5.0 V Micropower 150 mA LDO Linear Regulator with DELAY, Adjustable RESET, and Monitor FLAG

The NCV4279B is a 5.0 V precision micropower voltage regulator. The output current capability is 150 mA.

The output voltage is accurate within $\pm 2.0\%$ with a maximum dropout voltage of 0.6 V at 150 mA. Low quiescent current is a feature drawing only 90 μ A with a 100 μ A load. This part is ideal for any and all battery operated microprocessor equipment.

Microprocessor control logic includes an active $\overline{\text{RESET}}$ (with DELAY), and a FLAG monitor which can be used to provide an early warning signal to the microprocessor of a potential impending $\overline{\text{RESET}}$ signal. The use of the FLAG monitor allows the microprocessor to finish any signal processing before the $\overline{\text{RESET}}$ shuts the microprocessor down.

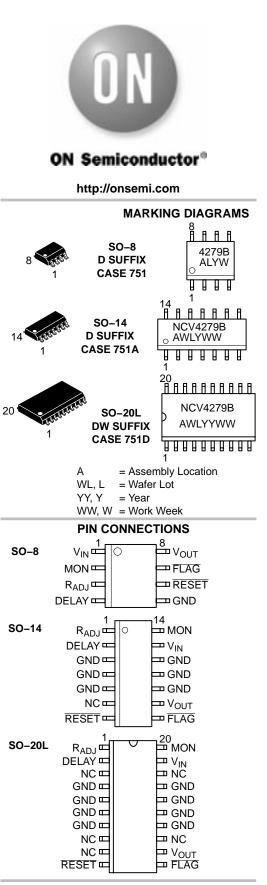
The active $\overline{\text{RESET}}$ circuit operates correctly at an output voltage as low as 1.0 V. The $\overline{\text{RESET}}$ function is activated during the power up sequence or during normal operation if the output voltage drops outside the regulation limits.

The reset threshold voltage can be decreased by the connection of external resistor divider to R_{ADJ} lead.

The regulator is protected against reverse battery, short circuit, and thermal overload conditions. The device can withstand load dump transients making it suitable for use in automotive environments. The device has also been optimized for EMC conditions.

Features

- 5.0 V ± 2.0% Output
- Low 90 µA Quiescent Current
- Active **RESET**
- Adjustable Reset
- 150 mA Output Current Capability
- Fault Protection
 - +60 V Peak Transient Voltage
 - -15 V Reverse Voltage
 - Short Circuit
 - Thermal Overload
- Early Warning through FLAG/MON Leads
- Internally Fused Leads in SO-14 and SO-20L Packages
- NCV Prefix for Automotive and Other Applications Requiring Site and Control Changes



ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 10 of this data sheet.

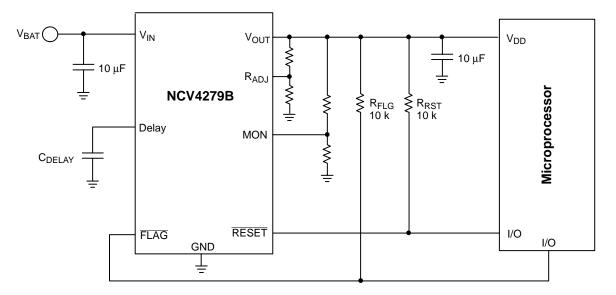


Figure 1. Application Diagram

MAXIMUM RATINGS*[†]

Rating		Value	Unit
V _{IN} (DC)		-15 to 45	V
Peak Transient Voltage (46 V Load Dump @ V _{IN} = 14 V)		60	V
Operating Voltage		45	V
V _{OUT} (DC)		16	V
Voltage Range (RESET, FLAG)		-0.3 to 10	V
Input Voltage Range (MON)		-0.3 to 10	V
ESD Susceptibility (Human Body Model)		2.0	kV
Junction Temperature, T _J		-40 to +150	°C
Storage Temperature, T _S		-55 to 150	°C
Package Thermal Resistance, SO–8: Junction–to–Case, R _{θJC} Junction–to–Ambient, R _{θJA}		45 165	°C/W
$\begin{array}{l} \mbox{Package Thermal Resistance, SO-14 (Fused) Minimum Pad Data:} \\ \mbox{Junction-to-Case, } R_{\theta JC} \\ \mbox{Junction-to-Ambient, } R_{\theta JA} \\ \mbox{Junction-to-Pin, } R_{\theta JP} (Note 3) \end{array}$		15 110 33	°C/W
Package Thermal Resistance, SO–20L (Fused) Minimum Pad Data Junction–to–Case, R _{θJC} Junction–to–Ambient, R _{θJA} Junction–to–Pin, R _{θJP} (Note 4)	:	12 82 26	°C/W
Lead Temperature Soldering:	Reflow: (SMD styles only) (Notes 1, 2)	240 peak	°C

