## Document Title

## 128Kx18-Bit Synchronous Pipelined Burst SRAM

## Revision History

| Rev. No. | History | Draft Date | Remark |
| ---: | :--- | :--- | :--- |
| 0.0 | Initial draft | Sep. 16.1998 | Preliminary |
| 1.0 | Final spec release. | Nov. 16.1998 | Final |
| 2.0 | Add VDDQ Supply voltage( 2.5 V$)$ | Dec. 02.1998 | Final |

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## 128Kx18-Bit Synchronous Pipelined Burst SRAM

## FEATURES

- Synchronous Operation.
- 2 Stage Pipelined operation with 4 Burst.
- On-Chip Address Counter.
- Self-Timed Write Cycle.
- On-Chip Address and Control Registers.
- VdD $=3.3 \mathrm{~V}+0.3 \mathrm{~V} /-0.165 \mathrm{~V}$ Power Supply.
- Vdda Supply Voltage 3.3V+0.3V/-0.165V for 3.3V I/O or $2.5 \mathrm{~V}+0.4 \mathrm{~V} /-0.125 \mathrm{~V}$ for $2.5 \mathrm{~V} \mathrm{I} / \mathrm{O}$.
- 5V Tolerant Inputs Except I/O Pins.
- Byte Writable Function.
- Global Write Enable Controls a full bus-width write.
- Power Down State via ZZ Signal.
- $\overline{\mathrm{LBO}}$ Pin allows a choice of either a interleaved burst or a linear burst.
- Three Chip Enables for simple depth expansion with No Data Contention ; 2 cycle Enable, 1 cycle Disable.
- Asynchronous Output Enable Control.
- $\overline{\mathrm{ADSP}}, \overline{\mathrm{ADSC}}, \overline{\mathrm{ADV}}$ Burst Control Pins.
- TTL-Level Three-State Output.
- 100-TQFP-1420A


## FAST ACCESS TIMES

| PARAMETER | Symbol | $\mathbf{- 2 2}$ | $\mathbf{- 2 0}$ | $\mathbf{- 1 8}$ | $\mathbf{- 1 6}$ | $\mathbf{- 1 5}$ | $\mathbf{- 1 4}$ | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Cycle Time | tcyc | 4.4 | 5.0 | 5.4 | 6.0 | 6.7 | 7.2 | ns |
| Clock Access Time | tcD | 3.1 | 3.1 | 3.1 | 3.5 | 3.8 | 4.0 | ns |
| Output Enable Access Time | toe | 3.1 | 3.1 | 3.1 | 3.5 | 3.8 | 4.0 | ns |

## GENERAL DESCRIPTION

The K7A201800A is a $2,359,296$-bit Synchronous Static Random Access Memory designed for high performance second level cache of Pentium and Power PC based System.
It is organized as 128 K words of 18 bits and integrates address and control registers, a 2-bit burst address counter and added some new functions for high performance cache RAM applications; $\overline{G W}, \overline{B W}, \overline{L B O}, \mathrm{ZZ}$. Write cycles are internally self-timed and synchronous.
Full bus-width write is done by $\overline{\mathrm{GW}}$, and each byte write is performed by the combination of $\overline{\mathrm{WE}}$ and $\overline{\mathrm{BW}}$ when $\overline{\mathrm{GW}}$ is high. And with $\overline{\mathrm{CS}}_{1}$ high, $\overline{\mathrm{ADSP}}$ is blocked to control signals.
Burst cycle can be initiated with either the address status processor ( $\overline{\mathrm{ADSP}})$ or address status cache controller( $\overline{\mathrm{ADSC}})$ inputs. Subsequent burst addresses are generated internally in the system's burst sequence and are controlled by the burst address advance( $\overline{\mathrm{ADV}}$ ) input.
$\overline{\mathrm{LBO}}$ pin is DC operated and determines burst sequence(linear or interleaved).
ZZ pin controls Power Down State and reduces Stand-by current regardless of CLK.
The K7A201800A is fabricated using SAMSUNG's high performance CMOS technology and is available in a 100pin TQFP package. Multiple power and ground pins are utilized to minimize ground bounce.

