this application it uses strong internal pullups when emitting 1s.</p> <p>During accesses to external Data Memory that use 8-bit addresses (MOVX @ Ri), Port 2 emits the contents of the P2 Special Function Register.</p> <p>Port 2 also receives the high-order address bits during program verification.</p> | | | | | | | | | | | | | | | | | | | | | | | | | |
| 10-17 | 14-16, 18, 19, 23-25 | <p>Port 3—Port 3 is an 8-bit bidirectional I/O port with internal pullups. Port 3 pins that have 1s written to them are pulled high by the internal pullups, and in that state can be used as inputs. As inputs, Port 3 pins that are externally being pulled low will source current (I_{IL}, on the data sheet) because of the pullups.</p> <p>Port 3 also serves the functions of various special features of the MCS-51 Family, as listed below:</p> | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | <table><tr><th>Pin</th><th>Name</th><th>Alternate Function</th></tr><tr><td>P3.0</td><td>RXD</td><td>Serial input line</td></tr><tr><td>P3.1</td><td>TXD</td><td>Serial output line</td></tr><tr><td>P3.2</td><td>INT0</td><td>External Interrupt 0</td></tr><tr><td>P3.3</td><td>INT1</td><td>External Interrupt 1</td></tr><tr><td>P3.4</td><td>T0</td><td>Timer 0 external input</td></tr><tr><td>P3.5</td><td>T1</td><td>Timer 1 external input</td></tr><tr><td>P3.6</td><td>WR</td><td>External Data Memory Write strobe</td></tr><tr><td>P3.7</td><td>RD</td><td>External Data Memory Read strobe</td></tr></table> | Pin | Name | Alternate Function | P3.0 | RXD | Serial input line | P3.1 | TXD | Serial output line | P3.2 | INT0 | External Interrupt 0 | P3.3 | INT1 | External Interrupt 1 | P3.4 | T0 | Timer 0 external input | P3.5 | T1 | Timer 1 external input | P3.6 | WR | External Data Memory Write strobe | P3.7 |
| Pin | Name | Alternate Function | | | | | | | | | | | | | | | | | | | | | | | | | |
| P3.0 | RXD | Serial input line | | | | | | | | | | | | | | | | | | | | | | | | | |
| P3.1 | TXD | Serial output line | | | | | | | | | | | | | | | | | | | | | | | | | |
| P3.2 | INT0 | External Interrupt 0 | | | | | | | | | | | | | | | | | | | | | | | | | |
| P3.3 | INT1 | External Interrupt 1 | | | | | | | | | | | | | | | | | | | | | | | | | |
| P3.4 | T0 | Timer 0 external input | | | | | | | | | | | | | | | | | | | | | | | | | |
| P3.5 | T1 | Timer 1 external input | | | | | | | | | | | | | | | | | | | | | | | | | |
| P3.6 | WR | External Data Memory Write strobe | | | | | | | | | | | | | | | | | | | | | | | | | |
| P3.7 | RD | External Data Memory Read strobe | | | | | | | | | | | | | | | | | | | | | | | | | |

NOTES:

1. N.C. pins on PLCC package may be connected to internal die and should not be used in customer applications.
2. It is recommended that both Pin 3 and Pin 33 be grounded for PLCC devices.

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Pin Description (Continued)

| Pin # | | Pin Description |
|-------|-------|---|
| 47-40 | 65-58 | Port 4 —Port 4 is an 8-bit bidirectional I/O port with internal pullups. Port 4 pins that have 1s written to them are pulled high by the internal pullups, and in that state can be used as inputs. As inputs, Port 4 pins that are externally being pulled low will source current (I_{IL} , on the data sheet) because of the internal pullups. In addition, Port 4 also receives the low-order address bytes during program verification. |
| 9 | 13 | RST —Reset input. A logic low on this pin for three machine cycles while the oscillator is running resets the device. An internal pullup resistor permits a power-on reset to be generated using only an external capacitor to V_{SS} . Although the GSC recognizes the reset after three machine cycles, data may continue to be transmitted for up to 4 machine cycles after Reset is first applied. |
| 38 | 55 | ALE —Address Latch Enable output signal for latching the low byte of the address during accesses to external memory. In normal operation ALE is emitted at a constant rate of $1/6$ the oscillator frequency, and may be used for external timing or clocking purposes. Note, however, that one ALE pulse is skipped during each access to external Data Memory. While in Reset, ALE remains at a constant high level. |
| 37 | 54 | PSEN —Program Store Enable is the Read strobe to External Program Memory. When the 8XC152 is executing from external program memory, PSEN is active (low). When the device is executing code from External Program Memory, PSEN is activated twice each machine cycle, except that two PSEN activations are skipped during each access to External Data Memory. While in Reset, PSEN remains at a constant high level. |
| 39 | 56 | EA —External Access enable. EA must be externally pulled low in order to enable the 8XC152 to fetch code from External Program Memory locations 0000H to 0FFFFH. EA must be connected to V_{CC} for internal program execution. |
| 23 | 32 | XTAL1 —Input to the inverting oscillator amplifier and input to the internal clock generating circuits. |
| 22 | 31 | XTAL2 —Output from the inverting oscillator amplifier. |

