

HB56A1636 Series, HB56A1632 Series

16,777,216-word $\times$ 36-bit High Density Dynamic RAM Module

16,777,216-word $\times$ 32-bit High Density Dynamic RAM Module

HITACHI

ADE-203-752A (Z)

Rev.1.0

Feb. 27, 1997

Description

The HB56A1636 is a $16\text{M} \times 36$ dynamic RAM module, mounted 36 pieces of 16-Mbit DRAM (HM5116100) sealed in SOJ package. The HB56A1632 is a $16\text{M} \times 32$ dynamic RAM module, mounted 32 pieces of 16-Mbit DRAM (HM5116100) sealed in SOJ package. An outline of the HB56A1636, HB56A1632 is 72-pin single in-line package. Therefore, the HB56A1636, HB56A1632 make high density mounting possible without surface mount technology. The HB56A1636, HB56A1632 provide common data inputs and outputs. Decoupling capacitors are mounted on the module board.

Features

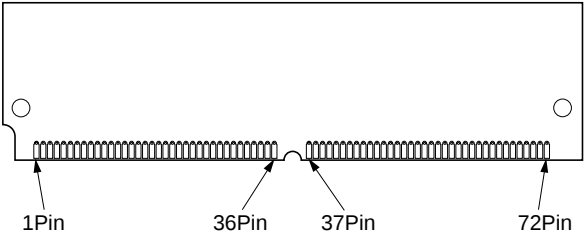
- 72-pin single in-line package
 - Outline: 115.57 mm (Length) $\times$ 36.195 mm (Height) $\times$ 9.10 mm (Thickness)
 - Lead pitch: 1.27 mm
- Single 5 V ($\pm 5\%$) supply
- High speed
 - Access time: $t_{\text{RAC}} = 50/60/70$ ns (max)
- Low power dissipation
 - Active mode: 17.01/15.12/13.23 W (max) (HB56A1636 Series)
15.12/13.44/11.76 W (max) (HB56A1632 Series)
 - Standby mode (TTL): 378 mW (max) (HB56A1636 Series)
(TTL): 336 mW (max) (HB56A1632 Series)
(CMOS): 189 mW (max) (HB56A1636 Series)
(CMOS): 168 mW (max) (HB56A1632 Series)
- Fast page mode capability
- Refresh period
 - 4096 refresh cycles: 64 ms
- 3 variations of refresh
 - $\overline{\text{RAS}}$ -only refresh
 - $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh
 - Hidden refresh
- TTL compatible

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Ordering Information

Type No.	Access time	Package	Contact pad
HB56A1636B-5	50 ns	72-pin SIP socket type	Gold
HB56A1636B-6	60 ns		
HB56A1636B-7	70 ns		
HB56A1632B-5	50 ns	72-pin SIP socket type	Solder
HB56A1632B-6	60 ns		
HB56A1632B-7	70 ns		
HB56A1636SB-5	50 ns	72-pin SIP socket type	Solder
HB56A1636SB-6	60 ns		
HB56A1636SB-7	70 ns		
HB56A1632SB-5	50 ns	72-pin SIP socket type	Solder
HB56A1632SB-6	60 ns		
HB56A1632SB-7	70 ns		

Pin Arrangement



Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name
1	V _{SS}	19	A10	37	DQ17 (NC)* ³	55	DQ12
2	DQ0	20	DQ4	38	DQ35 (NC)* ⁴	56	DQ30
3	DQ18	21	DQ22	39	V _{SS}	57	DQ13
4	DQ1	22	DQ5	40	$\overline{\text{CAS0}}$	58	DQ31
5	DQ19	23	DQ23	41	$\overline{\text{CAS2}}$	59	V _{CC}
6	DQ2	24	DQ6	42	$\overline{\text{CAS3}}$	60	DQ32
7	DQ20	25	DQ24	43	$\overline{\text{CAS1}}$	61	DQ14
8	DQ3	26	DQ7	44	$\overline{\text{RAS0}}$	62	DQ33
9	DQ21	27	DQ25	45	NC	63	DQ15
10	V _{CC}	28	A7	46	NC	64	DQ34
11	NC	29	A11	47	$\overline{\text{WE}}$	65	DQ16
12	A0	30	V _{CC}	48	NC	66	NC
13	A1	31	A8	49	DQ9	67	PD1
14	A2	32	A9	50	DQ27	68	PD2
15	A3	33	NC	51	DQ10	69	PD3
16	A4	34	$\overline{\text{RAS2}}$	52	DQ28	70	PD4
17	A5	35	DQ26 (NC)* ¹	53	DQ11	71	NC
18	A6	36	DQ8 (NC)* ²	54	DQ29	72	V _{SS}

Notes: 1. DQ26: HB56A1636, NC: HB56A1632
2. DQ8: HB56A1636, NC: HB56A1632
3. DQ17: HB56A1636, NC: HB56A1632
4. DQ35: HB56A1636, NC: HB56A1632

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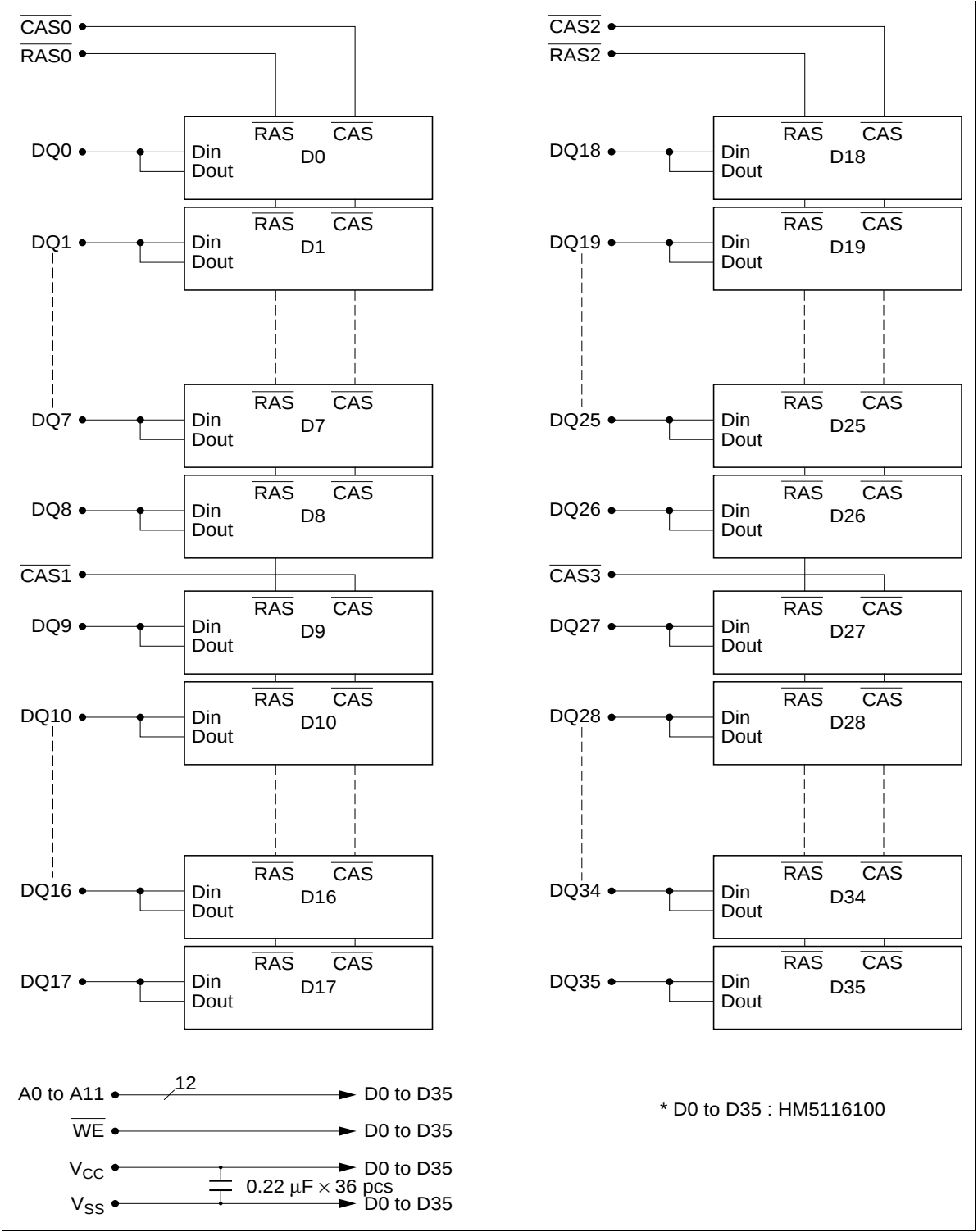
Pin Description