60 second maximum above 183°C.
 -5°C/+0°C allowable conditions.

Measured to pin 9.
 Measured to pin 12.

*The maximum package power dissipation must be observed. †During the voltage range which exceeds the maximum tested voltage of V_{IN}, operation is assured, but not specified. Wider limits may apply. Thermal dissipation must be observed closely.

Characteristic	Test Conditions	Min	Тур	Max	Uni
Output Stage					
Output Voltage	9.0 V < V _{IN} < 16 V, 100 $\mu A \le I_{OUT} \le 150$ mA 6.0 V < V _{IN} < 26 V, 100 $\mu A \le I_{OUT} \le 150$ mA	4.90 4.85	5.0 5.0	5.10 5.15	V V
Dropout Voltage (V _{IN} – V _{OUT})	I _{OUT} = 150 mA I _{OUT} = 100 μA	_	400 100	600 150	mV mV
Load Regulation	V_{IN} = 14 V, 5.0 mA \leq I_{OUT} \leq 150 mA	-30	5.0	30	mV
Line Regulation	$[V_{OUT}(typ) + 1.0] < V_{IN} < 26 \text{ V}, I_{OUT} = 1.0 \text{ mA}$	-	15	60	mV
Quiescent Current, (I _Q) Active Mode	$ I_{OUT} = 100 \ \mu\text{A}, \ V_{\text{IN}} = 12 \ \text{V}, \ \text{Delay} = 3.0 \ \text{V}, \ \text{MON} = 3.0 \ \text{V} \\ I_{OUT} = 75 \ \text{mA}, \ V_{\text{IN}} = 14 \ \text{V}, \ \text{Delay} = 3.0 \ \text{V}, \ \text{MON} = 3.0 \ \text{V} \\ I_{OUT} \leq 150 \ \text{mA}, \ V_{\text{IN}} = 14 \ \text{V}, \ \text{Delay} = 3.0 \ \text{V}, \ \text{MON} = 3.0 \ \text{V} $			125 6.0 19	μA mA mA
Current Limit	-	151	300	-	mA
Short Circuit Output Current V _{OUT} = 0 V		40	190	-	mA
Thermal Shutdown (Guaranteed by Design)		150	180	-	°C
leset Function (RESET)					
RESET Threshold HIGH (V _{RH}) LOW (V _{RL})	V _{OUT} Increasing V _{OUT} Decreasing	4.55 4.50	4.70 4.60	$\begin{array}{c} 0.98 \times V_{OUT} \\ 0.97 \times V_{OUT} \end{array}$	V V
Output Voltage Low (V _{RLO})	$1.0 \text{ V} \leq \text{V}_{\text{OUT}} \leq \text{V}_{\text{RL}}, \text{R}_{\overline{\text{RESET}}} = 10 \text{ k}$	-	0.1	0.4	v
Delay Switching Threshold (V _{DT})	-	1.4	1.8	2.2	V
Reset Delay Low Voltage V _{OUT} < RESET Threshold Low(min)		-	-	0.1	V
Delay Charge Current DELAY = 1.0 V, V _{OUT} > V _{RH}		1.5	2.5	3.5	μA
Delay Discharge Current DELAY = 1.0 V, V _{OUT} = 1.5 V		5.0	-	-	mA
Reset Adjust Switching Voltage (V _{R(ADJ)})	-	1.23	1.31	1.39	V