OSCILLATOR CHARACTERISTICS

XTAL1 and XTAL2 are the input and output, respectively, of an inverting amplifier which can be configured for use as an on-chip oscillator, as shown in Figure 3.

To drive the device from an external clock source, XTAL1 should be driven, while XTAL2 is left unconnected, as shown in Figure 4. There are no requirements on the duty cycle of the external clock signal, since the input to the internal clocking circuitry is through a divide-by-two flip-flop, but minimum and maximum high and low times specified on the Data Sheet must be observed.

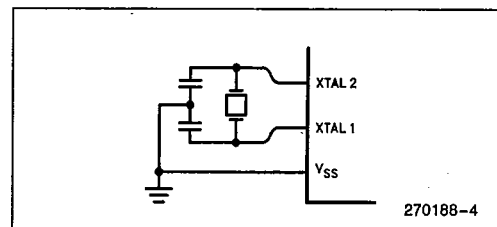


Figure 3. Using the On-Chip Oscillator

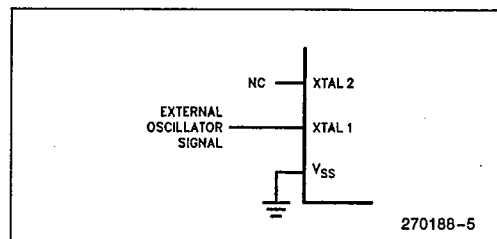


Figure 4. External Clock Drive

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IDLE MODE

In Idle Mode, the CPU puts itself to sleep while most of the on-chip peripherals remain active. The major peripherals that do not remain active during Idle, are the DMA channels. The Idle Mode is invoked by software. The content of the on-chip RAM and all the Special Function Registers remain unchanged during this mode. The Idle Mode can be terminated by any enabled interrupt or by a hardware reset.

POWER DOWN MODE

In Power Down Mode, the oscillator is stopped and all on-chip functions cease except that the on-chip RAM contents are maintained. The mode Power Down is invoked by software. The Power Down Mode can be terminated only by a hardware reset.

Table 1. Status of the external pins during Idle and Power Down modes

| Mode | Program Memory | ALE | PSEN | Port 0 | Port 1 | Port 2 | Port 3 | Port 4 |
|------------|----------------|-----|------|--------|--------|---------|--------|--------|
| Idle | Internal | 1 | 1 | Data | Data | Data | Data | Data |
| Idle | External | 1 | 1 | Float | Data | Address | Data | Data |
| Power Down | Internal | 0 | 0 | Data | Data | Data | Data | Data |
| Power Down | External | 0 | 0 | Float | Data | Data | Data | Data |

NOTE:

For more detailed information on the reduced power modes refer to the Embedded Controller Handbook, and Application Note AP-252, "Designing with the 80C51BH."

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PRELIMINARY

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ABSOLUTE MAXIMUM RATINGS*

Ambient Temperature Under Bias0°C to +70°C
 Storage Temperature -65°C to +150°C
 Voltage on Any pin to V_{SS} . . -0.5V to (V_{CC} + 0.5V)
 Voltage on V_{CC} to V_{SS} -0.5V to +6.5V
 Power Dissipation 1.0 W(7)

*Notice: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

NOTICE: Specifications contained within the following tables are subject to change.