Pin name	Function
A0 to A11	Address inputs: — Row address: A0 to A11 — Column address: A0 to A11 — Refresh address: A0 to A11
DQ0 to DQ35	Data-in/Data-out
$\overline{\text{CAS0}}$ to $\overline{\text{CAS3}}$	Column address strobe
$\overline{\text{RAS0}}$, $\overline{\text{RAS2}}$	Row address strobe
$\overline{\text{WE}}$	Read/Write enable
V_{CC}	Power supply
V_{SS}	Ground
PD1 to PD4	Presence detect pin
NC	No connection

Presence Detect Pin Arrangement

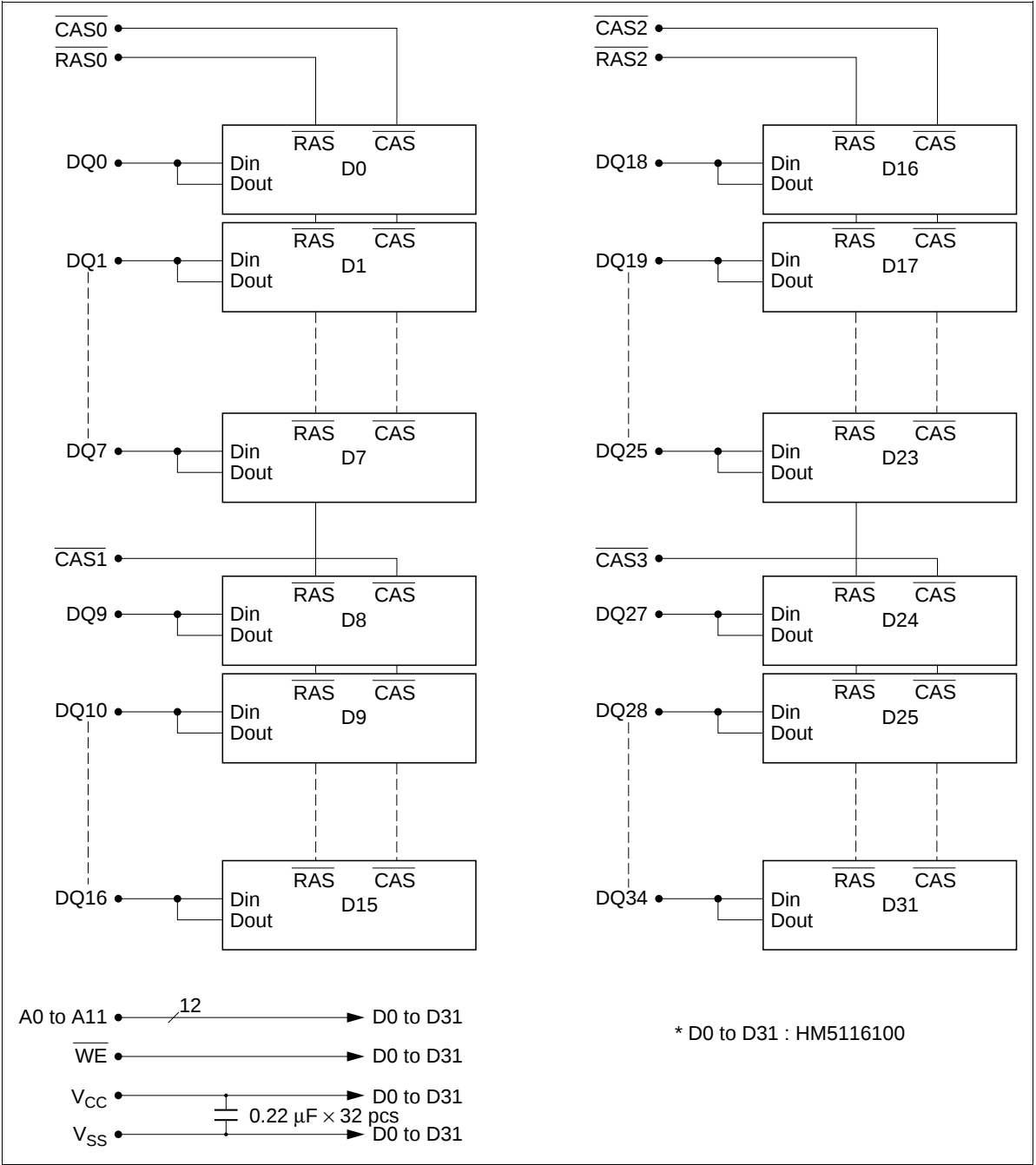
Pin No.	Pin name	Function		
		50 ns	60 ns	70 ns
67	PD1	V_{SS}	V_{SS}	V_{SS}
68	PD2	V_{SS}	V_{SS}	V_{SS}
69	PD3	V_{SS}	NC	V_{SS}
70	PD4	V_{SS}	NC	NC

Block Diagram (HB56A1636)



HB56A1636 Series, HB56A1632 Series

Block Diagram (HB56A1632)



Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Voltage on any pin relative to V_{SS}	V_T	−1.0 to +7.0	V
Supply voltage relative to V_{SS}	V_{CC}	−1.0 to +7.0	V
Short circuit output current	I_{out}	50	mA
Power dissipation (HB56A1636)	Pt	36	W
Power dissipation (HB56A1632)	Pt	32	W
Operating temperature	T_{opr}	0 to +70	°C
Storage temperature	T_{stg}	−55 to +125	°C

Recommended DC Operating Conditions ($T_a = 0$ to 70°C)

Parameter	Symbol	Min	Typ	Max	Unit	Note
Supply voltage	V_{SS}	0	0	0	V	
	V_{CC}	4.75	5.0	5.25	V	1
Input high voltage	V_{IH}	2.4	—	5.5	V	1
Input low voltage	V_{IL}	−1.0	—	0.8	V	1

Note: 1. All voltage referred to V_{SS} .