## LOGIC BLOCK DIAGRAM



## PIN CONFIGURATION(TOP VIEW)



PIN NAME

| SYMBOL | PIN NAME | TQFP PIN No. | SYMBOL | PIN NAME | TQFP PIN No. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A0-A16 | Address Inputs | 32,33,34,35,36,37, | Vdd | Power Supply(+3.3V) | 15,41,65,91 |
|  |  | 44,45,46,47,48,49, | Vss | Ground | 17,40,67,90 |
|  |  | 80,81,82,99,100 | N.C. | No Connect | 1,2,3,6,7,14,16,25,28 |
| $\overline{\text { ADV }}$ | Burst Address Advance | 83 |  |  | 29,30,38,39,42,43,50, |
| $\overline{\text { ADSP }}$ | Address Status Processor | 84 |  |  | 51,52,53,56,57,66,75, |
| $\overline{\text { ADSC }}$ | Address Status Controller | 85 |  |  | 78,79,95,96 |
| CLK | Clock | 89 | DQa0~a7 | Data Inputs/Outputs | 58,59,62,63,68,69,72,7 |
| $\mathrm{CS}_{1}$ | Chip Select | 98 | DQbo~b7 |  | 38,9,12,13,18,19,22,23 |
| CS2 | Chip Select | 97 | DQPa, Pb |  | 74,24 |
| $\overline{\mathrm{CS}} 2$ | Chip Select | 92 | Vdda | Output Power Supply | 4,11,20,27,54,61,70,77 |
| WEx | Byte Write Inputs | 93,94 |  | (2.5V or 3.3V) |  |
| OE | Output Enable | 86 | VssQ | Output Ground | 5,10,21,26,55,60,71,76 |
| GW | Global Write Enable | 88 |  |  |  |
| BW | Byte Write Enable | 87 |  |  |  |
| ZZ | Power Down Input | 64 |  |  |  |
| $\overline{\text { LBO }}$ | Burst Mode Control | 31 |  |  |  |

## FUNCTION DESCRIPTION

The K7A201800A is a synchronous SRAM designed to support the burst address accessing sequence of the Pentium and Power PC based microprocessor. All inputs(with the exception of $\overline{\mathrm{OE}}, \overline{\mathrm{LBO}}$ and ZZ ) are sampled on rising clock edges. The start and duration of the burst access is controlled by $\overline{\text { ADSP }}, \overline{\mathrm{ADSC}}, \overline{\mathrm{ADV}}$ and Chip Select pins.
The accesses are enabled with the chip select signals and output enabled signals. Wait states are inserted into the access with $\overline{\text { ADV }}$.
When ZZ is pulled high, the SRAM will enter a Power Down State. At this time, internal state of the SRAM is preserved. When ZZ returns to low, the SRAM normally operates after 2 cycles of wake up time. $Z Z$ pin is pulled down internally.

Read cycles are initiated with $\overline{\operatorname{ADSP}}$ (regardless of $\overline{\mathrm{WEx}}$ and $\overline{\mathrm{ADSC}}$ ) using the new external address clocked into the on-chip address register whenever $\overline{\mathrm{ADSP}}$ is sampled low, the chip selects are sampled active, and the output buffer is enabled with $\overline{\mathrm{OE}}$. In read operation the data of cell array accessed by the current address, registered in the Data-out registers by the positive edge of CLK, are carried to the Data-out buffer by the next positive edge of CLK. The data, registered in the Data-out buffer, are projected to the output pins. $\overline{\mathrm{ADV}}$ is ignored on the clock edge that samples $\overline{\mathrm{ADSP}}$ asserted, but is sampled on the subsequent clock edges. The address increases internally for the next access of the burst when WEx are sampled High and ADV is sampled Low. And ADSP is blocked to control signals by disabling $\overline{\mathrm{CS}} 1$.