D.C. CHARACTERISTICS (T_A = 0°C to +70°C; V_{CC} = 5V ± 10%; V_{SS} = 0V)

| Symbol | Parameter | Min | Typ (Note 1) | Max | Unit | Test Conditions |
|------------------|--|--------------------------|-----------------|--------------------------|------|---|
| V _{IL} | Input Low Voltage (All Except EA) | -0.5 | | 0.2V _{CC} - 0.1 | V | |
| V _{IL1} | Input Low Voltage (EA) | -0.5 | | 0.2V _{CC} - 0.3 | V | |
| V _{IH} | Input High Voltage (Except XTAL1, RST) | 0.2V _{CC} + 0.9 | | V _{CC} + 0.5 | V | |
| V _{IH1} | Input High Voltage (XTAL1, RST) | 0.7V _{CC} | | V _{CC} + 0.5 | V | |
| V _{OL} | Output Low Voltage (Ports 1, 2, 3, 4) | | | 0.45 | V | I _{OL} = 1.6 mA (Note 2) |
| V _{OL1} | Output Low Voltage (Port 0, ALE, PSEN) | | | 0.45 | V | I _{OL} = 3.2 mA (Note 2) |
| V _{OH} | Output High Voltage (Ports 1, 2, 3, 4, ALE, PSEN) | 2.4 | | | V | I _{OH} = -60 μA V _{CC} = 5V ± 10% |
| | | 0.9V _{CC} | | | V | I _{OH} = -10 μA |
| V _{OH1} | Output High Voltage (Port 0 in External Bus Mode) | 2.4 | | | V | I _{OH} = -400 μA V _{CC} = 5V ± 10% |
| | | 0.9V _{CC} | | | V | I _{OH} = -40 μA (Note 3) |
| I _{IL} | Logical 0 Input Current (Ports 1, 2, 3, 4) | | | -50 | μA | V _{IN} = 0.45V |
| I _{TL} | Logical 1 to 0 Transition Current (Ports 1, 2, 3, 4) | | | -650 | μA | V _{IN} = 2V |
| I _{LI} | Input Leakage (Port 0, EA) | | | ± 10 | μA | 0.45 < V _{IN} < V _{CC} |
| RRST | Reset Pullup Resistor | 40 | | | kΩ | |

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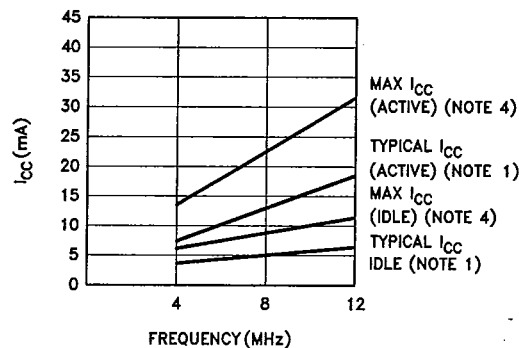
NOTES:

1. "Typicals" are based on samples taken from early manufacturing lots and are not guaranteed. The measurements were made with $V_{CC} = 5V$ at room temperature.
2. Capacitive loading on Ports 0 and 2 may cause spurious noise pulses to be superimposed on the V_{OLs} of ALE and Ports 1 and 3. The noise is due to external bus capacitance discharging into the Port 0 and Port 2 pins when these pins make 1-to-0 transitions during bus operations. In the worst cases (capacitive loading > 100 pF), the noise pulse on the ALE pin may exceed 0.8V. In such cases it may be desirable to qualify ALE with a Schmitt Trigger, or use an address latch with a Schmitt Trigger STROBE input.
3. Capacitive loading on Ports 0 and 2 may cause the V_{OH} on ALE and \overline{PSEN} to momentarily fall below the $0.9V_{CC}$ specification when the address bits are stabilizing.
4. I_{CC} is measured with all output pins disconnected; XTAL1 driven with TCLCH, TCHCL = 5 ns, $V_{IL} = V_{SS} + 0.5V$, $V_{IH} = V_{CC} - 0.5V$; XTAL2 N.C.; Port 0 pins connected to V_{CC} . "Operating" current is measured with EA connected to V_{CC} and RST connected to V_{SS} . "Idle" current is measured with EA connected to V_{SS} , RST connected to V_{CC} and GSC inactive.
5. The specifications relating to external data memory characteristics are also applicable to DMA operations.
6. TQVWX should not be confused with TQVWX as specified for 80C51BH. On 80C152, TQVWX is measured from data valid to rising edge of WR. On 80C51BH, TQVWX is measured from data valid to falling edge of WR. See timing diagrams.
7. This value is based on the maximum allowable die temperature and the thermal resistance of the package.

$$\text{MAX } I_{CC} (\text{ACTIVE}) = (2.24 \times \text{FREQ}) + 4.16 \text{ (Note 4)}$$

$$\text{MAX } I_{CC} (\text{IDLE}) = (0.8 \times \text{FREQ}) + 2.2 \text{ (Note 4)}$$

where FREQ is the external oscillator Frequency in Megahertz and I_{CC} is in Milliamps



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Figure 5. I_{CC} vs Frequency**EXPLANATION OF THE AC SYMBOLS**

Each timing symbol has 5 characters. The first character is always a 'T' (stands for time). The other characters, depending on their positions, stand for the name of a signal or the logical status of that signal. The following is a list of all the characters and what they stand for.