Monitor Threshold	Increasing and Decreasing		1.20	1.31	V
Hysteresis	-	20	50	100	mV
Input Current	MON = 2.0 V	-0.5	0.1	0.5	μA
Output Saturation Voltage	MON = 0 V, I _{FLAG} = 1.0 mA	-	0.1	0.4	V

PACKAGE PIN DESCRIPTION

Pa	Package Pin Number			
SO-8	SO-14	SO-20L	Pin Symbol	Function
3	1	1	R _{ADJ}	Reset Adjust. If not needed connect to ground.
4	2	2	DELAY	Timing capacitor for RESET function.
5	3–5, 10–12	4–7, 14–17	GND	Ground. All GND leads must be connected to Ground
_	6	3, 8, 9, 13, 18	NC	No connection.
6	7	10	RESET	Active reset (accurate to $V_{OUT} \ge 1.0 \text{ V}$)
7	8	11	FLAG	Open collector output from early warning comparator.
8	9	12	V _{OUT}	±2.0%, 150 mA output.
1	13	19	V _{IN}	Input Voltage.
2	14	20	MON	Monitor. Input for early warning comparator. If not needed connect to $V_{OUT.}$

TYPICAL PERFORMANCE CHARACTERISTICS

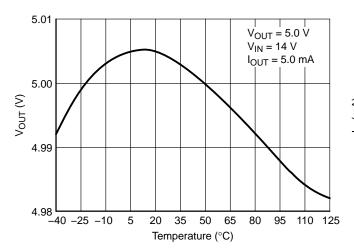


Figure 2. Output Voltage vs. Temperature

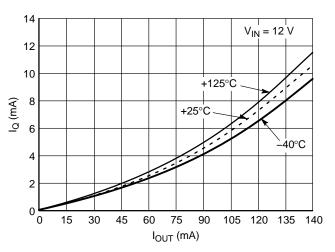


Figure 4. Quiescent Current vs. Output Current

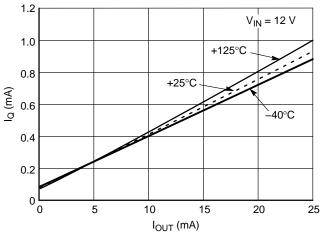
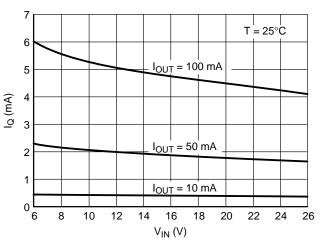


Figure 3. Quiescent Current vs. Output Current





T = 25°C $I_{OUT} = 100 \ \mu A$ Dropout Voltage (mV) +125°C +25°C l_Q (μΑ) –40°[′]C . V_{IN} (V) I_{OUT} (mA)

TYPICAL PERFORMANCE CHARACTERISTICS





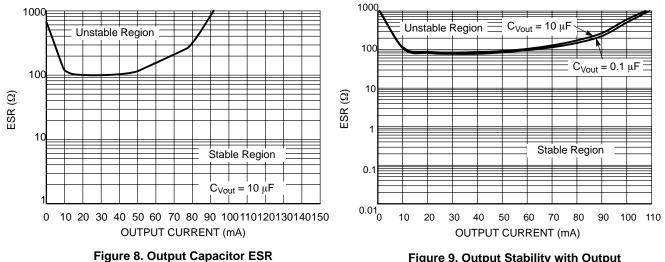


Figure 9. Output Stability with Output Capacitor Change

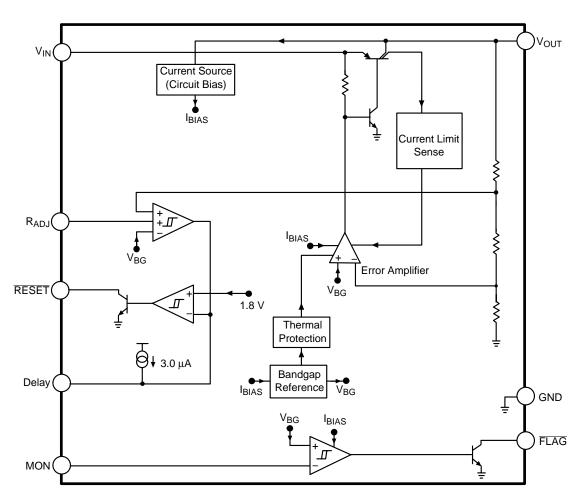
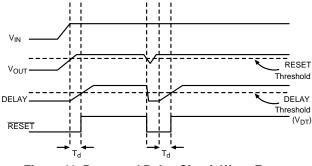