All byte write is done by $\overline{\mathrm{GW}}$ (regardless of $\overline{\mathrm{BW}}$ and $\overline{\mathrm{WE}}$.), and each byte write is performed by the combination of $\overline{\mathrm{BW}}$ and $\overline{\mathrm{WEx}}$ when $\overline{\mathrm{GW}}$ is High.
Write cycles are performed by disabling the output buffers with $\overline{\mathrm{OE}}$ and asserting $\overline{\mathrm{WE} x}$. WEx are ignored on the clock edge that samples $\overline{\text { ADSP }}$ Low, but are sampled on the subsequent clock edges. The output buffers are disabled when $\overline{W E x}$ are sampled Low(regaedless of OE). Data is clocked into the data input register when WEx sampled Low. The address increases internally to the next address of burst, if both $\overline{\mathrm{WEx}}$ and $\overline{\mathrm{ADV}}$ are sampled Low. Individual byte write cycles are performed by any one or more byte write enable signals( $\overline{W E a}$ or $\overline{\mathrm{WEb}}$ ) sampled low. The $\overline{\text { WEa controls DQao } \sim}$ DQa7 and DQPa, $\overline{\text { WEb controls DQbo ~ DQb7 and DQPb. }}$ Read or write cycle may also be initiated with $\overline{\text { ADSC }}$, instead of $\overline{\text { ADSP }}$. The differences between cycles initiated with $\overline{\text { ADSC }}$ and $\overline{\mathrm{ADSP}}$ as are follows;
$\overline{\mathrm{ADSP}}$ must be sampled high when $\overline{\text { ADSC }}$ is sampled low to initiate a cycle with $\overline{\mathrm{ADSC}}$. $\overline{\mathrm{WEx}}$ are sampled on the same clock edge that sampled $\overline{\mathrm{ADSC}}$ low(and $\overline{\mathrm{ADSP}}$ high).

Addresses are generated for the burst access as shown below, The starting point of the burst sequence is provided by the external address. The burst address counter wraps around to its initial state upon completion. The burst sequence is determined by the state of the $\overline{\mathrm{LBO}}$ pin. When this pin is Low, linear burst sequence is selected. And when this pin is High, Interleaved burst sequence is selected.

BURST SEQUENCE TABLE
(Interleaved Burst)

| $\overline{\text { LBO }}$ PIN | HIGH | Case 1 |  | Case 2 |  | Case 3 |  | Case 4 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | A1 | A0 | A1 | A0 | A1 | A0 | A1 | A0 |
| First Address |  | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 1 |
|  |  | 0 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| Fourth Address |  | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 1 |
|  |  | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 |

(Linear Burst)

| $\overline{\text { LBO PIN }}$ | LOW | Case 1 |  | Case 2 |  | Case 3 |  | Case 4 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | A1 | A0 | A1 | A0 | A1 | A0 | A1 | A0 |
| First Address |  | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 1 |
| Fourth Address |  | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 0 |
|  |  | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 1 |
|  |  | 1 | 1 | 0 | 0 | 0 | 1 | 1 | 0 |

Note : 1. $\overline{\mathrm{LBO}}$ pin must be tied to High or Low, and Floating State must not be allowed.

## TRUTH TABLES

SYNCHRONOUS TRUTH TABLE

| $\overline{\mathbf{C S}}_{1}$ | $\mathbf{C S}_{2}$ | $\overline{\mathbf{C S}}$ |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{2}$ | $\overline{\text { ADSP }}$ | $\overline{\text { ADSC }}$ | $\overline{\text { ADV }}$ | $\overline{\text { WRITE }}$ | $\mathbf{C L K}$ | ADDRESS ACCESSED | OPERATION |  |  |
| H | X | X | X | L | X | X | $\uparrow$ | N/A | Not Selected |
| L | L | X | L | X | X | X | $\uparrow$ | N/A | Not Selected |
| L | X | H | L | X | X | X | $\uparrow$ | N/A | Not Selected |
| L | L | X | X | L | X | X | $\uparrow$ | N/A | Not Selected |
| L | X | H | X | L | X | X | $\uparrow$ | N/A | Begin Burst Read Cycle |
| L | H | L | L | X | X | X | $\uparrow$ | External Address | Begin Burst Write Cycle |
| L | H | L | H | L | X | L | $\uparrow$ | External Address | Begin Burst Read Cycle |
| L | H | L | H | L | X | H | $\uparrow$ | External Address | Continue Burst Read Cycle |
| X | X | X | H | H | L | H | $\uparrow$ | Next Address | Continue Burst Read Cycle |
| H | X | X | X | H | L | H | $\uparrow$ | Next Address | Continue Burst Write Cycle |
| X | X | X | H | H | L | L | $\uparrow$ | Next Address | Continue Burst Write Cycle |
| H | X | X | X | H | L | L | $\uparrow$ | Next Address | Suspend Burst Read Cycle |
| X | X | X | H | H | H | H | $\uparrow$ | Current Address | Suspend Burst Read Cycle |
| H | X | X | X | H | H | H | $\uparrow$ | Current Address | Suspend Burst Write Cycle |
| X | X | X | H | H | H | L | $\uparrow$ | Current Address | Suspend Burst Write Cycle |
| H | X | X | X | H | H | L | $\uparrow$ | Current Address |  |