- A: Address.
- C: Clock
- D: Input data.
- H: Logic level HIGH.

- I: Instruction (program memory contents).
- L: Logic level LOW, or ALE.
- P: \overline{PSEN} .
- Q: Output data.
- R: READ signal.
- T: Time.
- V: Valid.
- W: WRITE signal.
- X: No longer a valid logic level.
- Z: Float.

For example,

TAVLL = Time for Address Valid to ALE Low.
 TLLPL = Time for ALE Low to \overline{PSEN} Low.

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A.C. CHARACTERISTICS ($T_A = 0^\circ\text{C}$ to $+70^\circ\text{C}$; $V_{CC} = 5\text{V} \pm 10\%$; $V_{SS} = 0\text{V}$; Load Capacitance for Port 0, ALE, and $\overline{\text{PSEN}} = 100\text{ pF}$; Load Capacitance for All Other Outputs = 80 pF)

EXTERNAL PROGRAM AND DATA MEMORY CHARACTERISTICS (Note 5)

| Symbol | Parameter | 12 MHz | | Variable Oscillator | | Unit |
|-------------------|---|--------|-----|---------------------|-------------|------|
| | | Min | Max | Min | Max | |
| 1/TCLCL | Oscillator Frequency | | | 3.5 | 12 | MHz |
| TLHLL | ALE Pulse Width | 126 | | 2TCLCL-40 | | ns |
| TAVLL | Address Valid to ALE Low | 28 | | TCLCL-55 | | ns |
| TLLAX | Address Hold After ALE Low | 48 | | TCLCL-35 | | ns |
| TLLIV | ALE Low to Valid Instruction In | | 233 | | 4TCLCL-100 | ns |
| TLLPL | ALE Low to $\overline{\text{PSEN}}$ Low | 43 | | TCLCL-40 | | ns |
| TPLPH | $\overline{\text{PSEN}}$ Pulse Width | 205 | | 3TCLCL-45 | | ns |
| TPLIV | $\overline{\text{PSEN}}$ Low to Valid Instruction In | | 145 | | 3TCLCL-105 | ns |
| TPXIX | Input Instruction Hold After $\overline{\text{PSEN}}$ | 0 | | 0 | | ns |
| TPXIZ | Input Instruction Float After $\overline{\text{PSEN}}$ | | 58 | | TCLCL-25 | ns |
| TAVIV | Address to Valid Instruction In | | 311 | | 5TCLCL-105 | ns |
| TPLAZ | $\overline{\text{PSEN}}$ Low to Address Float | | 10 | | 10 | ns |
| TRLRH | $\overline{\text{RD}}$ Pulse Width | 400 | | 6TCLCL-100 | | ns |
| TWLWH | $\overline{\text{WR}}$ Pulse Width | 400 | | 6TCLCL-100 | | ns |
| TRLDV | $\overline{\text{RD}}$ Low to Valid Data In | | 251 | | 5TCLCL-165 | ns |
| TRHDX | Data Hold After $\overline{\text{RD}}$ | 0 | | 0 | | ns |
| TRHDZ | Data Float After $\overline{\text{RD}}$ | | 96 | | 2TCLCL-70 | ns |
| TLLDV | ALE Low to Valid Data In | | 516 | | 8TCLCL-150 | ns |
| TAVDV | Address to Valid Data In | | 585 | | 9TCLCL-165 | ns |
| TLLWL | ALE Low to $\overline{\text{RD}}$ or $\overline{\text{WR}}$ Low | 200 | 300 | 3TCLCL-50 | 3TCLCL + 50 | ns |
| TAVWL | Address to $\overline{\text{RD}}$ or $\overline{\text{WR}}$ Low | 203 | | 4TCLCL-130 | | ns |
| TQVWX (Note 6) | Data Valid to $\overline{\text{WR}}$ Transition | 333 | | 6TCLCL-167 | | ns |
| TWHQX | Data Hold After $\overline{\text{WR}}$ | 33 | | TCLCL-50 | | ns |
| TRLAZ | $\overline{\text{RD}}$ Low to Address Float | | 0 | | 0 | ns |
| TWHLH | $\overline{\text{RD}}$ or $\overline{\text{WR}}$ High to ALE High | 43 | 123 | TCLCL-40 | TCLCL + 40 | ns |