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DC Characteristics (Ta = 0 to 70°C, VCC = 5 V ± 5%, VSS = 0 V) (HB56A1636)

Parameter	Symbol	50 ns		60 ns		70 ns		Unit	Test conditions	Notes
		Min	Max	Min	Max	Min	Max			
Operating current	ICC1	—	3240	—	2880	—	2520	mA	tRC = min	1, 2
Standby current	ICC2	—	72	—	72	—	72	mA	TTL interface, RAS, CAS = VIH, Dout = High-Z	
		—	36	—	36	—	36	mA	CMOS interface, RAS, CAS ≥ VCC – 0.2 V, Dout = High-Z	
RAS-only refresh current	ICC3	—	3240	—	2880	—	2520	mA	tRC = min	2
Standby current	ICC5	—	180	—	180	—	180	mA	RAS = VIH, CAS = VIL, Dout = enable	1
CAS-before-RAS refresh current	ICC6	—	3240	—	2880	—	2520	mA	tRC = min	
Fast page mode current	ICC7	—	2880	—	2520	—	2160	mA	tPC = min	1, 3
Input leakage current	ILI	–10	10	–10	10	–10	10	μA	0 V ≤ Vin ≤ 5.5 V	
Output leakage current	ILO	–10	10	–10	10	–10	10	μA	0 V ≤ Vout ≤ 5.5 V, Dout = disable	
Output high voltage	VOH	2.4	VCC	2.4	VCC	2.4	VCC	V	High Iout = –5 mA	
Output low voltage	VOL	0	0.4	0	0.4	0	0.4	V	Low Iout = 4.2 mA	

- Notes: 1. ICC depends on output load condition when the device is selected, ICC max is specified at the output open condition.
2. Address can be changed once or less while RAS = VIL.
3. Address can be changed once or less while CAS = VIH.

DC Characteristics (Ta = 0 to 70°C, V_{CC} = 5 V ± 5%, V_{SS} = 0 V) (HB56A1632)

Parameter	Symbol	50 ns		60 ns		70 ns		Unit	Test conditions	Notes
		Min	Max	Min	Max	Min	Max			
Operating current	I _{CC1}	—	2880	—	2560	—	2240	mA	t _{RC} = min	1, 2
Standby current	I _{CC2}	—	64	—	64	—	64	mA	TTL interface, RAS, CAS = V _{IH} , Dout = High-Z	
		—	32	—	32	—	32	mA	CMOS interface, RAS, CAS ≥ V _{CC} − 0.2 V, Dout = High-Z	
RAS-only refresh current	I _{CC3}	—	2880	—	2560	—	2240	mA	t _{RC} = min	2
Standby current	I _{CC5}	—	160	—	160	—	160	mA	RAS = V _{IH} , CAS = V _{IL} , Dout = enable	1
CAS-before-RAS refresh current	I _{CC6}	—	2880	—	2560	—	2240	mA	t _{RC} = min	
Fast page mode current	I _{CC7}	—	2560	—	2240	—	1920	mA	t _{PC} = min	1, 3
Input leakage current	I _{LI}	−10	10	−10	10	−10	10	μA	0 V ≤ Vin ≤ 5.5 V	
Output leakage current	I _{LO}	−10	10	−10	10	−10	10	μA	0 V ≤ Vout ≤ 5.5 V, Dout = disable	
Output high voltage	V _{OH}	2.4	V _{CC}	2.4	V _{CC}	2.4	V _{CC}	V	High Iout = −5 mA	
Output low voltage	V _{OL}	0	0.4	0	0.4	0	0.4	V	Low Iout = 4.2 mA	

- Notes: 1. I_{CC} depends on output load condition when the device is selected, I_{CC} max is specified at the output open condition.
2. Address can be changed once or less while RAS = V_{IL}.
3. Address can be changed once or less while CAS = V_{IH}.

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Capacitance (Ta = 25°C, V_{CC} = 5 V ± 5%) (HB56A1636)

Parameter	Symbol	Typ	Max	Unit	Notes
Input capacitance (Address)	C _{I1}	—	195	pF	1
Input capacitance ($\overline{WE}$)	C _{I2}	—	267	pF	1
Input capacitance ($\overline{RAS}$)	C _{I3}	—	146	pF	1
Input capacitance ($\overline{CAS}$)	C _{I4}	—	83	pF	1
I/O capacitance (DQ)	C _{I/O}	—	25	pF	1, 2

Notes: 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.
2. $\overline{CAS} = V_{IH}$ to disable Dout.

Capacitance (Ta = 25°C, V_{CC} = 5 V ± 5%) (HB56A1632)

Parameter	Symbol	Typ	Max	Unit	Notes
Input capacitance (Address)	C _{I1}	—	175	pF	1
Input capacitance ($\overline{WE}$)	C _{I2}	—	239	pF	1
Input capacitance ($\overline{RAS}$)	C _{I3}	—	132	pF	1
Input capacitance ($\overline{CAS}$)	C _{I4}	—	76	pF	1
I/O capacitance (DQ)	C _{I/O}	—	25	pF	1, 2

Notes: 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.
2. $\overline{CAS} = V_{IH}$ to disable Dout.

AC Characteristics ($T_a = 0 \text{ to } 70^\circ\text{C}$, $V_{CC} = 5 \text{ V} \pm 5\%$, $V_{SS} = 0 \text{ V}$) *¹, *², *¹⁷**Test Conditions**

- Input rise and fall times: 5 ns
- Input timing reference levels: 0.8 V, 2.4 V
- Output timing reference levels: 0.4 V, 2.4 V
- Output load: 2 TTL gate + C_L (100 pF) (Including scope and jig)

Read, Write, and Refresh Cycles (Common parameters)

Parameter	Symbol	50 ns		60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max	Min	Max		
Random read or write cycle time	t_{RC}	90	—	110	—	130	—	ns	
$\overline{RAS}$ precharge time	t_{RP}	30	—	40	—	50	—	ns	
$\overline{CAS}$ precharge time	t_{CP}	7	—	10	—	10	—	ns	
$\overline{RAS}$ pulse width	t_{RAS}	50	10000	60	10000	70	10000	ns	
$\overline{CAS}$ pulse width	t_{CAS}	13	10000	15	10000	18	10000	ns	
Row address setup time	t_{ASR}	0	—	0	—	0	—	ns	
Row address hold time	t_{RAH}	7	—	10	—	10	—	ns	
Column address setup time	t_{ASC}	0	—	0	—	0	—	ns	
Column address hold time	t_{CAH}	7	—	10	—	15	—	ns	
$\overline{RAS}$ to $\overline{CAS}$ delay time	t_{RCD}	17	37	20	45	20	52	ns	3
$\overline{RAS}$ to column address delay time	t_{RAD}	12	25	15	30	15	35	ns	4
$\overline{RAS}$ hold time	t_{RSH}	13	—	15	—	18	—	ns	
$\overline{CAS}$ hold time	t_{CSH}	50	—	60	—	70	—	ns	
$\overline{CAS}$ to $\overline{RAS}$ precharge time	t_{CRP}	5	—	5	—	5	—	ns	
$\overline{CAS}$ delay time from D_{in}	t_{DZC}	0	—	0	—	0	—	ns	
Transition time (rise and fall)	t_T	3	50	3	50	3	50	ns	5
Refresh period (4,096 cycles)	t_{REF}	—	64	—	64	—	64	ms	