Notes: 1. X means "Don't Care".
2. The rising edge of clock is symbolized by $\uparrow$.
3. $\overline{\text { WRITE }}=\mathrm{L}$ means Write operation in WRITE TRUTH TABLE.
$\overline{\text { WRITE }}=\mathrm{H}$ means Read operation in WRITE TRUTH TABLE.
4. Operation finally depends on status of asynchronous input pins(ZZ and $\overline{\mathrm{OE}})$.

WRITE TRUTH TABLE

| $\overline{\text { GW }}$ | $\overline{\text { BW }}$ | $\overline{\text { WEa }}$ | $\overline{\text { WEb }}$ | OPERATION |
| :---: | :---: | :---: | :---: | :---: |
| $H$ | $H$ | $X$ | $X$ | READ |
| $H$ | L | $H$ | $H$ | READ |
| $H$ | L | L | H | WRITE BYTE a |
| $H$ | L | $H$ | L | WRITE BYTE b |
| $H$ | L | L | L | WRITE ALL BYTEs |
| L | $X$ | $X$ | $X$ | WRITE ALL BYTEs |

Notes: 1. X means "Don't Care".
2. All inputs in this table must meet setup and hold time around the rising edge of CLK ( $\uparrow$ ).

## ASYNCHRONOUS TRUTH TABLE

(See Notes 1 and 2):

| OPERATION | $\mathbf{Z Z}$ | $\overline{\mathbf{O E}}$ | I/O STATUS |
| :---: | :---: | :---: | :---: |
| Sleep Mode | H | X | High-Z |
| Read | L | L | DQ |
|  | L | H | High-Z |
| Write | L | X | Din, High-Z |
| Deselected | L | X | High-Z |

## Notes

1. X means "Don’t Care"
2. ZZ pin is pulled down internally
3. For write cycles that following read cycles, the output buffers must be disabled with OE, otherwise data bus contention will occur
4. Sleep Mode means power down state of which stand-by current does not depend on cycle time.
5. Deselected means power down state of which stand-by current depends on cycle time.

PASS-THROUGH TRUTH TABLE

| PREVIOUS CYCLE |  | PRESENT CYCLE |  |  |  | NEXT CYCLE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| OPERATION | WRITE | OPERATION | $\overline{\mathrm{CS}} 1$ | WRITE | $\overline{\mathrm{OE}}$ |  |
| Write Cycle, All bytes <br> Address=An-1, Data=Dn-1 | All L | Initiate Read Cycle <br> Address=An <br> Data=Qn-1 for all bytes | L | H | L | Read Cycle Data=Qn |
| Write Cycle, All bytes <br> Address=An-1, Data=Dn-1 | All L | No new cycle Data=Qn-1 for all bytes | H | H | L | No carryover from previous cycle |
| Write Cycle, All bytes <br> Address=An-1, Data=Dn-1 | All L | No new cycle Data=High-Z | H | H | H | No carryover from previous cycle |
| Write Cycle, One byte <br> Address=An-1, Data=Dn-1 | One L | Initiate Read Cycle <br> Address=An <br> Data=Qn-1 for one byte | L | H | L | Read Cycle Data=Qn |
| Write Cycle, One byte Address=An-1, Data=Dn-1 | One L | No new cycle Data=Qn-1 for one byte | H | H | L | No carryover from previous cycle |

Note : 1. This operation makes written data immediately available at output during a read cycle preceded by a write cycle.