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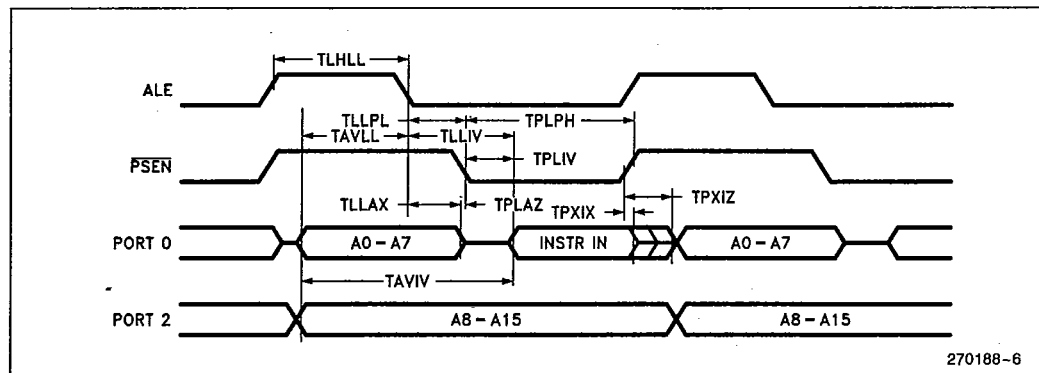


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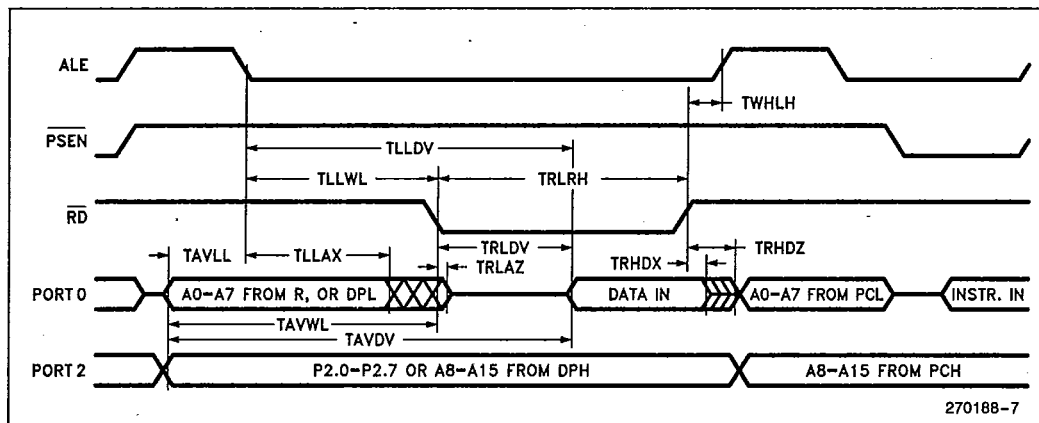
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EXTERNAL PROGRAM MEMORY READ CYCLE



EXTERNAL DATA MEMORY READ CYCLE



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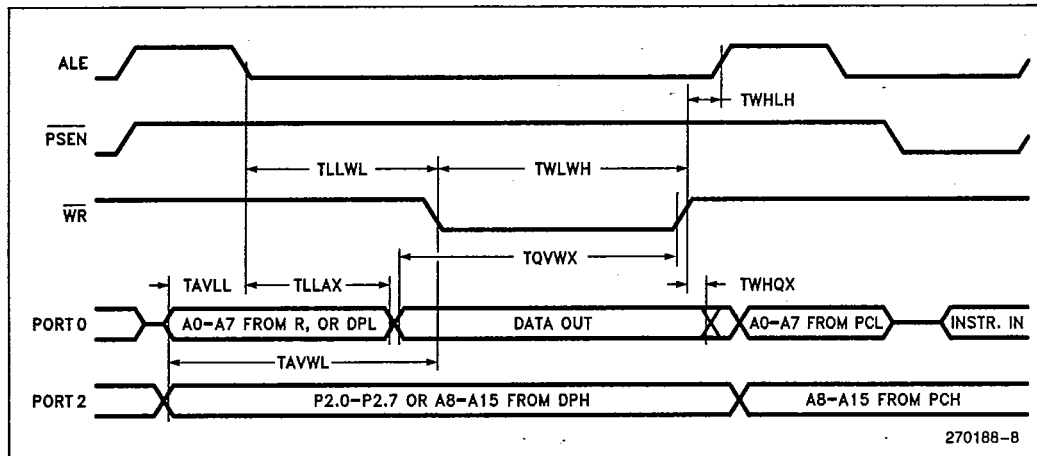