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Read Cycle

Parameter	Symbol	50 ns		60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max	Min	Max		
Access time from $\overline{\text{RAS}}$	t_{RAC}	—	50	—	60	—	70	ns	6, 7
Access time from $\overline{\text{CAS}}$	t_{CAC}	—	13	—	15	—	18	ns	7, 8, 15
Access time from address	t_{AA}	—	25	—	30	—	35	ns	7, 9, 15
Read command setup time	t_{RCS}	0	—	0	—	0	—	ns	
Read command hold time to $\overline{\text{CAS}}$	t_{RCH}	0	—	0	—	0	—	ns	10
Read command hold time to $\overline{\text{RAS}}$	t_{RRH}	5	—	5	—	5	—	ns	10
Column address to $\overline{\text{RAS}}$ lead time	t_{RAL}	25	—	30	—	35	—	ns	
Column address to $\overline{\text{CAS}}$ lead time	t_{CAL}	25	—	30	—	35	—	ns	
$\overline{\text{CAS}}$ to output in low-Z	t_{CLZ}	0	—	0	—	0	—	ns	
Output data hold time	t_{OH}	3	—	3	—	3	—	ns	
Output buffer turn-off time	t_{OFF}	—	13	—	15	—	15	ns	11
$\overline{\text{CAS}}$ to Din delay time	t_{CDD}	13	—	15	—	18	—	ns	

Write Cycle

Parameter	Symbol	50 ns		60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max	Min	Max		
Write command setup time	t_{WCS}	0	—	0	—	0	—	ns	12
Write command hold time	t_{WCH}	7	—	10	—	15	—	ns	
Write command pulse width	t_{WCP}	7	—	10	—	10	—	ns	
Data-in setup time	t_{DS}	0	—	0	—	0	—	ns	13
Data-in hold time	t_{DH}	7	—	10	—	15	—	ns	13

Refresh Cycle

Parameter	Symbol	50 ns		60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max	Min	Max		
$\overline{\text{CAS}}$ setup time (CBR refresh cycle)	t_{CSR}	5	—	5	—	5	—	ns	
$\overline{\text{CAS}}$ hold time (CBR refresh cycle)	t_{CHR}	7	—	10	—	10	—	ns	
$\overline{\text{WE}}$ setup time (CBR refresh cycle)	t_{WRP}	0	—	0	—	0	—	ns	
$\overline{\text{WE}}$ hold time (CBR refresh cycle)	t_{WRH}	7	—	10	—	10	—	ns	
$\overline{\text{RAS}}$ precharge to $\overline{\text{CAS}}$ hold time	t_{RPC}	5	—	5	—	5	—	ns	

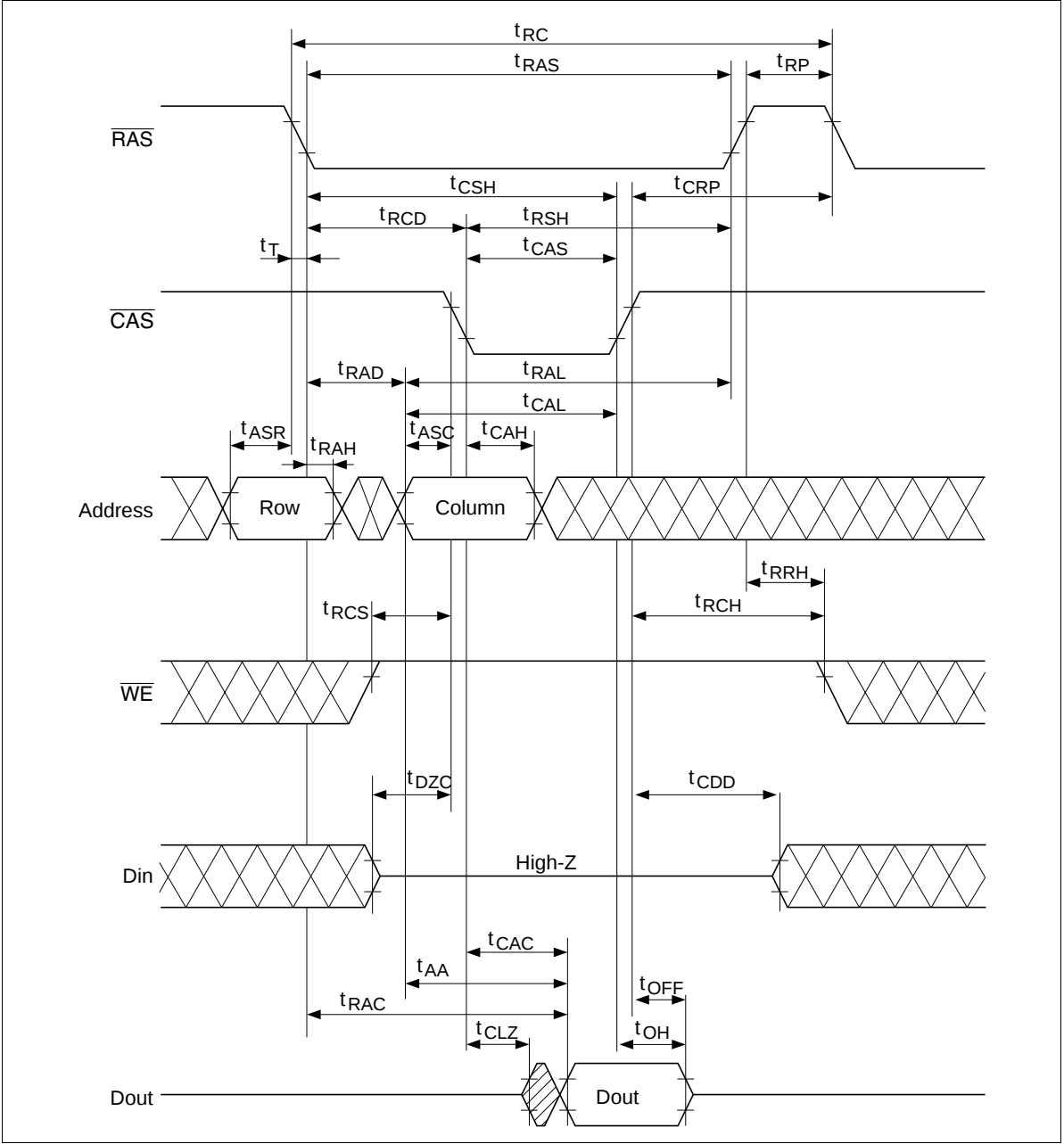
Fast Page Mode Cycle

Parameter	Symbol	50 ns		60 ns		70 ns		Unit	Notes
		Min	Max	Min	Max	Min	Max		
Fast page mode cycle time	t_{PC}	35	—	40	—	45	—	ns	
Fast page mode $\overline{\text{RAS}}$ pulse width	t_{RASP}	—	100000	—	100000	—	100000	ns	14
Access time from $\overline{\text{CAS}}$ precharge	t_{CPA}	—	30	—	35	—	40	ns	7, 15
$\overline{\text{RAS}}$ hold time from $\overline{\text{CAS}}$ precharge	t_{CPRH}	30	—	35	—	40	—	ns	