Figure 10. Block Diagram

CIRCUIT DESCRIPTION

REGULATOR CONTROL FUNCTIONS

The NCV4279B contains the microprocessor compatible control function $\overline{\text{RESET}}$ (Figure 11).





RESET Function

A RESET signal (low voltage) is generated as the IC powers up until V_{OUT} is within 6.0% of the regulated output voltage, or when V_{OUT} drops out of regulation, and is lower than 8.0% below the regulated output voltage. Hysteresis is included in the function to minimize oscillations.

The $\overline{\text{RESET}}$ output is an open collector NPN transistor, controlled by a low voltage detection circuit. The circuit is functionally independent of the rest of the IC thereby guaranteeing that the $\overline{\text{RESET}}$ signal is valid for V_{OUT} as low as 1.0 V.

Adjustable Reset Function

The reset threshold can be made lower by connecting an external resistor divider to the R_{ADJ} lead from the V_{OUT} lead, as displayed in Figure 12. This lead is grounded to select the default value of 4.6 V.

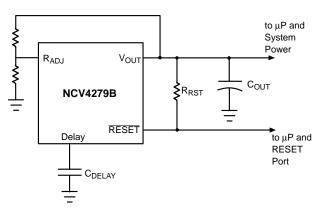


Figure 12. Adjustable RESET

DELAY Function

The reset delay circuit provides a programmable (by external capacitor) delay on the $\overline{\text{RESET}}$ output lead.

The DELAY lead provides source current (typically $2.5 \,\mu$ A) to the external DELAY capacitor during the following proceedings:

- 1. During Power Up (once the regulation threshold has been verified).
- 2. After a reset event has occurred and the device is back in regulation. The DELAY capacitor is discharged when the regulation (RESET threshold) has been violated. This is a latched incident. The capacitor will fully discharge and wait for the device to regulate before going through the delay time event again.

FLAG/Monitor Function

An on-chip comparator is provided to perform an early warning to the microprocessor of a possible reset signal. The reset signal typically turns the microprocessor off instantaneously. This can cause unpredictable results with the microprocessor. The signal received from the FLAG pin will allow the microprocessor time to complete its present task before shutting down. This function is performed by a comparator referenced to the bandgap reference. The actual trip point can be programmed externally using a resistor divider to the input monitor (MON) (Figure 13). The typical threshold is 1.20 V on the MON Pin.

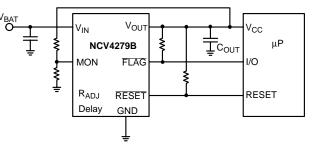


Figure 13. FLAG/Monitor Function

APPLICATION NOTES

FLAG MONITOR

Figure 14 shows the FLAG Monitor waveforms as a result of the circuit depicted in Figure 13. As the output voltage falls (V_{OUT}), the Monitor threshold is crossed. This causes the voltage on the FLAG output to go low sending a warning signal to the microprocessor that a RESET signal may occur in a short period of time. T_{WARNING} is the time the microprocessor has to complete the function it is currently working on and get ready for the RESET shutdown signal.

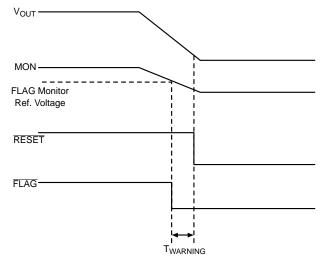


Figure 14. FLAG Monitor Circuit Waveform

SETTING THE DELAY TIME

The delay time is controlled by the Reset Delay Low Voltage, Delay Switching Threshold, and the Delay Charge Current. The delay follows the equation:

$$t_{\text{DELAY}} = \frac{[C_{\text{DELAY}}(V_{\text{dt}} - \text{Reset Delay Low Voltage})]}{\text{Delay Charge Current}}$$

Example:

Using $C_{DELAY} = 33 \text{ nF}$.