## ABSOLUTE MAXIMUM RATINGS*

| PARAMETER | SYMBOL | RATING | UNIT |
| :--- | :---: | :---: | :---: |
| Voltage on VDD Supply Relative to Vss | VDD | -0.3 to 4.6 |  |
| Voltage on VddQ Supply Relative to Vss | VDDQ | VdD |  |
| Voltage on Input Pin Relative to Vss | Vin | -0.3 to 6.0 | V |
| Voltage on I/O Pin Relative to Vss | VIO | -0.3 to VDDQ+0.5 | V |
| Power Dissipation | PD | 1.2 | W |
| Storage Temperature | TsTG | -65 to 150 | ${ }^{\circ} \mathrm{C}$ |
| Operating Temperature | ToPR | 0 to 70 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature Range Under Bias | TBIAS | -10 to 85 | ${ }^{\circ} \mathrm{C}$ |

*Note : Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

OPERATING CONDITIONS at $3.3 \mathrm{~V} \mathrm{I} / \mathrm{O}\left(0^{\circ} \mathrm{C} \leq \mathrm{TA} \leq 70^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | MIN | Typ. | MAX | UNIT |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Supply Voltage | VDD | 3.135 | 3.3 | 3.6 | V |
|  | VDDQ | 3.135 | 3.3 | 3.6 | V |
| Ground | Vss | 0 | 0 | 0 | V |

OPERATING CONDITIONS at $2.5 \mathrm{~V} \operatorname{I} / \mathrm{O}\left(0^{\circ} \mathrm{C} \leq \mathrm{TA} \leq 70^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | MIN | Typ. | MAX | UNIT |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Supply Voltage | VDD | 3.135 | 3.3 | 3.6 | V |
|  | VDDQ | 2.375 | 2.5 | 2.9 | V |
| Ground | Vss | 0 | 0 | 0 | V |

CAPACITANCE* $\left(\mathrm{TA}=25^{\circ} \mathrm{C}, \mathrm{f}=1 \mathrm{MHz}\right)$

| PARAMETER | SYMBOL | TEST CONDITION | MIN | MAX | UNIT |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Input Capacitance | CIN | VIN=0V | - | 5 | pF |
| Output Capacitance | CouT | VoUT=0V | - | 7 | pF |

[^0]DC ELECTRICAL CHARACTERISTICS $\left(\mathrm{TA}_{\mathrm{A}}=0\right.$ to $70^{\circ} \mathrm{C}, \mathrm{VDD}=3.3 \mathrm{~V}+0.3 \mathrm{~V} /-0.165 \mathrm{~V}$ )

| PARAMETER | SYMBOL | TEST CONDITIONS |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input Leakage Current(except ZZ) | IIL | VdD=Max ; VIN=Vss to Vdd |  | -2 | +2 | $\mu \mathrm{A}$ |
| Output Leakage Current | IoL | Output Disabled, Vout=Vss to VDDQ |  | -2 | +2 | $\mu \mathrm{A}$ |
| Operating Current | Icc | Device Selected, Iout=0mA, ZZ $\leq$ VIL, All Inputs=VIL or VIH Cycle Time $\geq$ tcyc min | -22 | - | 440 | mA |
|  |  |  | -20 | - | 400 |  |
|  |  |  | -18 | - | 380 |  |
|  |  |  | -16 | - | 360 |  |
|  |  |  | -15 | - | 320 |  |
|  |  |  | -14 | - | 280 |  |
| Standby Current | Isb | Device deselected, lout $=0 \mathrm{~mA}$, <br> $\mathrm{ZZ} \leq \mathrm{VIL}, \mathrm{f}=\mathrm{Max}$, <br> All Inputs $\leq 0.2 \mathrm{~V}$ or $\geq$ VDD-0.2V | -22 | - | 110 | mA |
|  |  |  | -20 | - | 100 |  |
|  |  |  | -18 | - | 100 |  |
|  |  |  | -16 | - | 90 |  |
|  |  |  | -15 | - | 80 |  |
|  |  |  | -14 | - | 70 |  |
|  | ISB1 | Device deselected, lout $=0 \mathrm{~mA}, \mathrm{ZZ} \leq 0.2 \mathrm{~V}$, $\mathrm{f}=0$, All Inputs=fixed (VDd-0.2V or 0.2V) |  | - | 20 | mA |
|  | ISB2 | Device deselected, lout=OmA, ZZ $\geq$ VDD-0.2V, $f=$ Max, All Inputs $\leq$ VIL $_{\text {IL }}$ or $\geq$ VIH |  | - | 20 | mA |
| Output Low Voltage(3.3V I/O) | Vol | $\mathrm{IOL}=8.0 \mathrm{~mA}$ |  | - | 0.4 | V |
| Output High Voltage(3.3V I/O) | Voh | $\mathrm{IOH}=-4.0 \mathrm{~mA}$ |  | 2.4 | - | V |
| Output Low Voltage(2.5V I/O) | Vol | $\mathrm{IOL}=1.0 \mathrm{~mA}$ |  | - | 0.4 | V |
| Output High Voltage(2.5V I/O) | Vor | $\mathrm{IOH}=-1.0 \mathrm{~mA}$ |  | 2.0 | - | V |
| Input Low Voltage(3.3V I/O) | VIL |  |  | -0.5* | 0.8 | V |
| Input High Voltage(3.3V I/O) | VIH |  |  | 2.0 | VDD +0.5 ** | V |
| Input Low Voltage(2.5V I/O) | VIL |  |  | -0.3* | 0.7 | V |
| Input High Voltage(2.5V I/O) | VIH |  |  | 1.7 | VDD+0.5** | V |