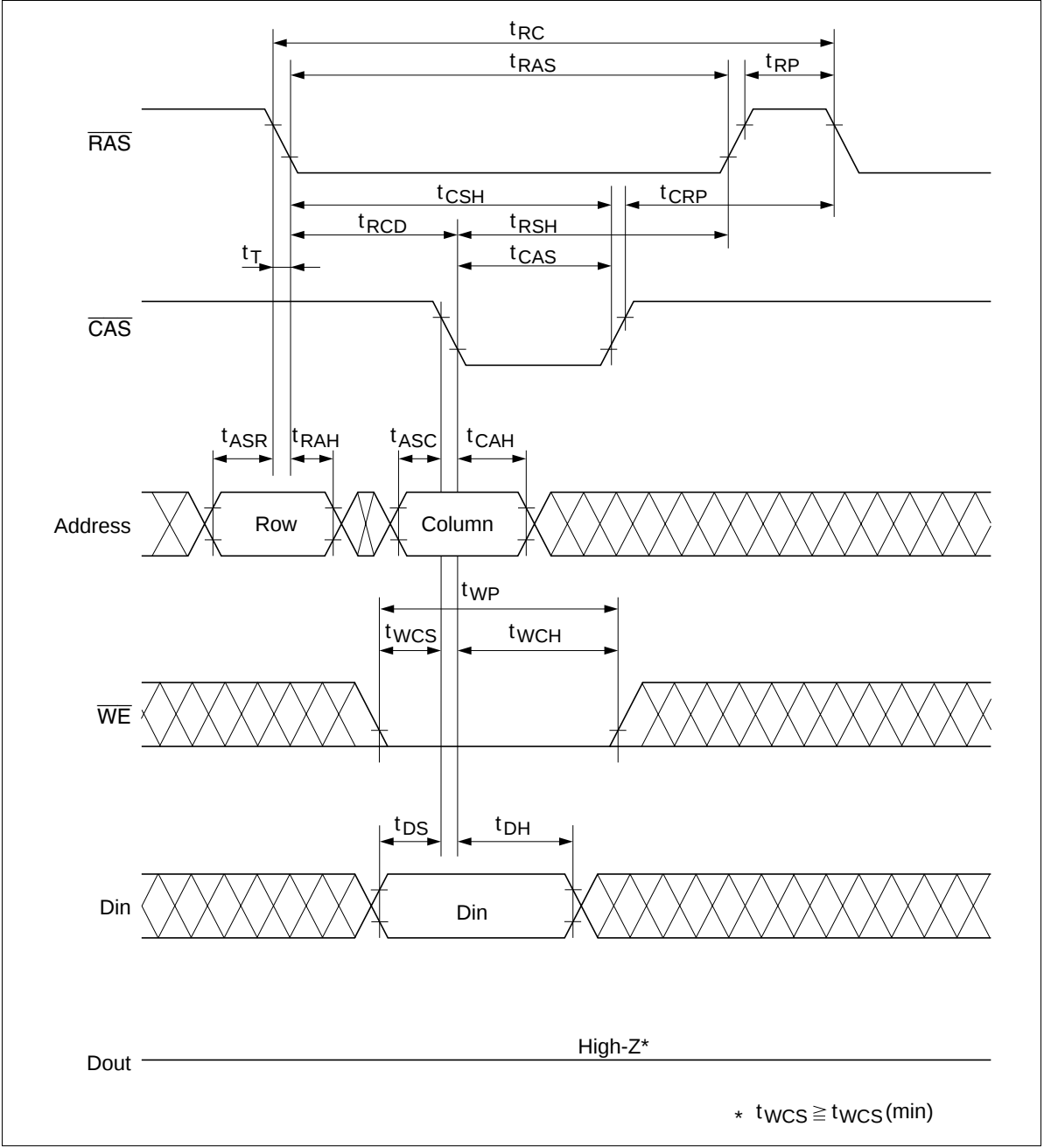
- Notes:
1. AC measurements assume $t_r = 5$ ns.
 2. An initial pause of 200 μ s is required after power up followed by a minimum of eight initialization cycles (any combination of cycles containing RAS-only refresh cycle or CAS-before-RAS refresh). If the internal refresh counter is used, a minimum of eight $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh cycles are required.
 3. Operation with the t_{RCD} (max) limit insures that t_{RAC} (max) can be met, t_{RCD} (max) is specified as a reference point only; if t_{RCD} is greater than the specified t_{RCD} (max) limit, then access time is controlled exclusively by t_{CAC} .
 4. Operation with the t_{RAD} (max) limit insures that t_{RAC} (max) can be met, t_{RAD} (max) is specified as a reference point only; if t_{RAD} is greater than the specified t_{RAD} (max) limit, then access time is controlled exclusively by t_{AA} .
 5. V_{IH} (min) and V_{IL} (max) are reference levels for measuring timing of input signals. Also, transition times are measured between V_{IH} (min) and V_{IL} (max).
 6. Assumes that $t_{\text{RCD}} \leq t_{\text{RCD}}$ (max) and $t_{\text{RAD}} \leq t_{\text{RAD}}$ (max). If t_{RCD} or t_{RAD} is greater than the maximum recommended value shown in this table, t_{RAC} exceeds the value shown.
 7. Measured with a load circuit equivalent to 2 TTL loads and 100 pF.
 8. Assumes that $t_{\text{RCD}} \geq t_{\text{RCD}}$ (max) and $t_{\text{RCD}} + t_{\text{CAC}}$ (max) $\geq t_{\text{RAD}} + t_{\text{AA}}$ (max).
 9. Assumes that $t_{\text{RAD}} \geq t_{\text{RAD}}$ (max) and $t_{\text{RCD}} + t_{\text{CAC}}$ (max) $\leq t_{\text{RAD}} + t_{\text{AA}}$ (max).
 10. Either t_{RCH} or t_{RRH} must be satisfied for a read cycles.
 11. t_{OFF} (max) defines the time at which the outputs achieve the open circuit condition and are not referred to output voltage levels.
 12. Early write cycle only ($t_{\text{WCS}} \geq t_{\text{WCS}}$ (min)).
 13. These parameters are referred to $\overline{\text{CAS}}$ leading edge in early write cycles.
 14. t_{RASP} defines $\overline{\text{RAS}}$ pulse width in Fast page mode cycles.
 15. Access time is determined by the longest among t_{AA} , t_{CAC} and t_{CPA} .
 16. When output buffers are enabled once, sustain the low impedance state until valid data is obtained. When output buffer is turned on and off within a very short time, generally it causes large $V_{\text{CC}} / V_{\text{SS}}$ line noise, which causes to degrade V_{IH} min./ V_{IL} max level.
 17. All the V_{CC} and V_{SS} pins shall be supplied with the same voltages.
 18. XXX: H or L (H: V_{IH} (min) $\leq V_{\text{IN}} \leq V_{\text{IH}}$ (max), L: V_{IL} (min) $\leq V_{\text{IN}} \leq V_{\text{IL}}$ (max))
/////: Invalid Dout
When the address, clock and input pins are not described on timing waveforms, their pins must be applied V_{IH} or V_{IL} .