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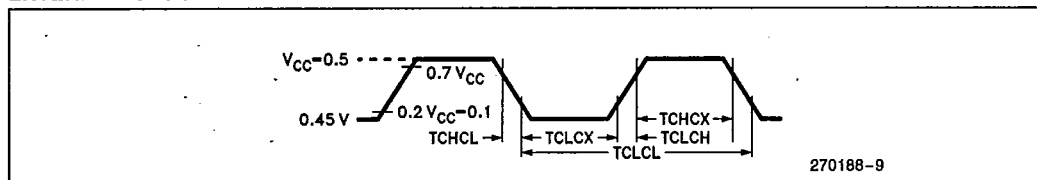
EXTERNAL DATA MEMORY WRITE CYCLE



EXTERNAL CLOCK DRIVE

| Symbol | Parameter | Min | Max | Units |
|---------|----------------------|-----|-----|-------|
| 1/TCLCL | Oscillator Frequency | 3.5 | 12 | MHz |
| TCHCX | High Time | 20 | | ns |
| TCLCX | Low Time | 20 | | ns |
| TCLCH | Rise Time | | 20 | ns |
| TCHCL | Fall Time | | 20 | ns |

EXTERNAL CLOCK DRIVE WAVEFORM



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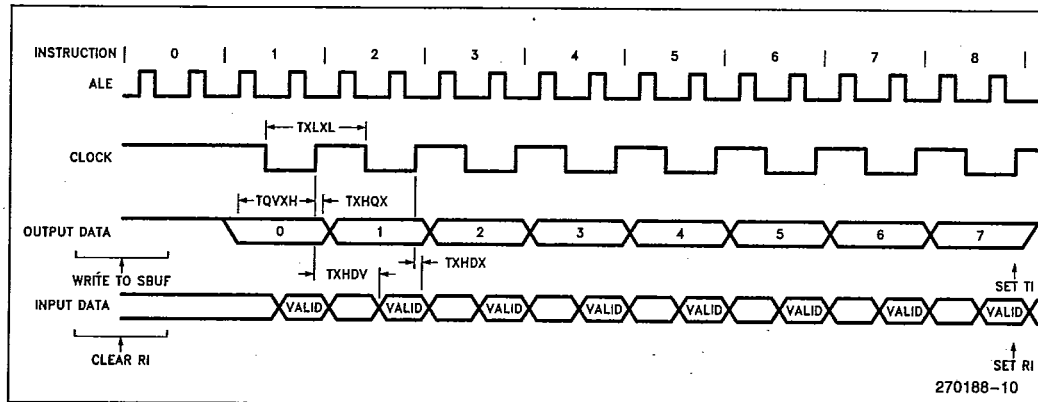
PRELIMINARY

T-52-33-05

LOCAL SERIAL CHANNEL TIMING—SHIFT REGISTER MODE

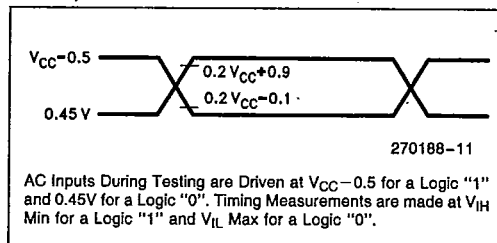
| Symbol | Parameter | 12 MHz | | Variable Oscillator | | Units |
|--------|--|--------|-----|---------------------|-------------|-------|
| | | Min | Max | Min | Max | |
| TXLXL | Serial Port Clock Cycle Time | 1000 | | 12TCLCL | | ns |
| TQVXH | Output Data Setup to Clock Rising Edge | 700 | | 10TCLCL-133 | | ns |
| TXHQX | Output Data Hold After Clock Rising Edge | 50 | | 2TCLCL-117 | | ns |
| TXHDX | Input Data Hold After Clock Rising Edge | 0 | | 0 | | ns |
| TXHDV | Clock Rising Edge to Input Data Valid | | 700 | | 10TCLCL-133 | ns |

SHIFT REGISTER MODE TIMING WAVEFORMS



A.C. TESTING:

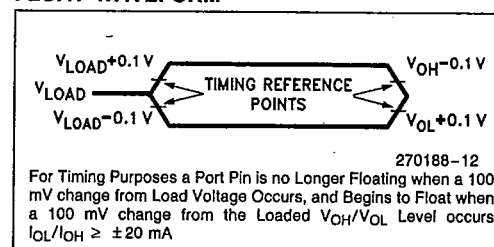
INPUT, OUTPUT WAVEFORMS



270188-11

AC Inputs During Testing are Driven at $V_{CC}-0.5$ for a Logic "1" and $0.45V$ for a Logic "0". Timing Measurements are made at V_{IH} Min for a Logic "1" and V_{IL} Max for a Logic "0".