Assume reset Delay Low Voltage = 0.

Use the typical value for $V_{dt} = 1.8$ V.

Use the typical value for Delay Charge Current = $2.5 \mu A$.

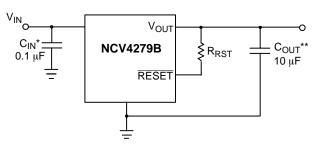
$$t_{\text{DELAY}} = \frac{[33 \text{ nF}(1.8 - 0)]}{2.5 \,\mu\text{A}} = 23.8 \text{ ms}$$

STABILITY CONSIDERATIONS

The output or compensation capacitor helps determine three main characteristics of a linear regulator: start–up delay, load transient response and loop stability.

The capacitor value and type should be based on cost, availability, size and temperature constraints. A tantalum or aluminum electrolytic capacitor is best, since a film or ceramic capacitor with almost zero ESR can cause instability. The aluminum electrolytic capacitor is the least expensive solution, but, if the circuit operates at low temperatures (-25° C to -40° C), both the value and ESR of the capacitor will vary considerably. The capacitor manufacturers data sheet usually provides this information.

The value for the output capacitor C_{OUT} shown in Figure 15 should work for most applications, however it is not necessarily the optimized solution.



*C_{IN} required if regulator is located far from the power supply filter. **C_{OUT} required for stability. Capacitor must operate at minimum temperature expected.

Figure 15. Test and Application Circuit Showing Output Compensation

CALCULATING POWER DISSIPATION IN A SINGLE OUTPUT LINEAR REGULATOR

The maximum power dissipation for a single output regulator (Figure 16) is:

$$PD(max) = [VIN(max) - VOUT(min)]^{I}OUT(max)$$
(1)
+ VIN(max)^{I}Q

where:

V_{IN(max)} is the maximum input voltage,

V_{OUT(min)} is the minimum output voltage,

 $I_{OUT(max)}$ is the maximum output current for the application, and

 I_Q is the quiescent current the regulator consumes at $I_{OUT(max)}$.

Once the value of $P_{D(max)}$ is known, the maximum permissible value of $R_{\theta JA}$ can be calculated:

$$R_{\theta JA} = \frac{150^{\circ}C - T_{A}}{P_{D}}$$
(2)

The value of $R_{\theta JA}$ can then be compared with those in the package section of the data sheet. Those packages with $R_{\theta JA}$'s less than the calculated value in equation 2 will keep the die temperature below 150°C.

In some cases, none of the packages will be sufficient to dissipate the heat generated by the IC, and an external heatsink will be required.

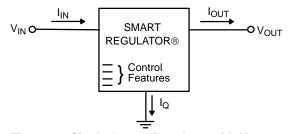


Figure 16. Single Output Regulator with Key Performance Parameters Labeled

HEAT SINKS

A heat sink effectively increases the surface area of the package to improve the flow of heat away from the IC and into the surrounding air.

Each material in the heat flow path between the IC and the outside environment will have a thermal resistance. Like series electrical resistances, these resistances are summed to determine the value of $R_{\theta JA}$:

$$R_{\theta}JA = R_{\theta}JC + R_{\theta}CS + R_{\theta}SA$$
(3)

where:

- $R_{\theta JC}$ = the junction-to-case thermal resistance,
- $R_{\theta CS}$ = the case-to-heatsink thermal resistance, and
- $R_{\theta SA}$ = the heatsink-to-ambient thermal resistance.

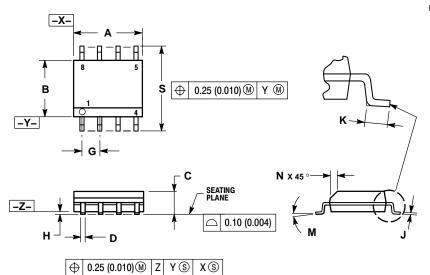
 $R_{\theta JC}$ appears in the package section of the data sheet. Like $R_{\theta JA}$, it too is a function of package type. $R_{\theta CS}$ and $R_{\theta SA}$ are functions of the package type, heatsink and the interface between them. These values appear in heat sink data sheets of heat sink manufacturers.