Timing Waveforms*18

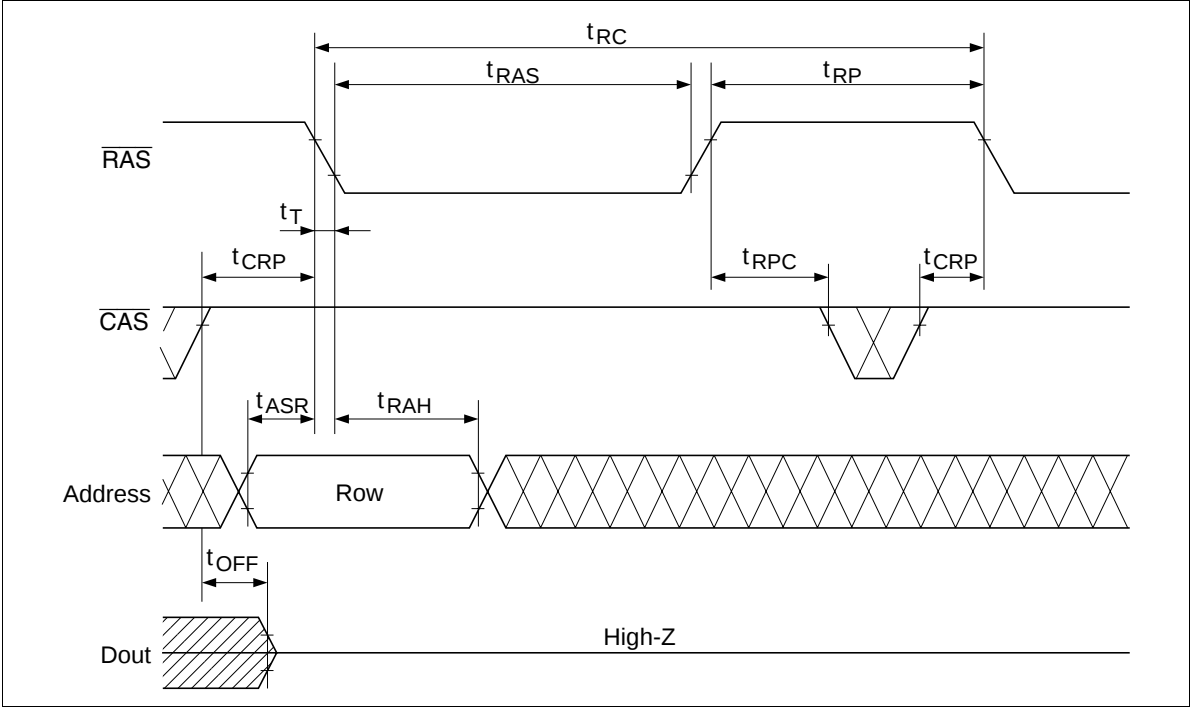
Read Cycle



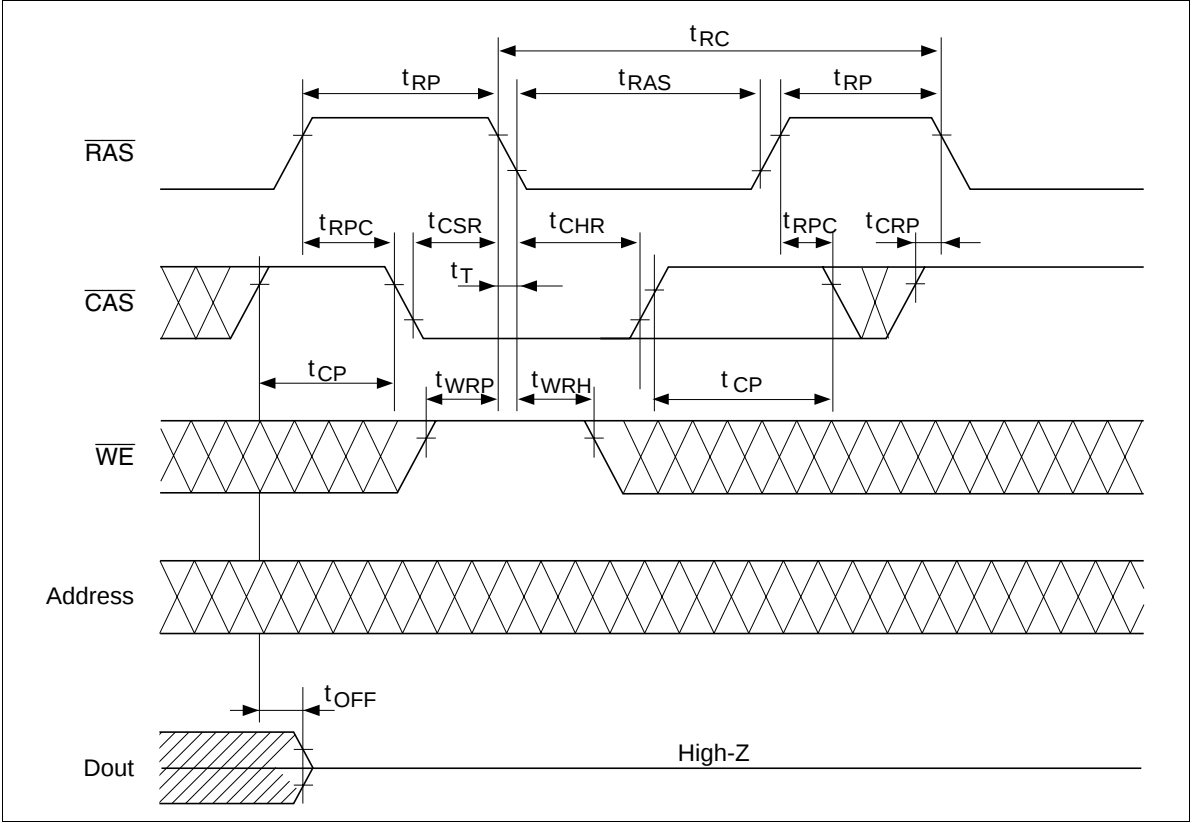
Early Write Cycle



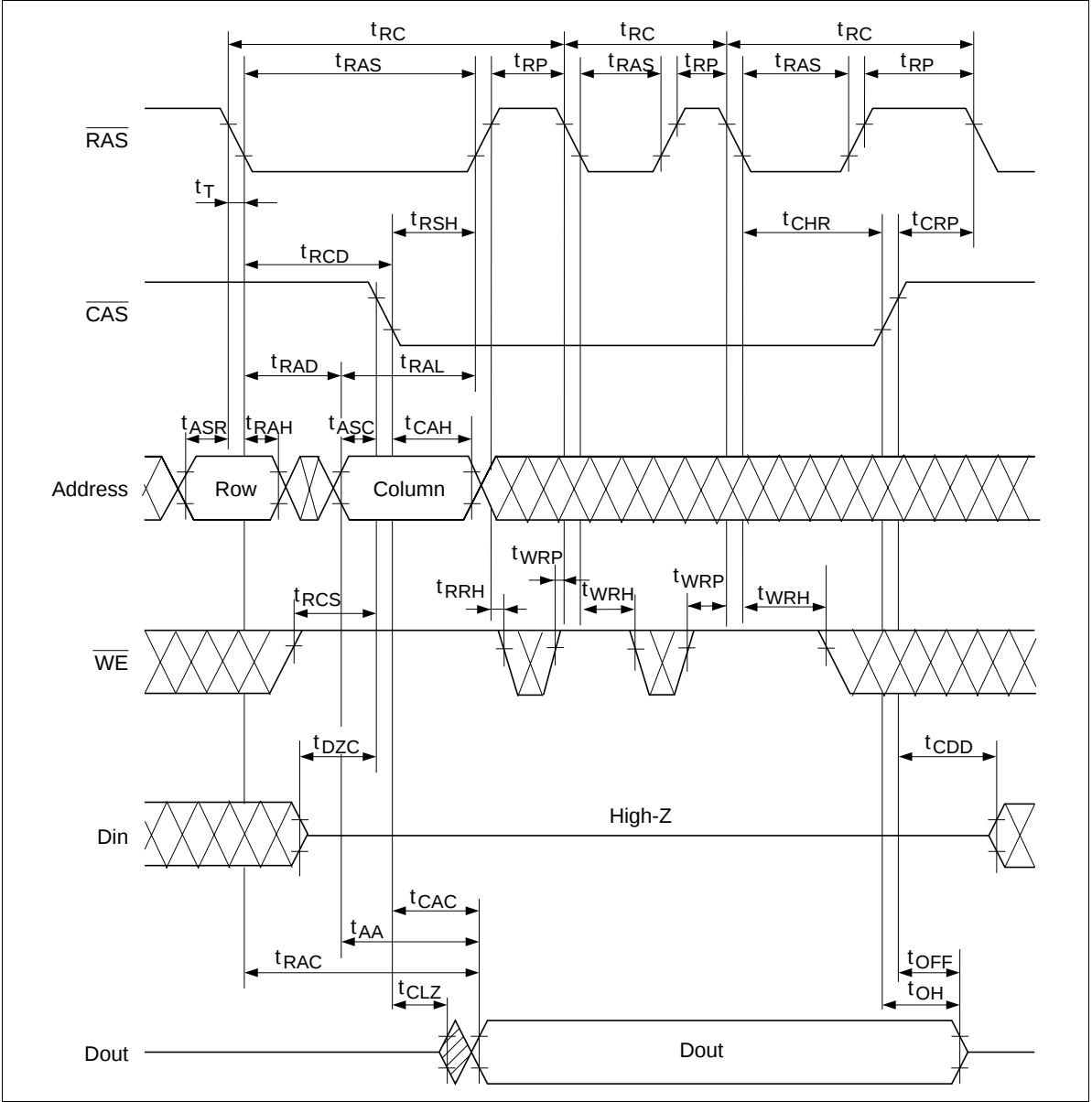
RAS-Only Refresh Cycle