FLOAT WAVEFORM



270188-12

For Timing Purposes a Port Pin is no Longer Floating when a 100 mV change from Load Voltage Occurs, and Begins to Float when a 100 mV change from the Loaded V_{OH}/V_{OL} Level occurs $I_{OL}/I_{OH} \geq \pm 20$ mA

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99D 59663 D



80C152A/83C152A

PRELIMINARY

T-52-33-05

GLOBAL SERIAL PORT TIMINGS—Internal Baud Rate Generator

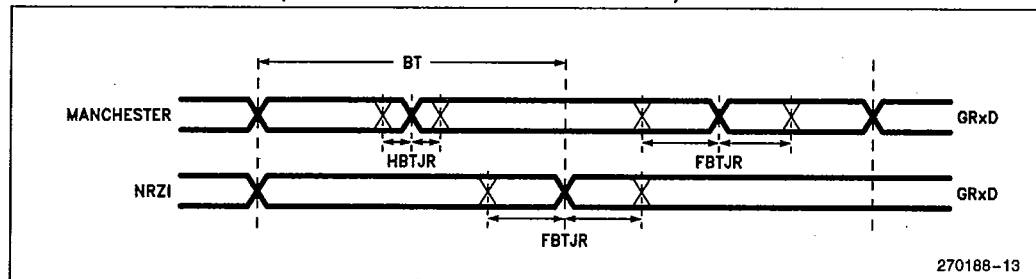
| Symbol | Parameter | 12 MHz (BAUD = 0) | | Variable Oscillator | | Unit |
|--------|--|-------------------|----------|---------------------|---|---------------|
| | | Min | Max | Min | Max | |
| HBTJR | Allowable jitter on the Receiver for 1/2 bit time (Manchester encoding only) | | 0.058 | | $(0.125 \times (\text{BAUD} + 1) \times 8\text{TCLCL}) - 25 \text{ ns}$ | μs |
| FBTJR | Allowable jitter on the Receiver for one full bit time (NRZI and Manchester) | | 0.142 | | $(0.25 \times (\text{BAUD} + 1) \times 8\text{TCLCL}) - 25 \text{ ns}$ | μs |
| HBTJT | Jitter of data from Transmitter for 1/2 bit time (Manchester encoding only) | | ± 35 | | ± 35 | ns |
| FBTJT | Jitter of data from Transmitter for one full bit time (NRZI and Manchester) | | ± 70 | | ± 70 | ns |
| DRTR | Data rise time for Receiver (Note 8) | | 20 | | 20 | ns |
| DFTR | Data fall time for Receiver (Note 9) | | 20 | | 20 | ns |

NOTES:

8. Same as TCLCH, use External Clock Drive Waveform.

9. Same as TCHCL, use External Clock Drive Waveform.

GSC RECEIVER TIMINGS (INTERNAL BAUD RATE GENERATOR)



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99D 59664 D

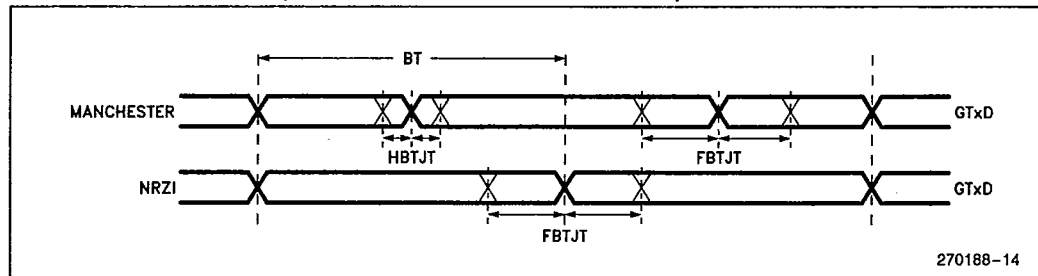


80C152A/83C152A

PRELIMINARY

T-52-33-05

GSC TRANSMIT TIMINGS (INTERNAL BAUD RATE GENERATOR)