ORDERING INFORMATION

Device	Output Voltage	Package	Shipping
NCV4279BD1		00.0	98 Units/Rail
NCV4279BD1R2		SO-8	2500 Tape & Reel
NCV4279BD2	5.0 V		55 Units/Rail
NCV4279BD2R2	5.0 V	SO-14	1000 Tape & Reel
NCV4279BDW			37 Units/Rail
NCV4279BDWR2		SO-20L	1000 Tape & Reel

PACKAGE DIMENSIONS

SO-8 **D SUFFIX** CASE 751-07 **ISSUE AA**

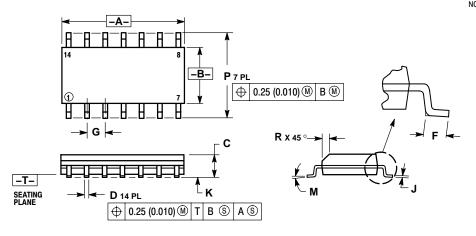


NOTES: 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 2. CONTROLLING DIMENSION: MILLIMETER.
 3. DIMENSION A AND B DO NOT INCLUDE MOLD DEPARTMENSION

- PROTRUSION. 4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER
- MAXIMUM MOLD PHOTHUSION 0.15 (0.006) PEH SIDE.
 DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION
- MATERIAL CONDITION. 6. 751-01 THRU 751-06 ARE OBSOLETE. NEW STANDAARD IS 751-07

	MILLIN	IETERS	INCHES	
DIM	MIN	MAX	MIN	MAX
Α	4.80	5.00	0.189	0.197
В	3.80	4.00	0.150	0.157
С	1.35	1.75	0.053	0.069
D	0.33	0.51	0.013	0.020
G	1.27 BSC		0.050 BSC	
Н	0.10	0.25	0.004	0.010
J	0.19	0.25	0.007	0.010
K	0.40	1.27	0.016	0.050
М	0 °	8 °	0 °	8 °
N	0.25	0.50	0.010	0.020
S	5.80	6.20	0.228	0.244

SO-14 **D SUFFIX** CASE 751A-03 **ISSUE F**



NOTES: DIES.
 DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 CONTROLLING DIMENSION: MILLIMETER.

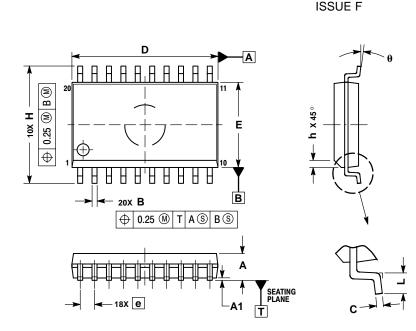
- 3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
 S. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR

PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIN	IETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	8.55	8.75	0.337	0.344
В	3.80	4.00	0.150	0.157
С	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27 BSC		0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
Μ	0 °	7°	0 °	7°
Р	5.80	6.20	0.228	0.244
R	0.25	0.50	0.010	0.019

PACKAGE DIMENSIONS

SO-20L **DW SUFFIX** CASE 751D-05



NOTES:

- DIMENSIONS ARE IN MILLIMETERS. INTERPRET DIMENSIONS AND TOLERANCES 2. PER ASME Y14.5M, 1994
- DIMENSIONS D AND E DO NOT INCLUDE MOLD 3.
- PROTRUSION. MAXIMUM MOLD PROTRUSION 0.15 PER SIDE.
- DIMENSION B DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS OF B DIMENSION AT MAXIMUM MATERIAL CONDITION

	MILLIMETERS		
DIM	MIN	MAX	
Α	2.35	2.65	
A1	0.10	0.25	
В	0.35	0.49	
С	0.23	0.32	
D	12.65	12.95	
Е	7.40	7.60	
е	1.27	BSC	
Н	10.05	10.55	
h	0.25	0.75	
L	0.50	0.90	
θ	0 °	7 °	

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