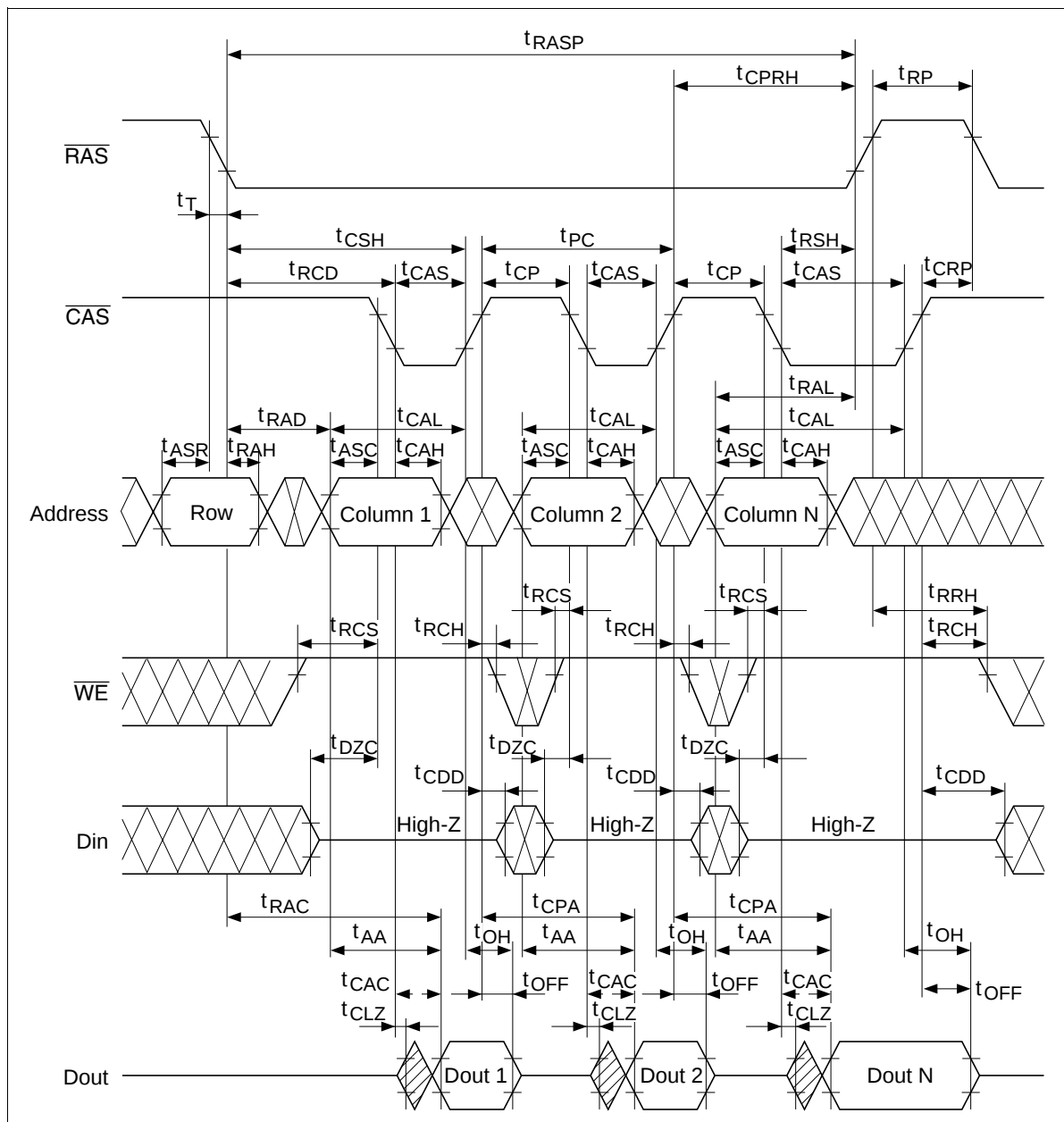


CAS-Before-RAS Refresh Cycle

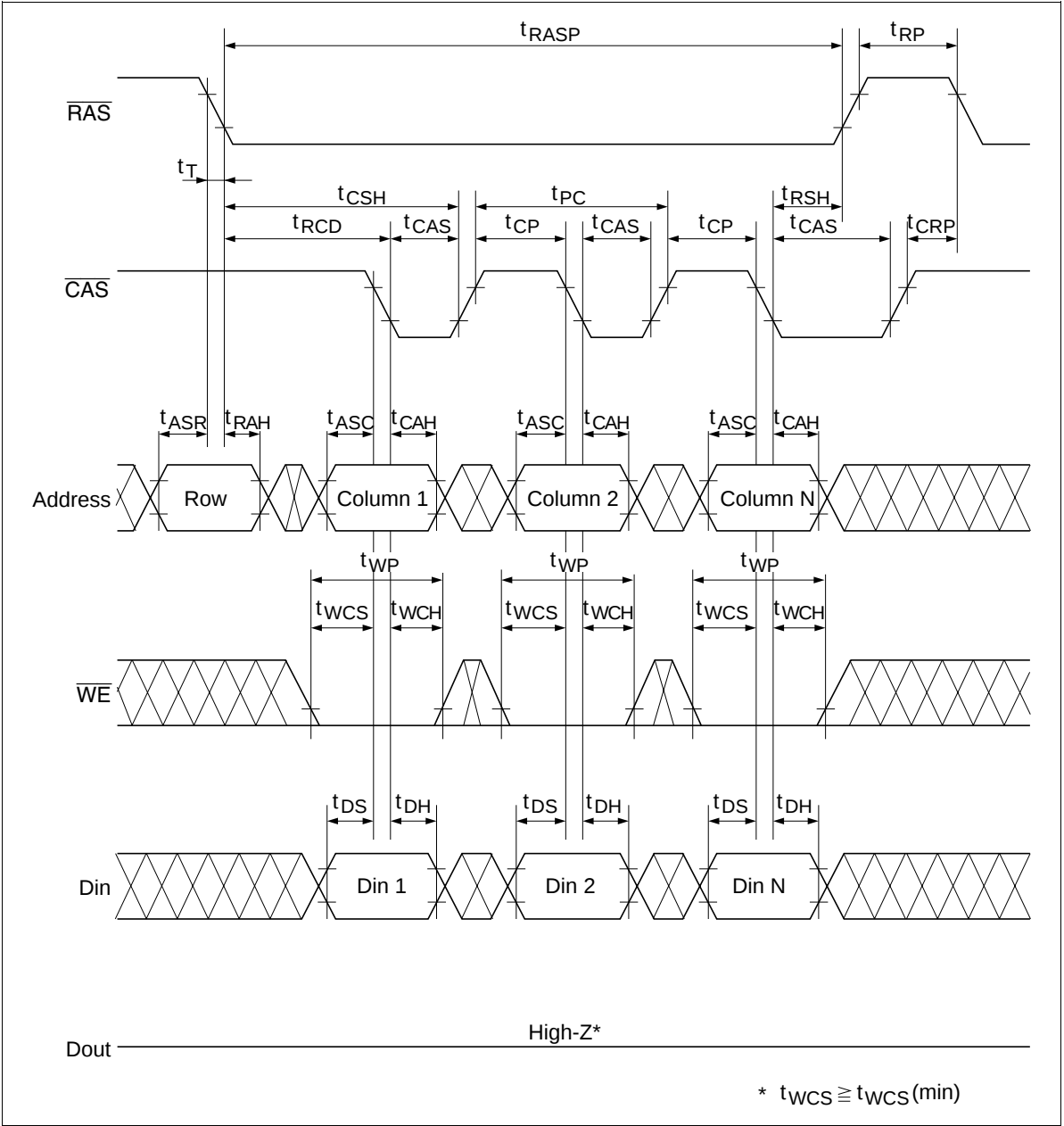


Hidden Refresh Cycle

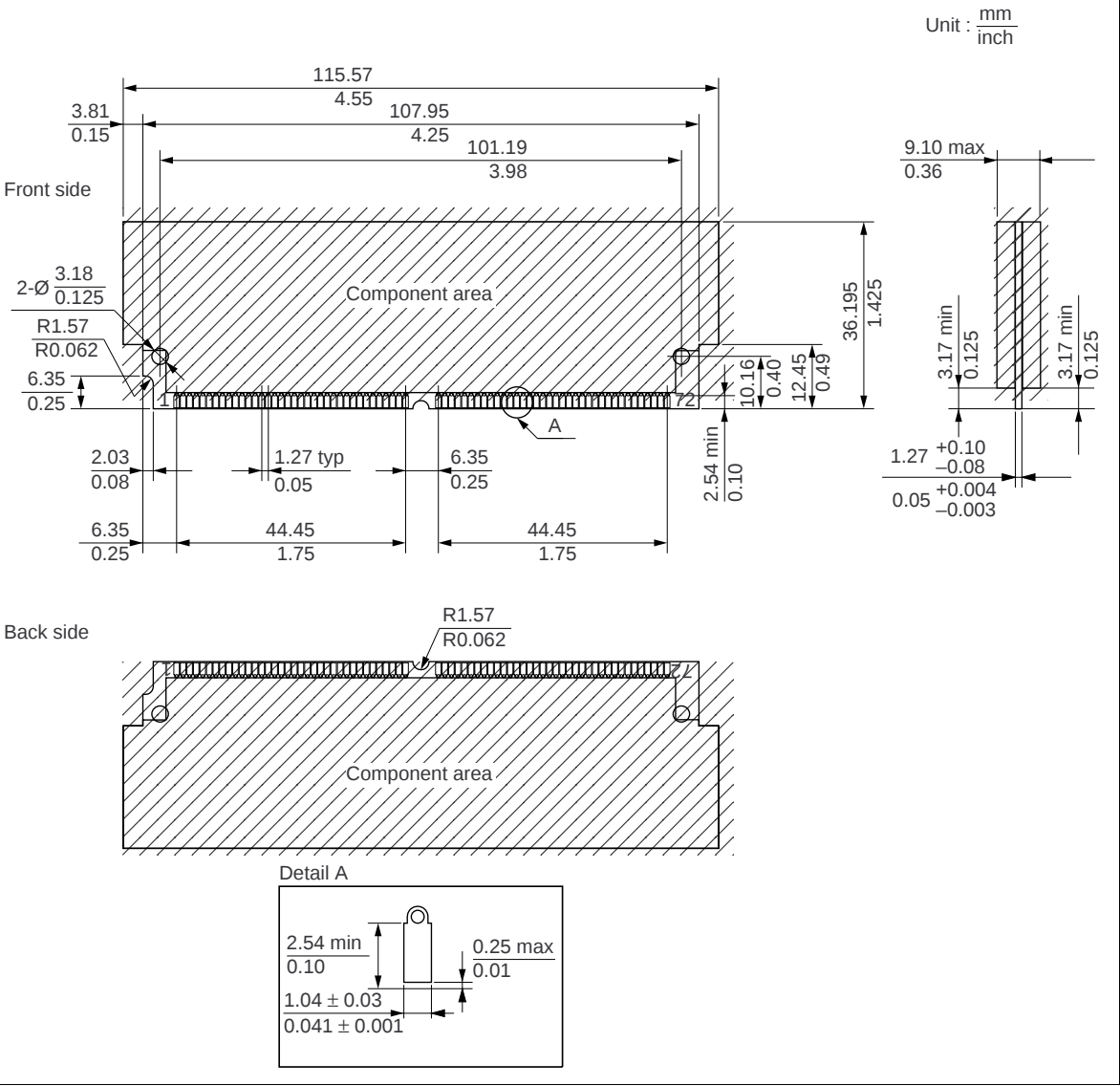




Fast Page Mode Early Write Cycle



Physical Outline



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HB56A1636 Series, HB56A1632 Series

Revision Record

Rev.	Date	Contents of Modification	Drawn by	Approved by
1.0	Feb. 27, 1997	Initial issue		