GLOBAL SERIAL PORT TIMINGS—External Clock

| Symbol | Parameter | 12 MHz | | Variable Oscillator | | Unit |
|--------|---|--------|-----|---------------------|----------|------|
| | | Min | Max | Min | Max | |
| 1/ECBT | GSC Frequency with an External Clock | 0.009 | 2.4 | 0.009 | 1/5TCLCL | MHz |
| ECH | External Clock High | 197 | | 2TCLCL + 30 ns | | ns |
| ECL | External Clock Low | 197 | | 2TCLCL + 30 ns | | ns |
| ECRT | External Clock Rise Time (Note 8) | | 20 | | 20 | ns |
| ECFT | External Clock Fall Time (Note 9) | | 20 | | 20 | ns |
| ECDVT | External Clock to Data Valid Out - Transmit (to External Clock Negative Edge) | | 150 | | 150 | ns |
| ECDHT | External Clock Data Hold - Transmit (to External Clock Negative Edge) | 0 | | 0 | | ns |
| ECDSR | External Clock Data Set-up - Receiver (to External Clock Positive Edge) | 45 | | 45 | | ns |
| ECDHR | External Clock to Data Hold - Receiver (to External Clock Positive Edge) | 50 | | 50 | | ns |

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99D 59665 D

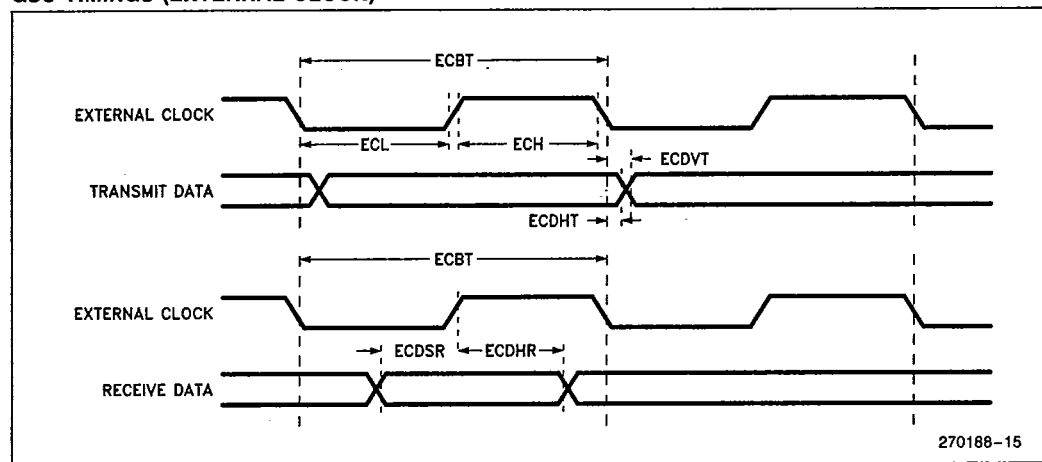


80C152A/83C152A

PRELIMINARY

T-52-33-05

GSC TIMINGS (EXTERNAL CLOCK)



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99D 59666 D



80C152A/83C152A

PRELIMINARY

T-52-33-05

NOTES ON THE OPERATION OF THE 80C152A**1. Current in Power Down Mode**

Typically, I_{CC} in Power Down Mode is about $10 \mu A$. However, you may note under certain conditions an abnormally high I_{CC} , about $600 \mu A$, in Power Down. This is caused by an interaction between internal signals local to the interrupt control system. The problem disappears once an interrupt, any interrupt, is requested and serviced. Therefore, if I_{CC} in Power Down is critical to the application, it is suggested that an interrupt be generated and exercised before Power Down is invoked.

2. SDLC Flags While Idling

In SDLC Mode, the GSC can be programmed to transmit SDLC flags between transmission frames. This is done by setting the GFLEN bit in PCON. When the GSC is so programmed, the \overline{DEN} signal is asserted only during the actual transmission frame, not during the idle fill flags. In this case the \overline{DEN} signal will normally not be used to enable the line driver, but is available for use as a positive indication that a transmission frame is in progress.

3. Immediate Deactivation of \overline{DEN} in CSMA/CD Mode

CSMA/CD protocols typically require two bit-times of inactivity in the line to indicate an idle condition. Note, however, that the 80C152A deactivates \overline{DEN} immediately at the end of the transmission frame.