* VIL(Min) $=-2.0$ (Pulse Width $\leq$ tcYC $/ 2$ )
** $\mathrm{V}_{\text {ін }}(\mathrm{Max})=4.6$ (Pulse Width $\leq \mathrm{tcYc} / 2$ )
** In Case of $\mathrm{I} / \mathrm{O}$ Pins, the Max. $\mathrm{V}_{\mathrm{IH}}=\mathrm{V}_{\mathrm{DDQ}}+0.5 \mathrm{~V}$


## TEST CONDITIONS

(VDD=3.3V+0.3V/-0.165V,VdDQ=3.3V+0.3/-0.165V or VdD=3.3V $+0.3 \mathrm{~V} /-0.165 \mathrm{~V}, \mathrm{~V} D \mathrm{D}=2.5 \mathrm{~V}+0.4 \mathrm{~V} /-0.125 \mathrm{~V}, \mathrm{~T}=0$ to $70^{\circ} \mathrm{C}$ )

| PARAMETER | VALUE |
| :--- | :---: |
| Input Pulse Level(for 3.3V I/O) | 0 to 3V |
| Input Pulse Level(for $2.5 \mathrm{~V} \mathrm{I/O)}$ | 0 to 2.5 V |
| Input Rise and Fall Time(Measured at 0.3 V and 2.7 V for 3.3V I/O) | 1 ns |
| Input Rise and Fall Time(Measured at 0.3 V and 2.1 V for $2.5 \mathrm{~V} \mathrm{I/O)}$ | 1 ns |
| Input and Output Timing Reference Levels for $3.3 \mathrm{~V} \mathrm{I/O}$ | 1.5 V |
| Input and Output Timing Reference Levels for $2.5 \mathrm{~V} \mathrm{I/O}$ | VDDQ/2 |
| Output Load | See Fig. 1 |

Output Load(B)
(for tlzc, ttzoe, thzoe \& thzc)


Fig. 1

AC TIMING CHARACTERISTICS(TA $=0$ to $70^{\circ} \mathrm{C}, \mathrm{VDD}=3.3 \mathrm{~V}+0.3 \mathrm{~V} /-0.165 \mathrm{~V}$ )

| PARAMETER | SYMBOL | -22 |  | -20 |  | -18 |  | -16 |  | -15 |  | -14 |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max |  |
| Cycle Time | tcyc | 4.4 | - | 5.0 | - | 5.4 | - | 6.0 | - | 6.7 | - | 7.2 | - | ns |
| Clock Access Time | tcd | - | 3.1 | - | 3.1 | - | 3.1 | - | 3.5 | - | 3.8 | - | 4.0 | ns |
| Output Enable to Data Valid | toe | - | 3.1 | - | 3.1 | - | 3.1 | - | 3.5 | - | 3.8 | - | 4.0 | ns |
| Clock High to Output Low-Z | tızc | 0 | - | 0 | - | 0 | - | 0 | - | 0 | - | 0 | - | ns |
| Output Hold from Clock High | toн | 1.0 | - | 1.0 | - | 1.0 | - | 1.5 | - | 1.5 | - | 1.5 | - | ns |
| Output Enable Low to Output Low-Z | tlzoe | 0 | - | 0 | - | 0 | - | 0 | - | 0 | - | 0 | - | ns |
| Output Enable High to Output High-Z | thzoe | - | 3.1 | - | 3.1 | - | 3.1 | - | 3.5 | - | 3.8 | - | 4.0 | ns |
| Clock High to Output High-Z | thzc | 1.0 | 3.1 | 1.0 | 3.1 | 1.0 | 3.1 | 1.5 | 3.5 | 1.5 | 3.8 | 1.5 | 4.0 | ns |
| Clock High Pulse Width | tch | 2.0 | - | 2.0 | - | 2.0 | - | 2.0 | - | 2.4 | - | 2.8 | - | ns |
| Clock Low Pulse Width | tcL | 2.0 | - | 2.0 | - | 2.0 | - | 2.0 | - | 2.4 | - | 2.8 | - | ns |
| Address Setup to Clock High | tas | 1.4 | - | 1.4 | - | 1.4 | - | 1.5 | - | 1.5 | - | 1.5 | - | ns |
| Address Status Setup to Clock High | tss | 1.4 | - | 1.4 | - | 1.4 | - | 1.5 | - | 1.5 | - | 1.5 | - | ns |
| Data Setup to Clock High | tos | 1.4 | - | 1.4 | - | 1.4 | - | 1.5 | - | 1.5 | - | 1.5 | - | ns |
| Write Setup to Clock High ( $\overline{\mathrm{GW}}, \overline{\mathrm{BW}}$, $\overline{\mathrm{WEx}}$ ) | tws | 1.4 | - | 1.4 | - | 1.4 | - | 1.5 | - | 1.5 | - | 1.5 | - | ns |
| Address Advance Setup to Clock High | tadvs | 1.4 | - | 1.4 | - | 1.4 | - | 1.5 | - | 1.5 | - | 1.5 | - | ns |
| Chip Select Setup to Clock High | tcss | 1.4 | - | 1.4 | - | 1.4 | - | 1.5 | - | 1.5 | - | 1.5 | - | ns |
| Address Hold from Clock High | tah | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | ns |
| Address Status Hold from Clock High | tsh | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | ns |
| Data Hold from Clock High | tDH | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | ns |
| Write Hold from Clock High ( $\overline{\mathrm{GW}}, \overline{\mathrm{BW}}, \overline{\mathrm{WE}}$ ) | twh | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | ns |
| Address Advance Hold from Clock High | tadvh | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | ns |
| Chip Select Hold from Clock High | tcsh | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | 0.5 | - | ns |
| zz High to Power Down | tpds | 2 | - | 2 | - | 2 | - | 2 | - | 2 | - | 2 | - | cycle |
| ZZ Low to Power Up | tpus | 2 | - | 2 | - | 2 | - | 2 | - | 2 | - | 2 | - | cycle |

Notes : 1. All address inputs must meet the specified setup and hold times for all rising clock edges whenever $\overline{\text { ADSC }}$ and/or $\overline{\mathrm{ADSP}}$ is sampled low and $\overline{\mathrm{CS}}$ is sampled low. All other synchronous inputs must meet the specified setup and hold times whenever this device is chip selected.
2. Both chip selects must be active whenever $\overline{\mathrm{ADSC}}$ or $\overline{\mathrm{ADSP}}$ is sampled low in order for the this device to remain enabled.
3. ADSC or ADSP must not be asserted for at least 2 Clock after leaving ZZ state.



TIMING WAVEFORM OF SINGLE READ/WRITE CYCLE( $\overline{\text { ADSC }}$ CONTROLLED,$\overline{\text { ADSP }}=\mathrm{HIGH})$



## APPLICATION INFORMATION

## DEPTH EXPANSION

The Samsung 128Kx18 Synchronous Pipelined Burst SRAM has two additional chip selects for simple depth expansion. This permits easy secondary cache upgrades from 128 K depth to 256 K depth without extra logic.


INTERLEAVE READ TIMING (Refer to non-interleave write timing for interleave write timing) ( $\overline{\text { ADSP }}$ CONTROLLED , $\overline{\text { ADSC }}=\mathrm{HIGH}$ )

*NOTES $\mathrm{n}=14$ 32K depth, 15 64K depth, 16 128K depth, 17 256K depth

## PACKAGE DIMENSIONS

100-TQFP-1420A
Units:millimeters/inches



[^0]:    *Note : Sampled not $100 \%$ tested.

